



# Hands-on Training on Weather Radar QC

7-8th February 2018

Junji HOTTA

Office of Observation Systems Operation

Observation Department

Japan Meteorological Agency

# Guide map of the workshop

## Weather radar

Basics and operation of weather radars

Day 1: 1

### Hardware

- Install
- Calibration
- Maintenance

Day 1-2: 2

Advanced techniques

- Solid-state transmitter

Day 1-2: 2

### Observation

- Obs. scheduling
- Quality control
- Sites composite

Day 2-4: 4,5

Advanced techniques

- Doppler velocity
- Accurate obs. using dual-pol

Day 4: 7

### Application

- QPE&QPF

Day 4: 7

Advanced techniques

- Detecting mesocyclone
- Products derived from dual-pol obs.

Day 4: 7

- Weather summary

Day 5: 9

## Regional radar network

Capacity development

Data exchange

Regional cooperation

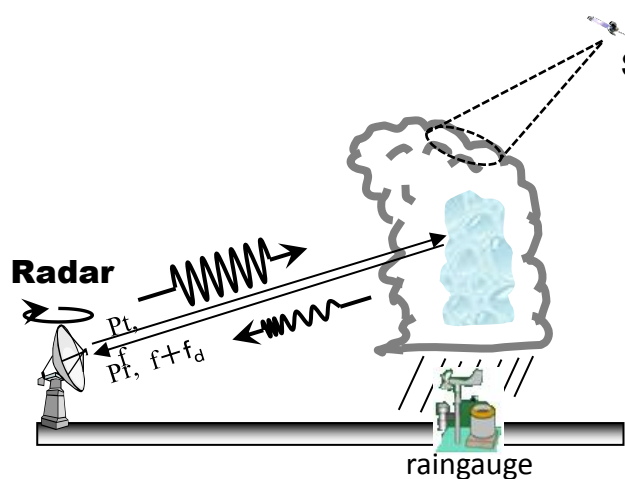
Day 9: 12



# Hands-on Training on Weather Radar QC

- Introduction of JMA Operational system (15min.)
- Quality control algorithms
  - Characteristics of non-precipitation echo (10min.)
  - JMA methods of Pseudo CAPPI process (15min.)
  - Statistical approach for QC (10min.)
- Hands on training (90min.)
  - Adjustment of elevation angle composite table
  - Making PCAPPI and Statistical data
  - Verification of the results

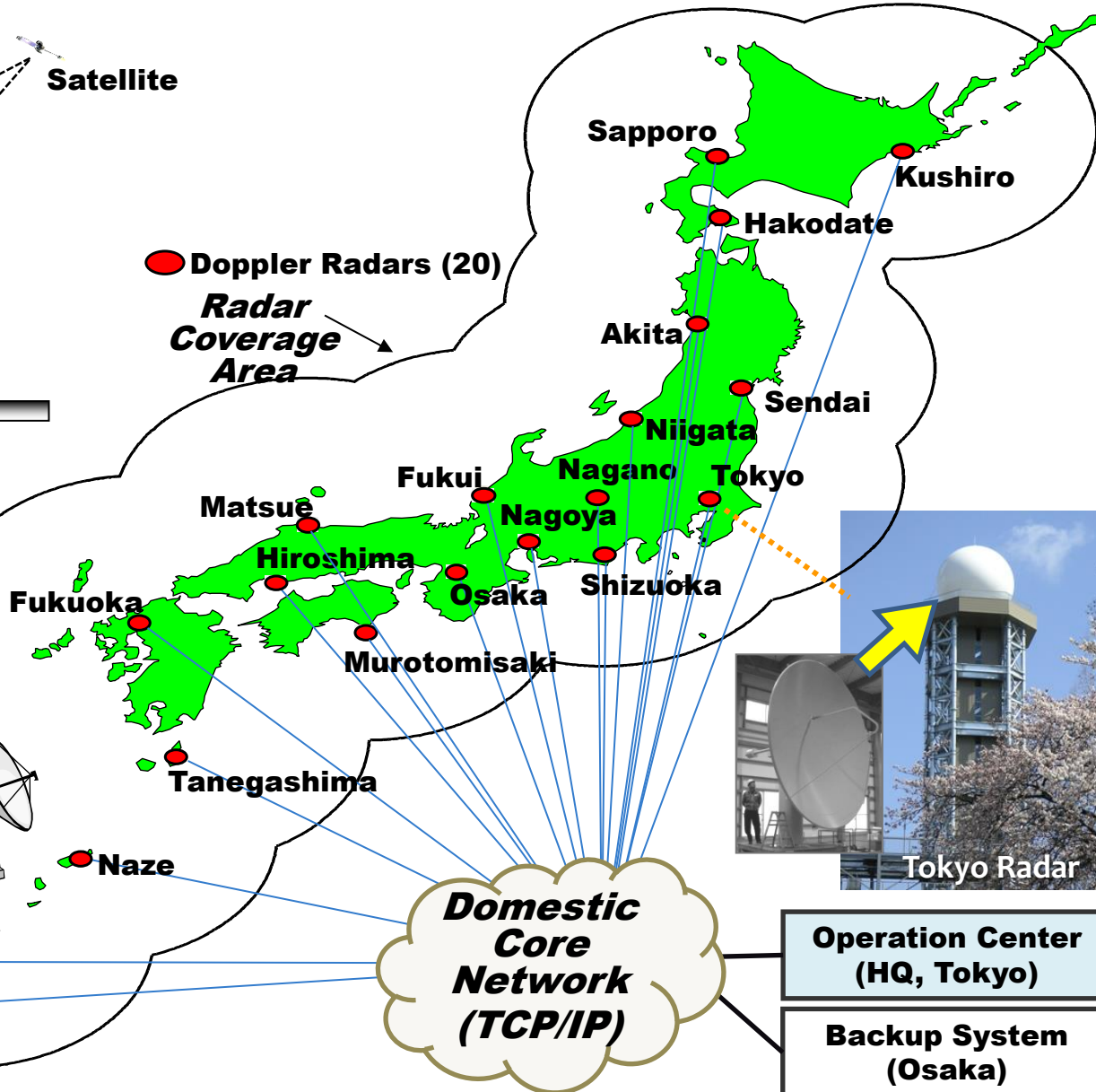
# JMA's Weather Radar Network



**C-band Radar observes reflected echo (precipitation drops) and Doppler Velocity.**

**Precipitation, Wind Every 5 min.**

**● Doppler Radars (20)**  
**Radar Coverage Area**



# JMA radar specifications

Frequency	5300 ~ 5370 MHz (C-band )		
TX type	Klystron		
Peak Power	250 kW		
Pulse Width	2.5 $\mu$ s	1.0 $\mu$ s	
Pulse Repetition Frequency (PRF)	330 Hz	600/480 Hz	940/752 Hz
Antenna Diameter	4 m (Beam Width < 1.2 °)		
Maximum Range	Rainfall intensity : 400 km Doppler velocity : 250 km		

# Nationwide Radar Composite Maps

C-band Radars

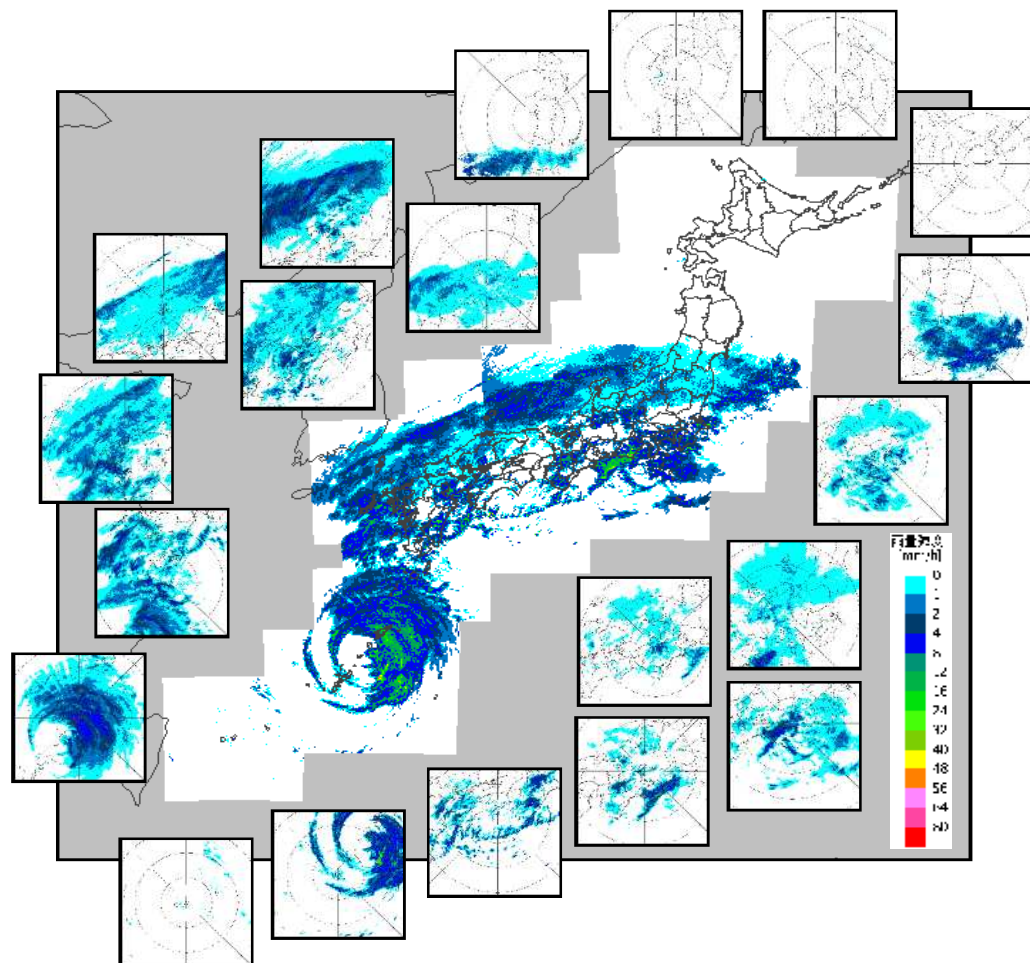
JMA C-Band : 20

MLIT C-Band: 26



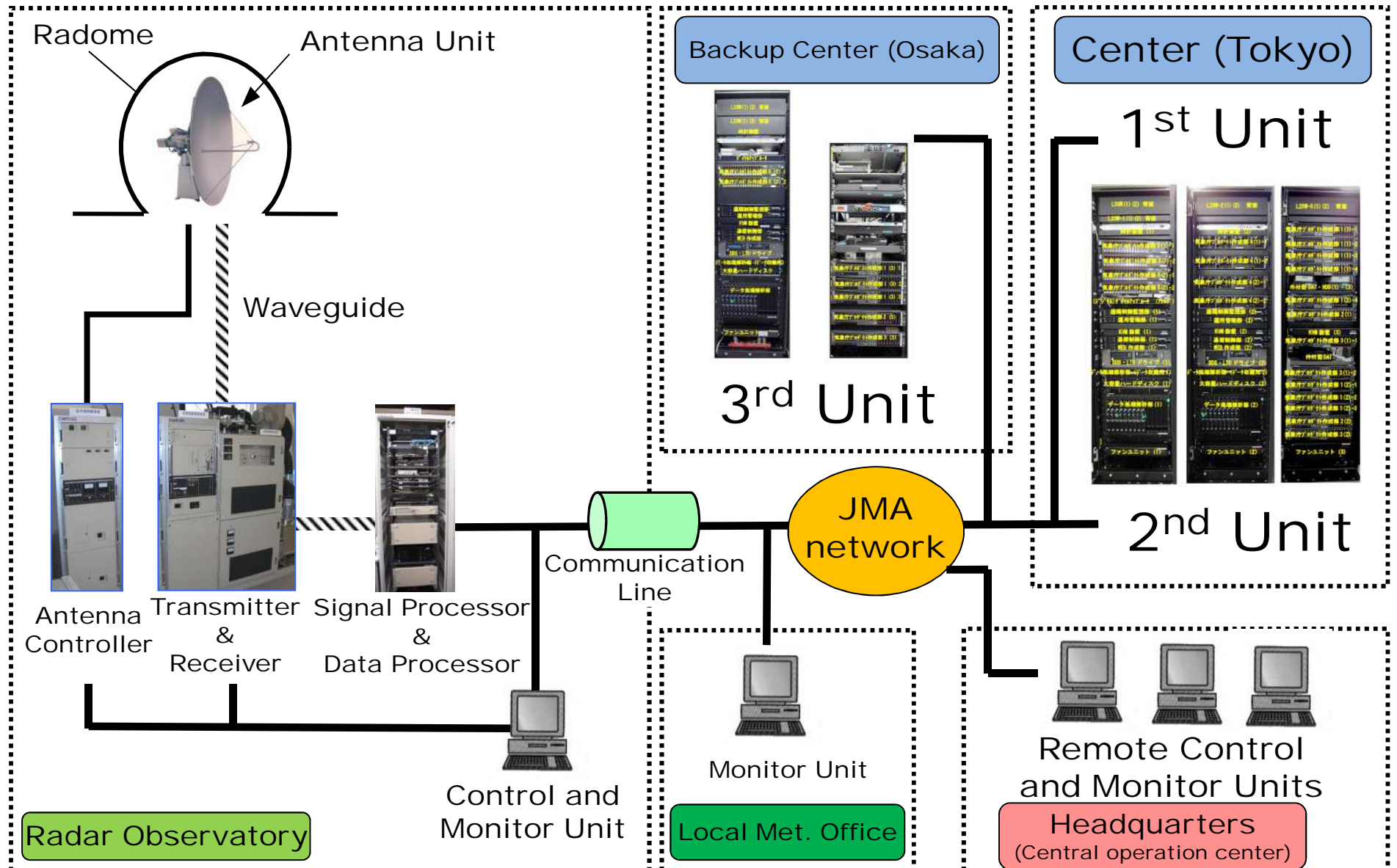
C-band Radar echo data (JMA, MLIT) are collected to the center system and integrated into a nationwide echo intensity composite map( every 5 minutes )

*MLIT: Ministry of Land, Infrastructure, Transport and Tourism*

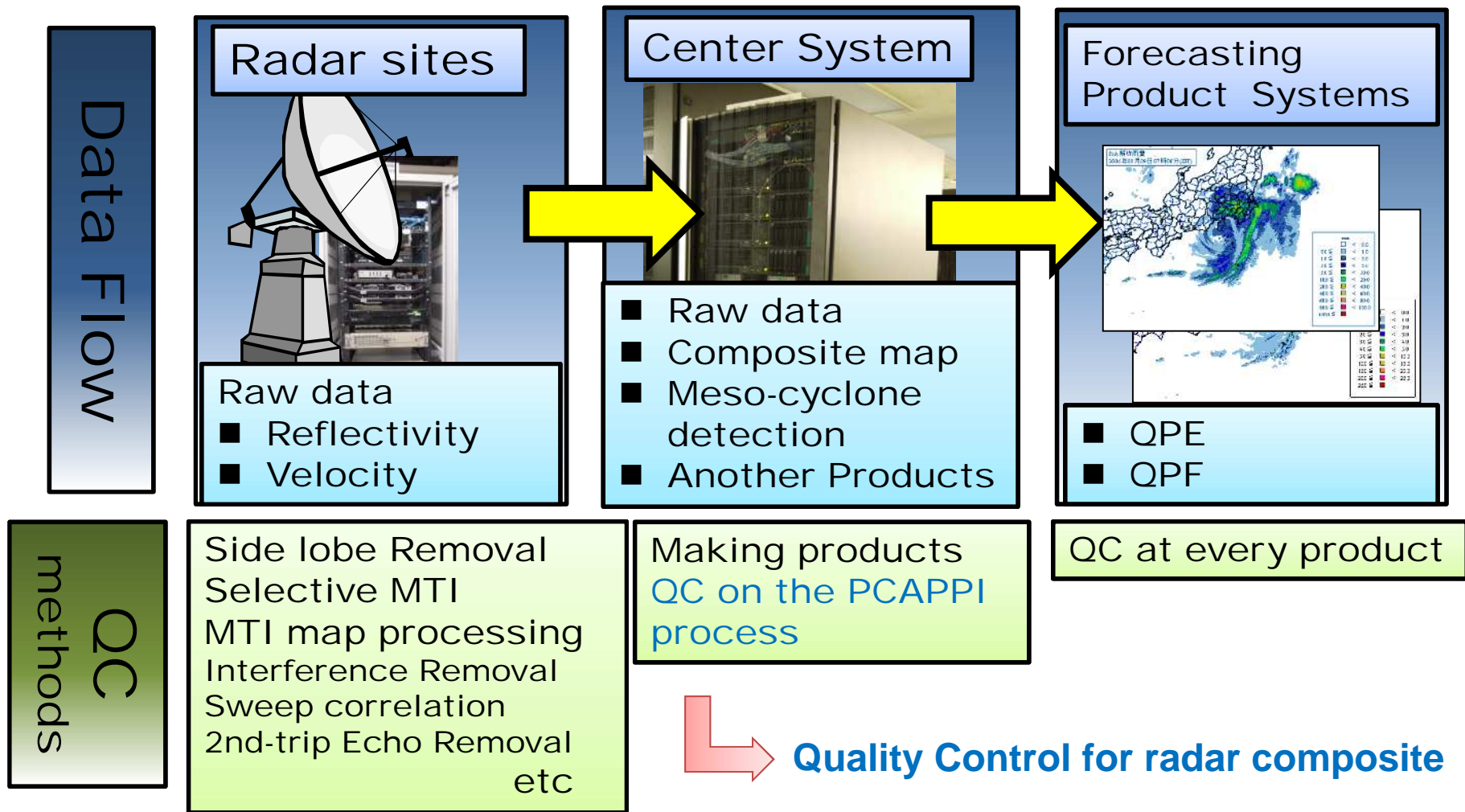


for Monitoring / Nowcasting  
Quantitative Precipitation  
Estimation / Forecast (QPE/QPF) etc.

# Radar network system



# Automated QC on radar systems





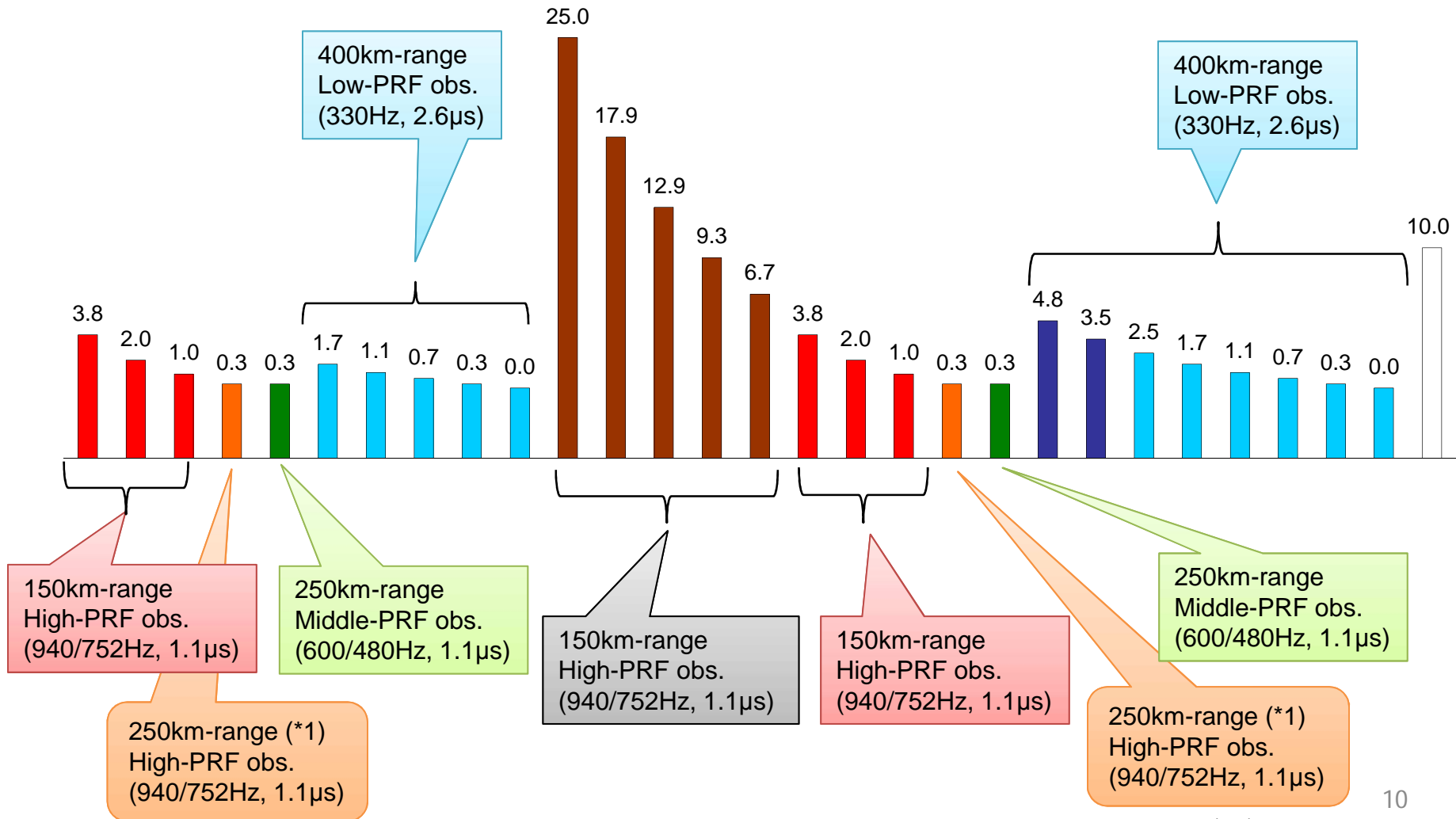
# Basic concept of scanning schedule

- Precipitation
  - Low PRF, long pulse (330 Hz, 2.6 micro sec.)
    - long distance
    - Mainly precipitation
- Velocity
  - Dual High PRF, short pulse  
(940/752 Hz, 600/480 Hz , 1.1 micro sec.)
    - Short distance
    - Velocity range is large

# Observation Scan Sequence

Example of Tokyo radar

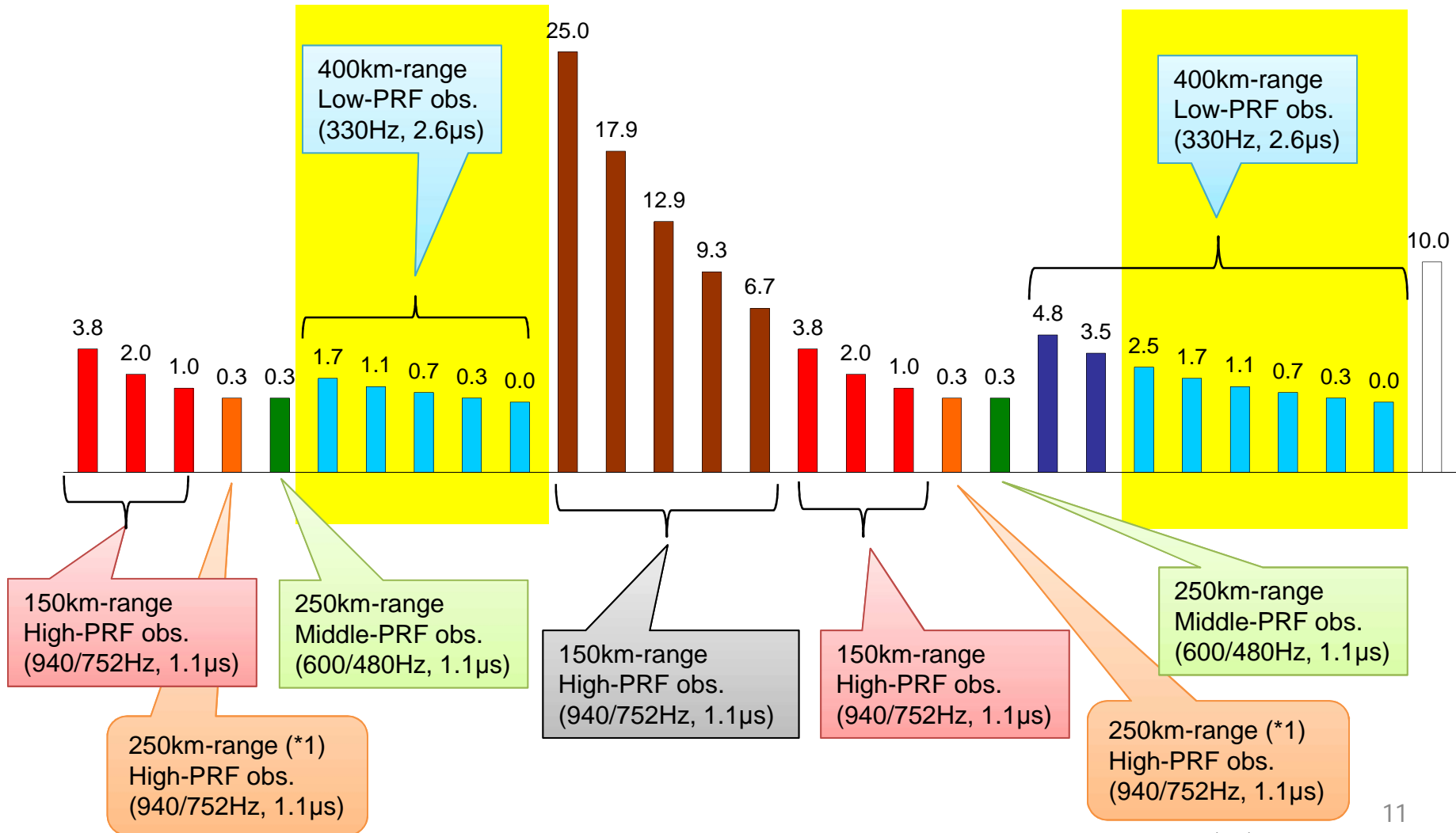
10-minute volume scanning



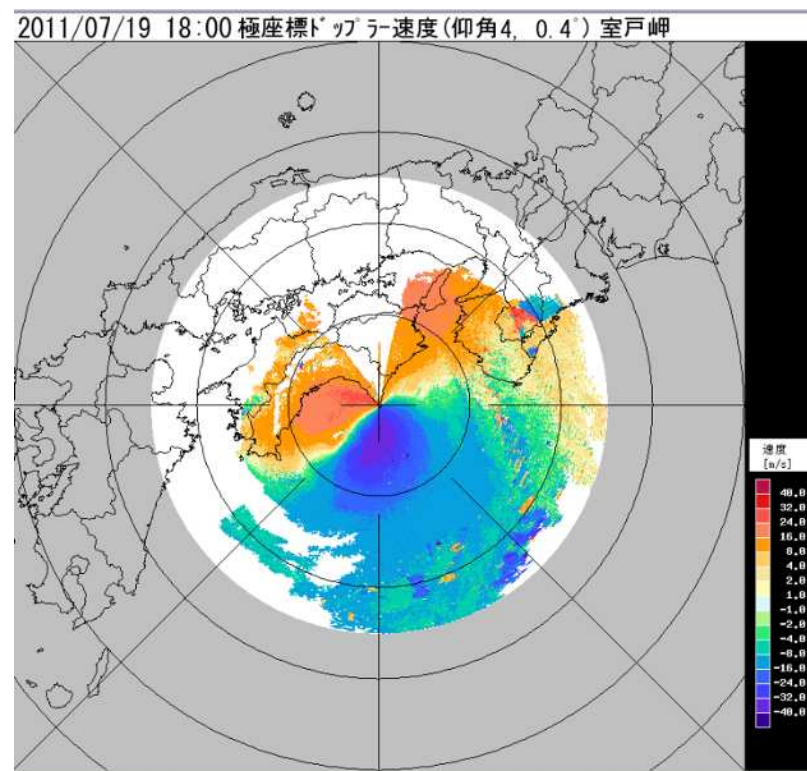
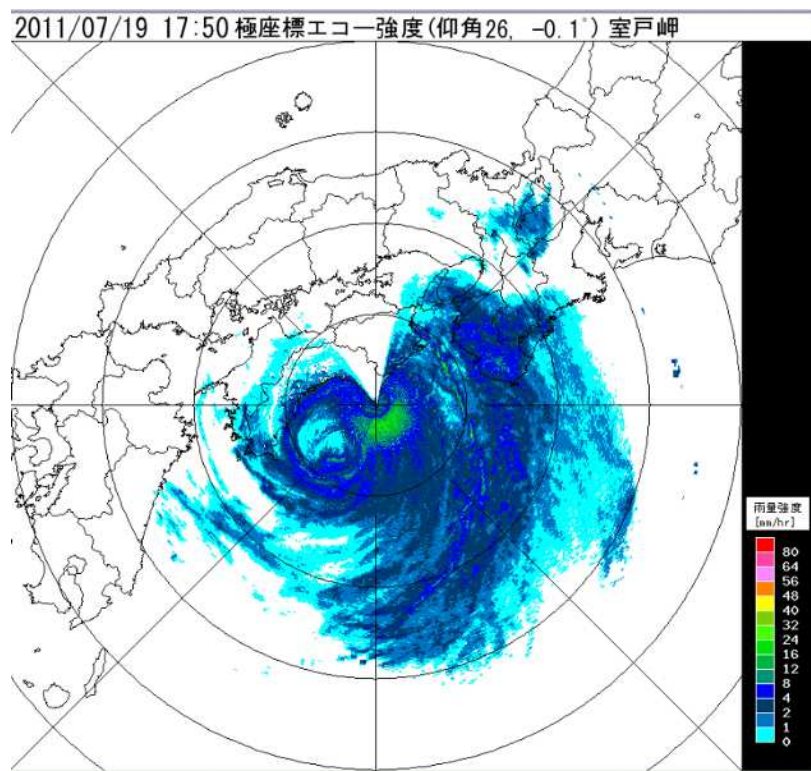
# Observation Scan Sequence

Example of Tokyo radar

10-minute volume scanning



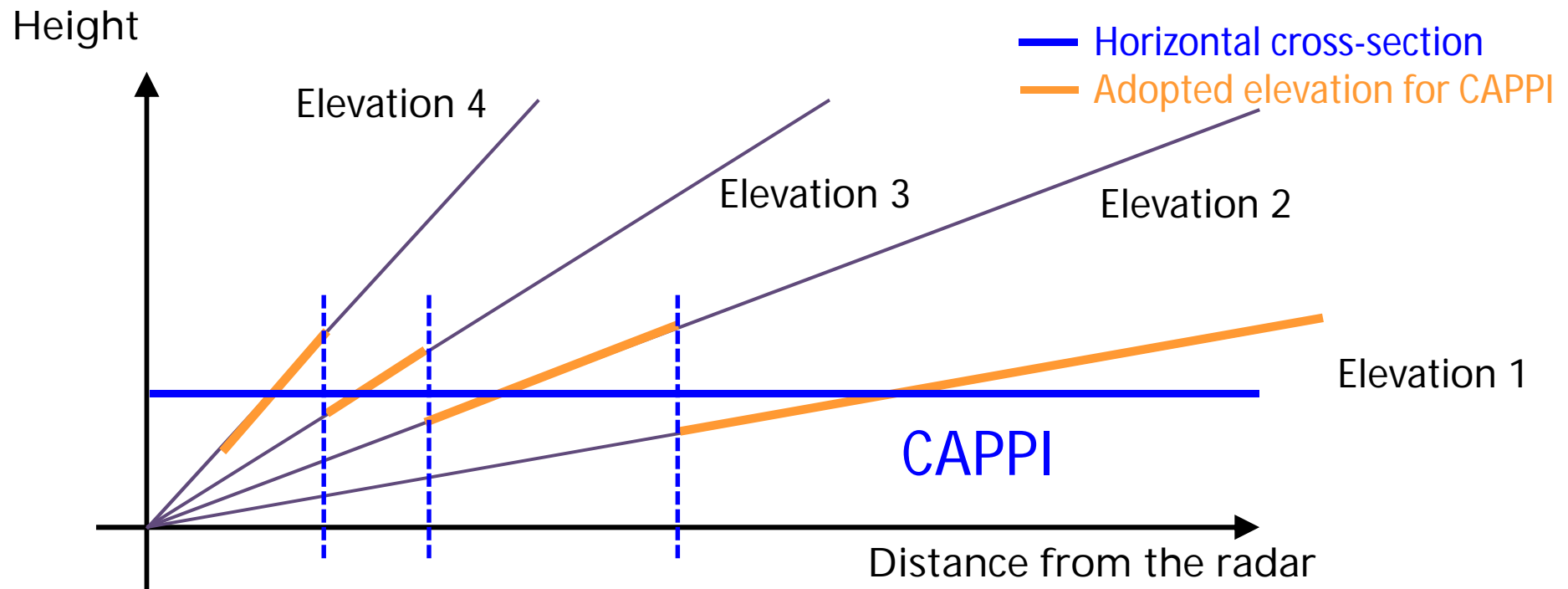
# Primary Data



Data Type		Unit	Coordinates	Mesh Size	Area	Number of Mesh	Data Size (one mesh)	Data Format	Period
Each radar	Echo intensity	dBZ	Polar	250 m x 0.7 deg	400 km radius	8,192,000	1 byte	GRIB2	10 min
	Doppler Velocity	m/s	Polar	250 m x 0.7 deg	250 km or 150 km radius	512,000 or 307,200	1 byte	GRIB2	10 min

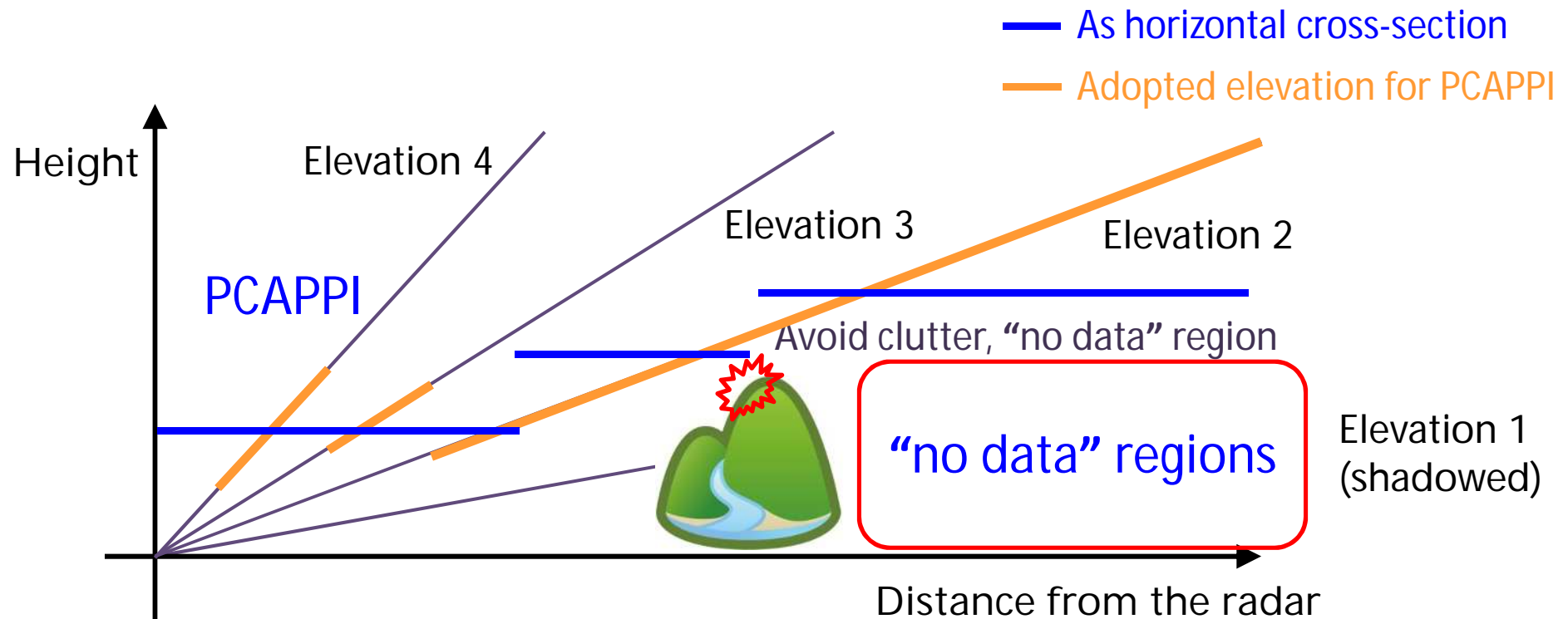
# CAPPI

- CAPPI stands for Constant Altitude Plan Position Indicator.
- A horizontal cross-section display of a variable at a specified altitude.



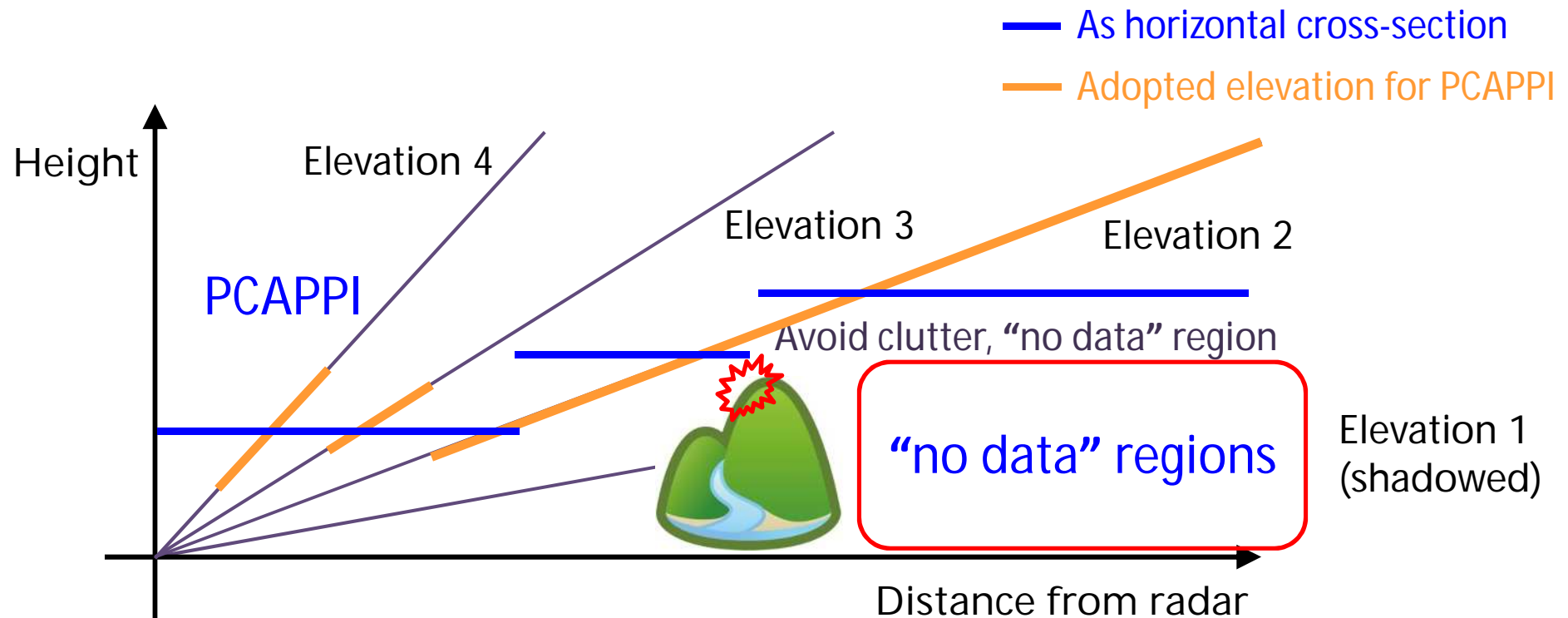
# Pseudo CAPPI

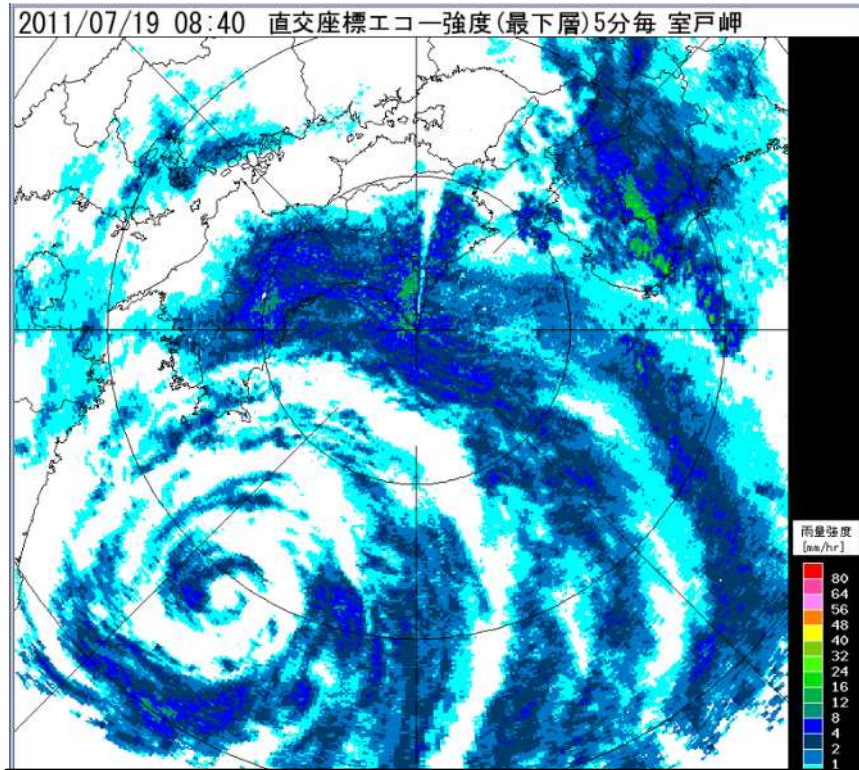
- The “no data” regions as seen in the CAPPI (close to and away from the radar with reference to the selected altitude) are filled with the data from the highest and the lowest elevations, respectively, in another form of CAPPI, called “Pseudo CAPPI”.



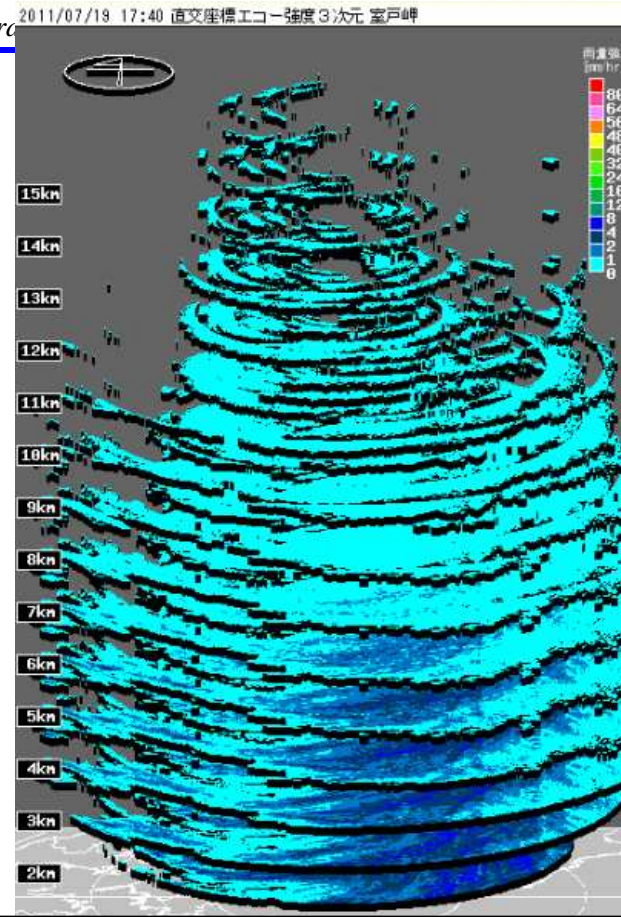
# Pseudo CAPPI

- Topography and suitable observation elevation depend on the place of radar sites.
- Every radar requires this setting for every direction. This setting for JMA methods of PCAPPI is called “elevation angle composite table.”





Pseudo CAPPI

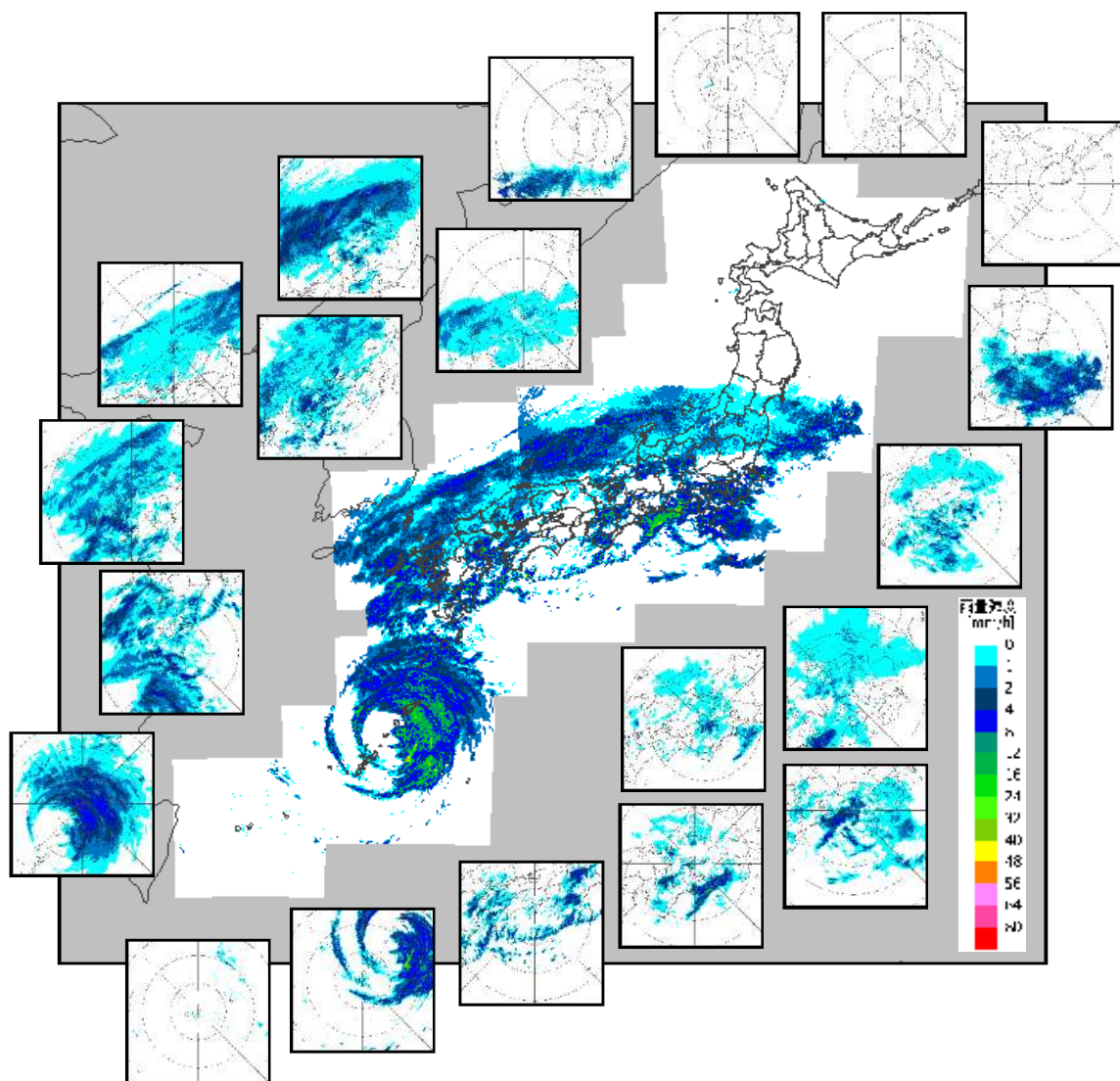


15 layers CAPPI

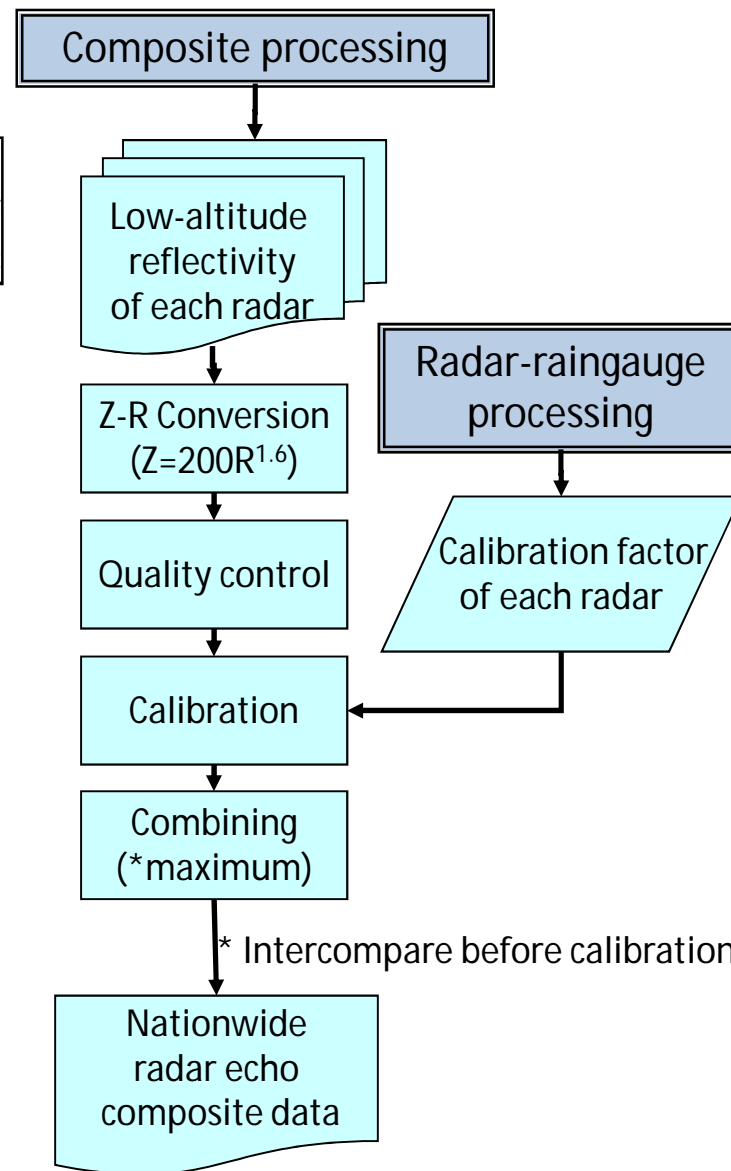
Data Type		Unit	Coordinates	Mesh Size	Area	Number of Mesh	Data Size (one mesh)	Data Format	Period
Each radar	Pseudo CAPPI	mm/hr	xy	1 x 1 km	500 x 500 km	250,000	1 byte	Radar IO	5 min
	CAPPI	dBZ	xy	1 x 1 km	500 x 500 km	250,000	1 byte	GRIB2	10 min



# Nationwide Radar Composite Precipitation Intensity



All radar echo data are collected to the center system, and nationwide composite map is made.





# Hands-on Training on Weather Radar QC

- Introduction of JMA Operational system
- **Quality control algorithms**
  - Characteristics of non-precipitation echo
  - JMA methods of Pseudo CAPPI process
  - Statistical approach for QC
- Hands on training
  - Adjustment of elevation angle composite table
  - Making PCAPPI and Statistical data
  - Verification of the results



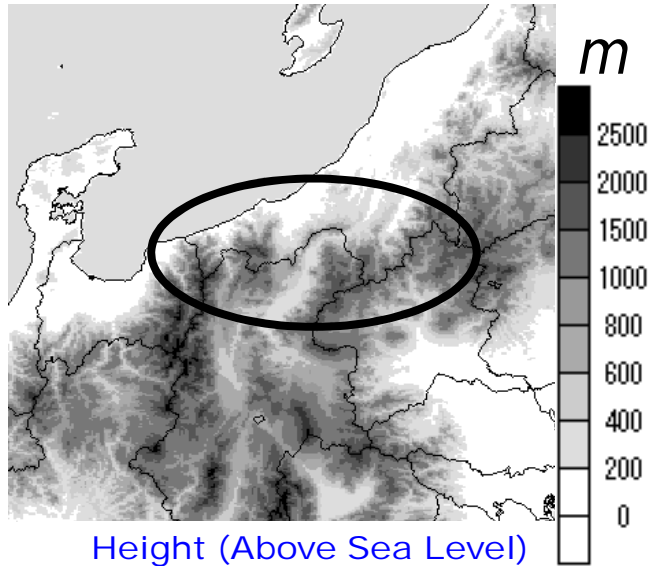
# Ground clutter

- Echoes due to non-precipitation targets are known as clutter.
- Clutter can be the result of a variety of targets, including buildings, hills, mountains, aircraft and chaff.

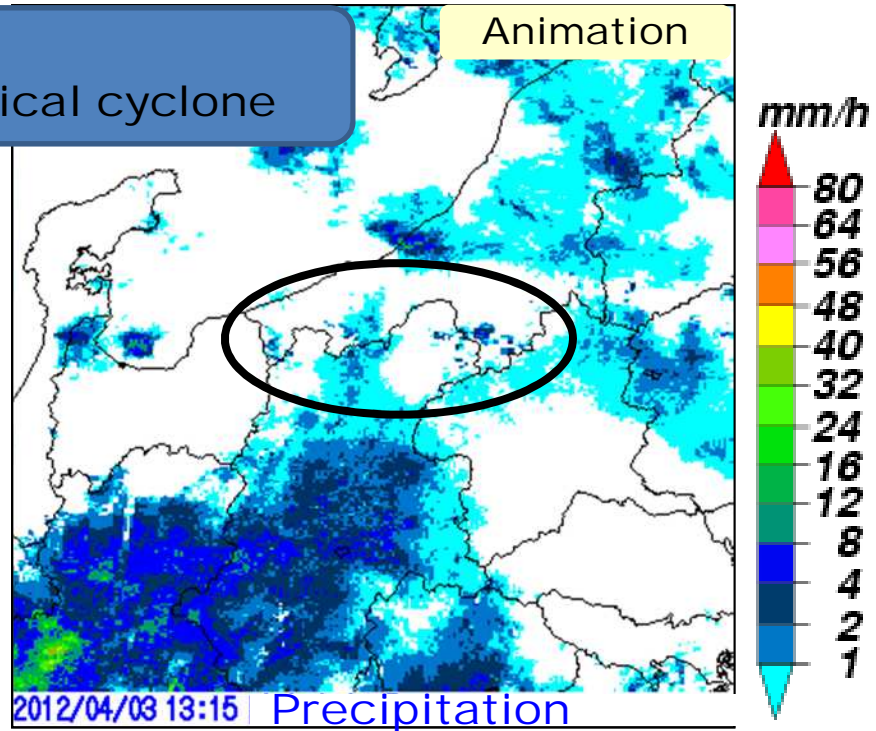
\* WMO GUIDE TO METEOROLOGICAL INSTRUMENTS AND METHODS OF OBSERVATION  
WMO-No. 8 (2008 edition, Updated in 2010) Part chapter 9 radar measurements

# Example of remaining ground clutters

2012/APR/03  
Rapidly developed extratropical cyclone



Height (Above Sea Level)

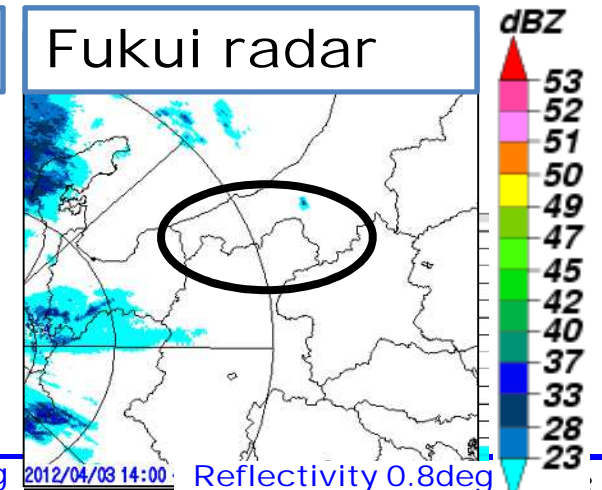


2012/04/03 13:15 Precipitation

- With the passage of a low pressure system, storms occurred across the country. In such cases, ground clutters may not be completely removed. Careful monitoring is required because they do not indicate actual precipitation.

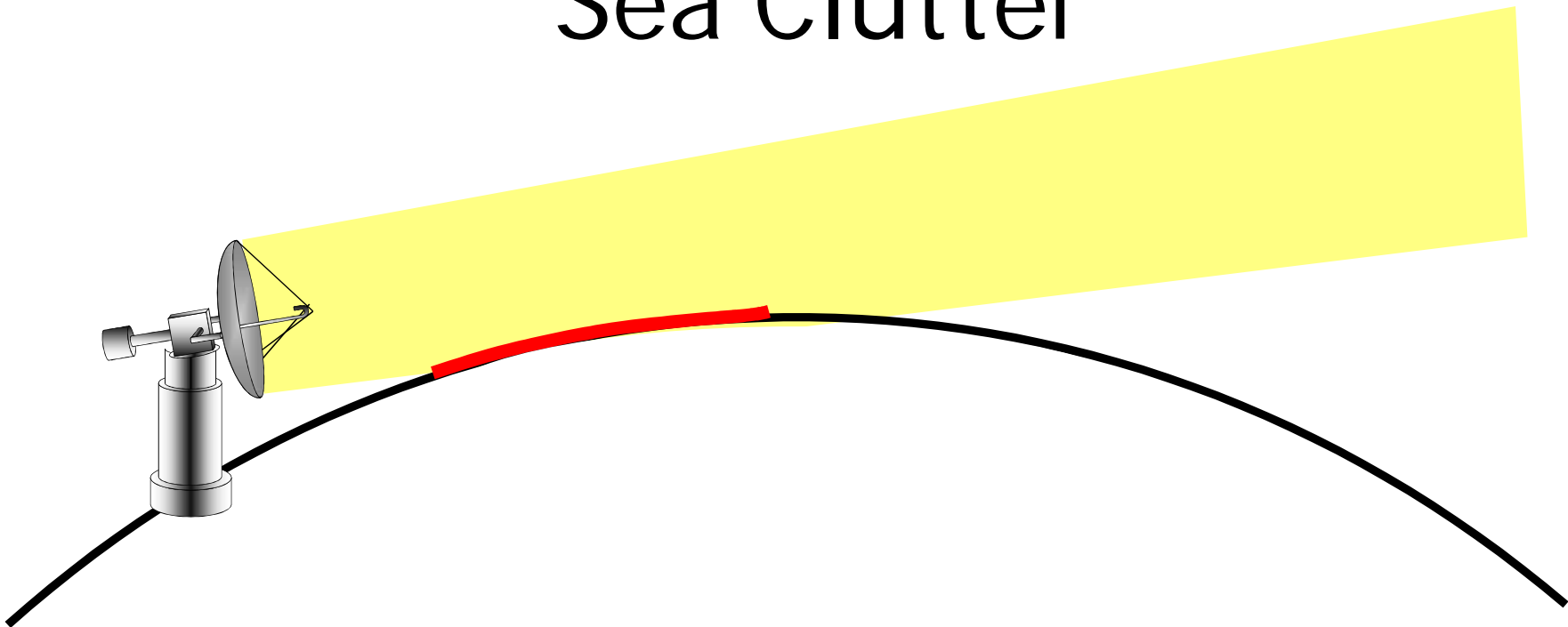


2012/04/03 14:00 Reflectivity 0.4deg



2012/04/03 14:00 Reflectivity 0.8deg

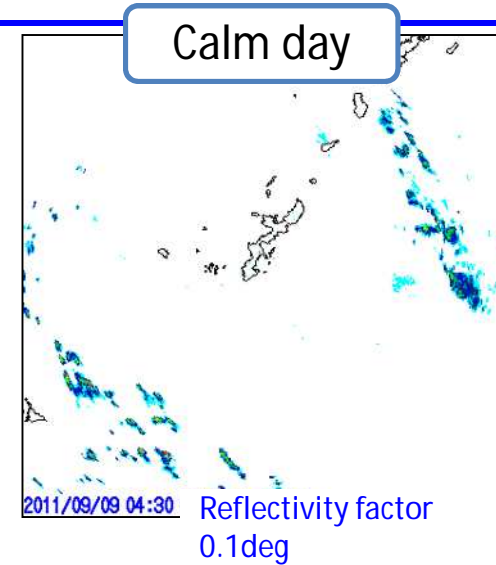
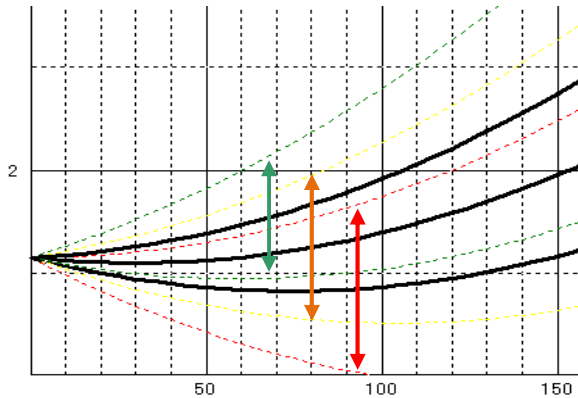
# Sea Clutter



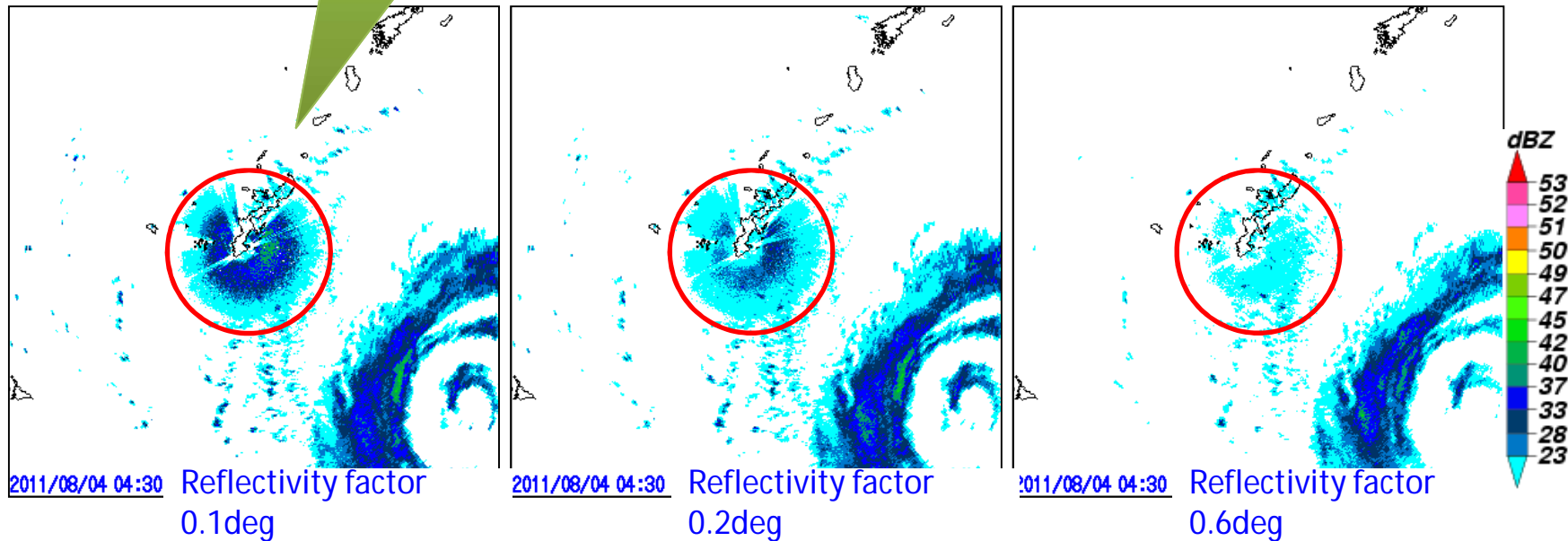
- Sea clutter is observed caused by sea wave or sea spray.
- Because of sea wave motion, suppression by MTI does not work well.
- For the elimination of usual sea clutters, the radar scans with high elevation angle are employed to produce the PCAPPI .

2011/08/04  
Typhoon MUIFA (1011)

  
Sea clutter

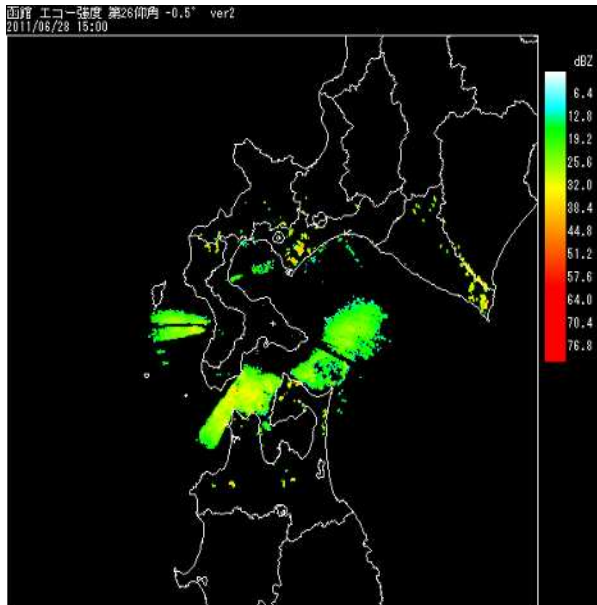
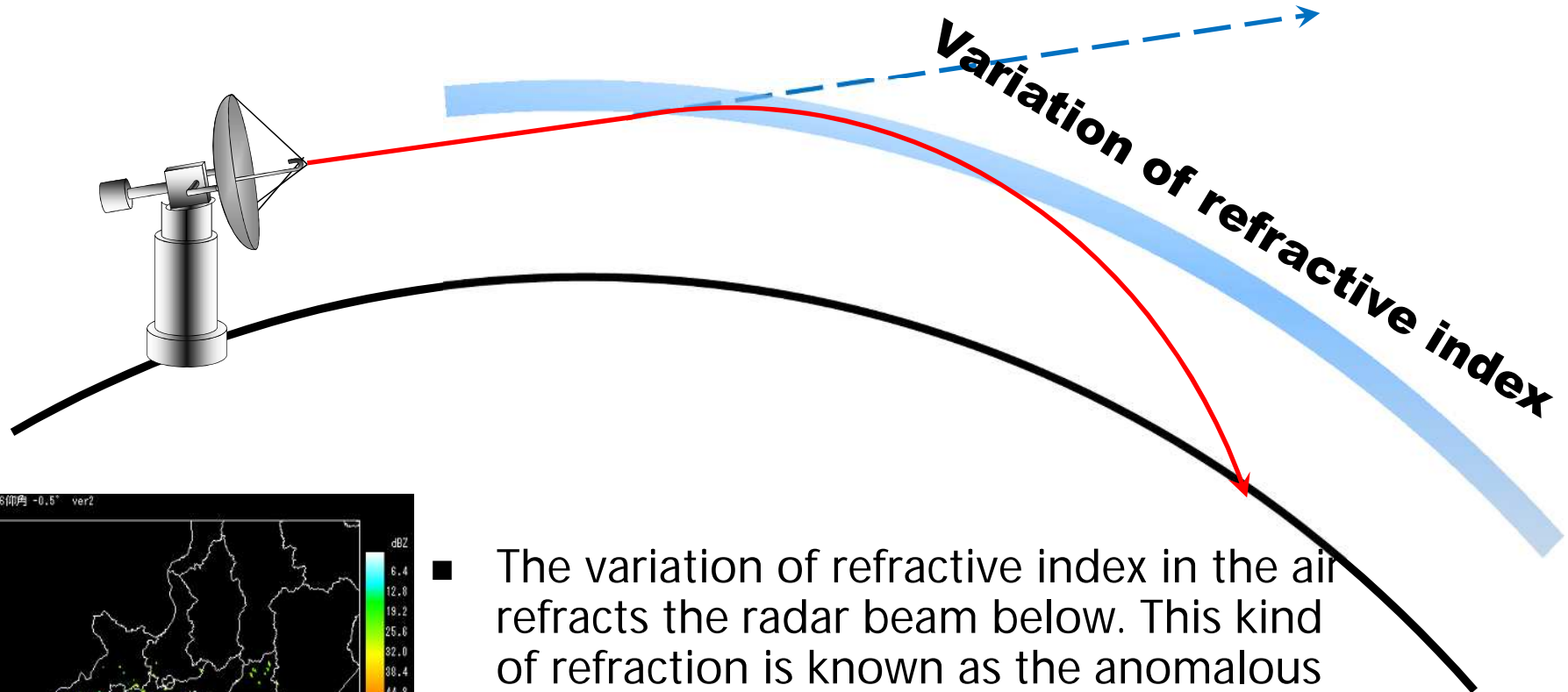


Okinawa radar



- In windy situations, the sea spray may be observed at low elevation angles.

# Anomalous propagation

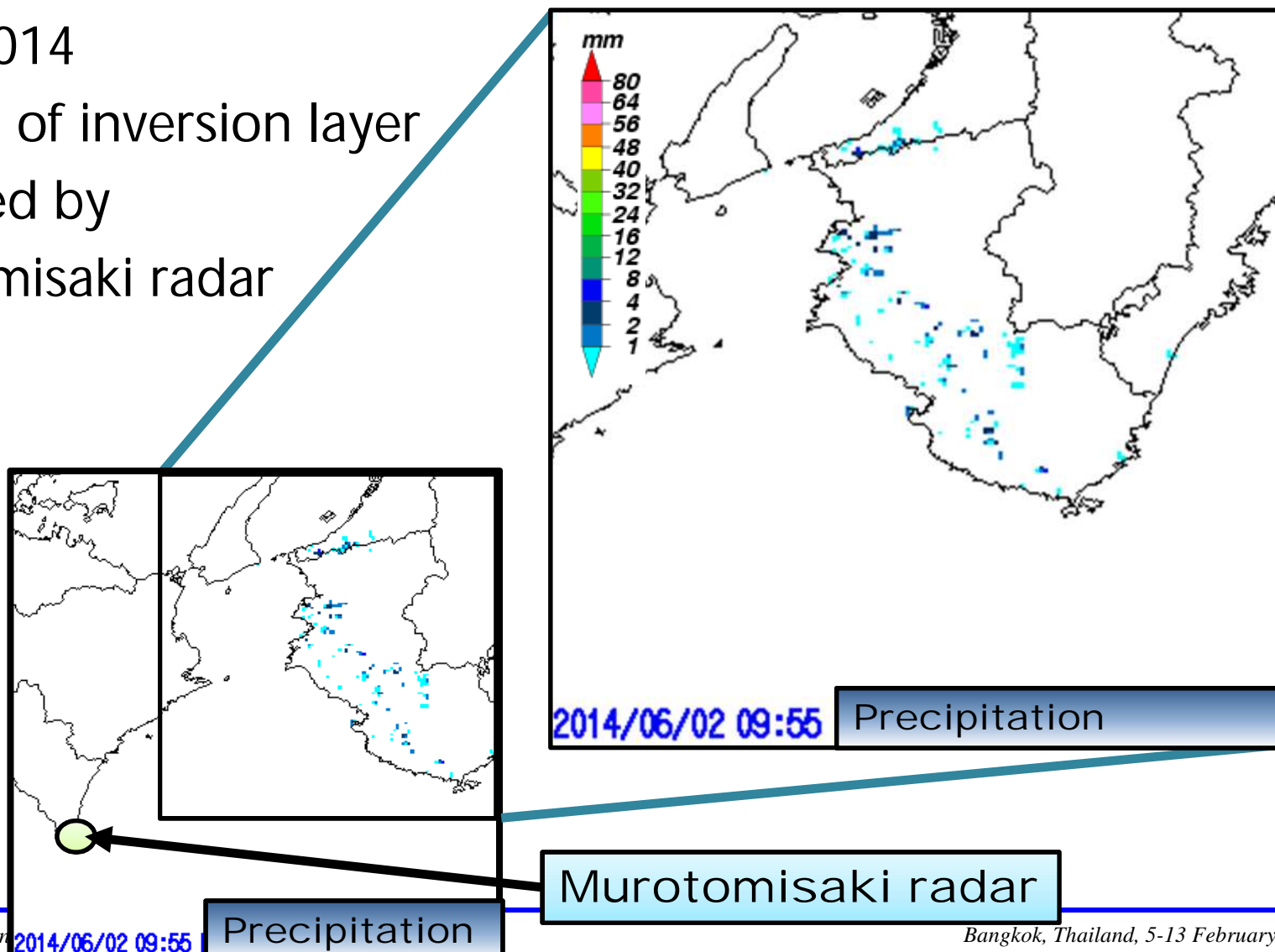


- The variation of refractive index in the air refracts the radar beam below. This kind of refraction is known as the anomalous propagation.
- The anomalous propagation produces some false echoes, in most cases as sea clutter.

An example of non precipitation echo due to anomalous propagation

# AP case of JMA radar

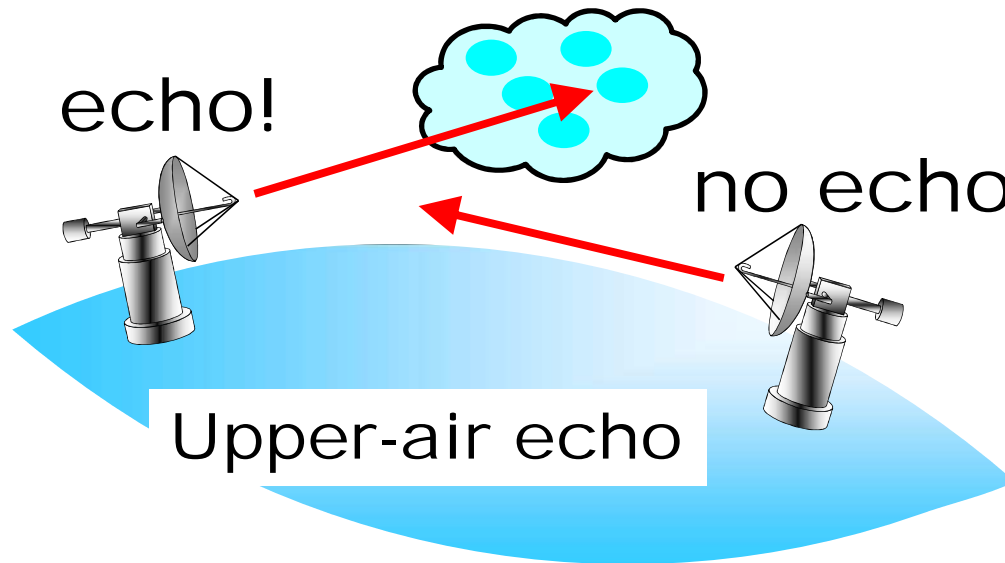
- Jun/2/2014
- Because of inversion layer
- Observed by Murotomisaki radar



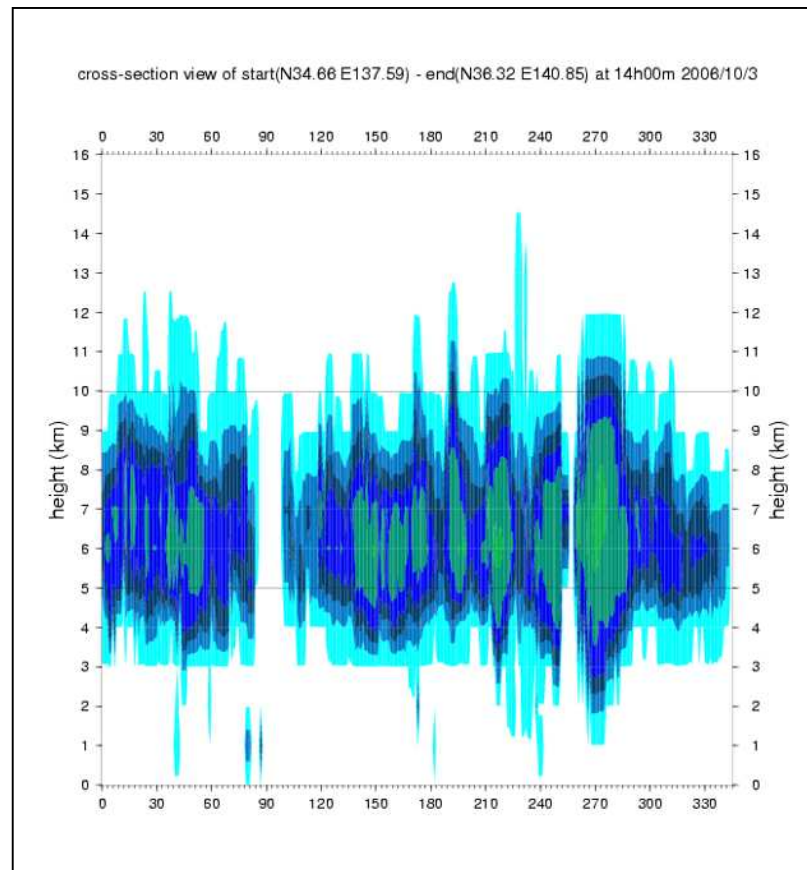
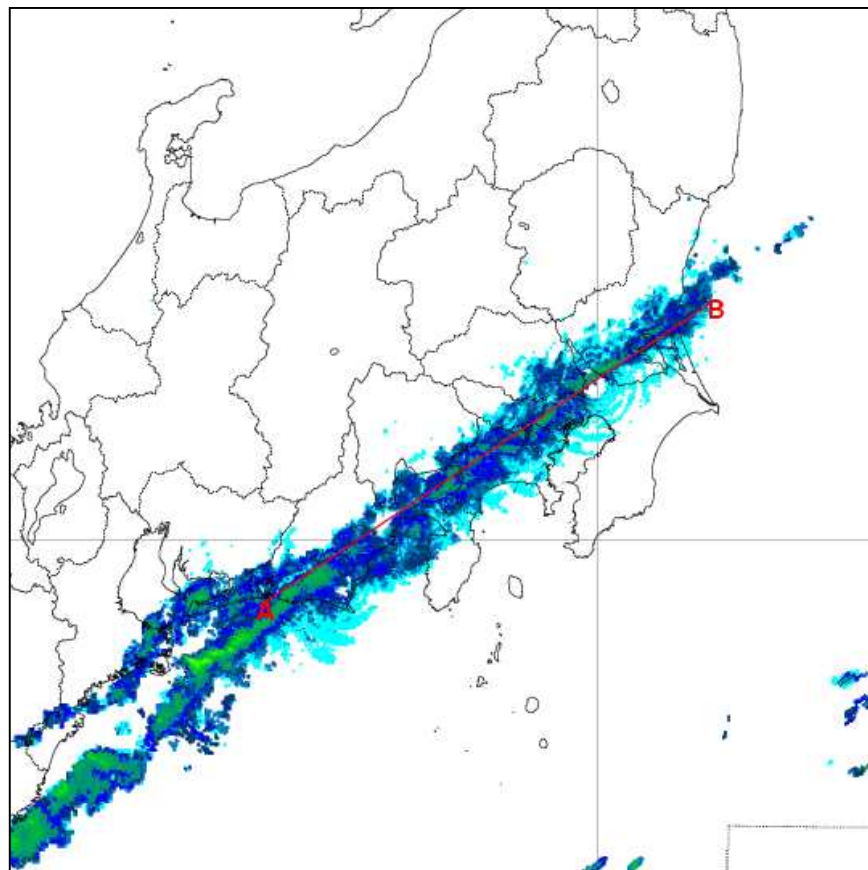


# Echo at upper altitudes

- upper-air echoes -

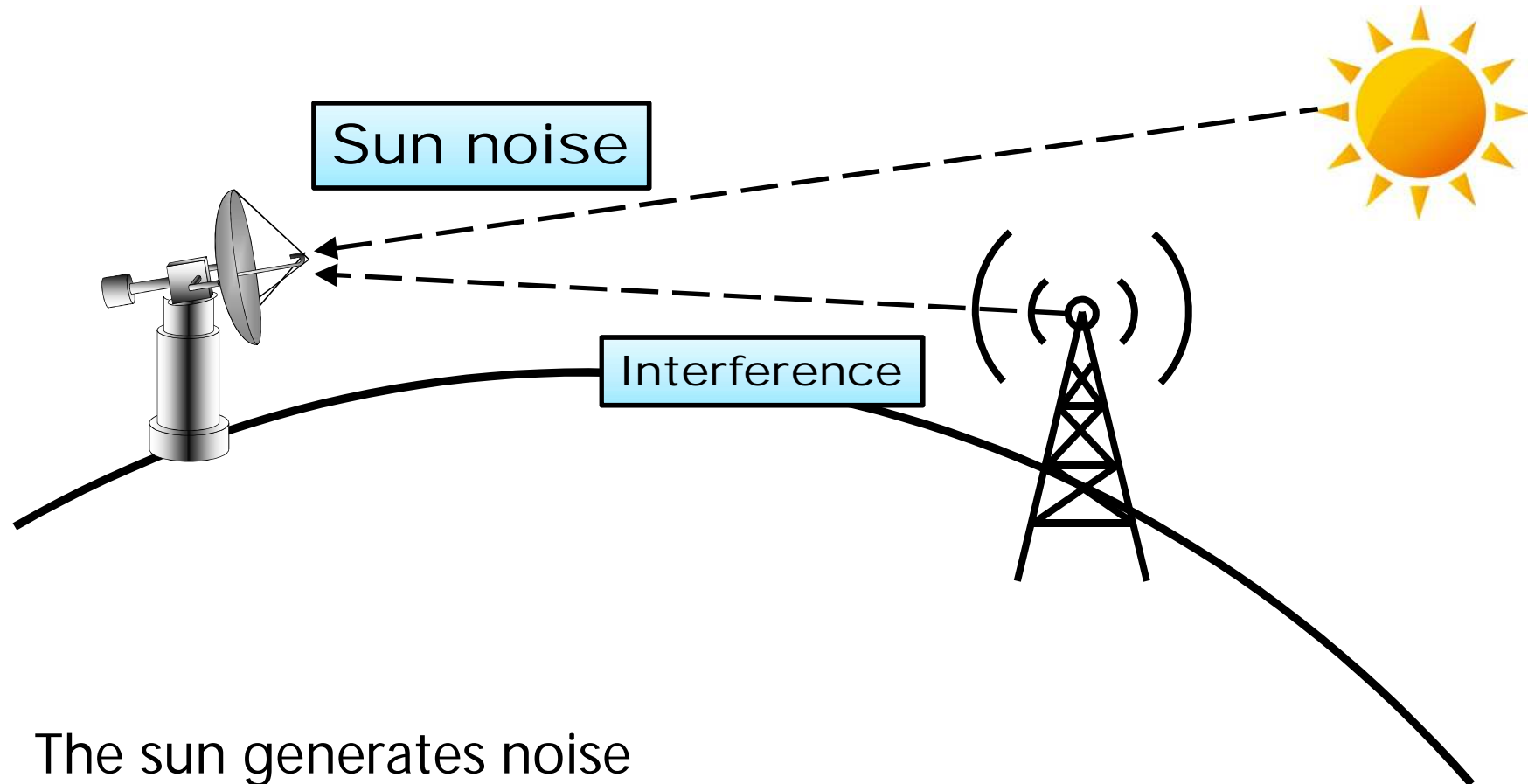


- The radar echo is sometimes observed only at upper altitudes.
- In this case, the liquid drop is completely vaporized during its falling, so precipitation don't reaches the ground.



CAPPI image at an altitude of 6 km(left)  
and cross section(right)

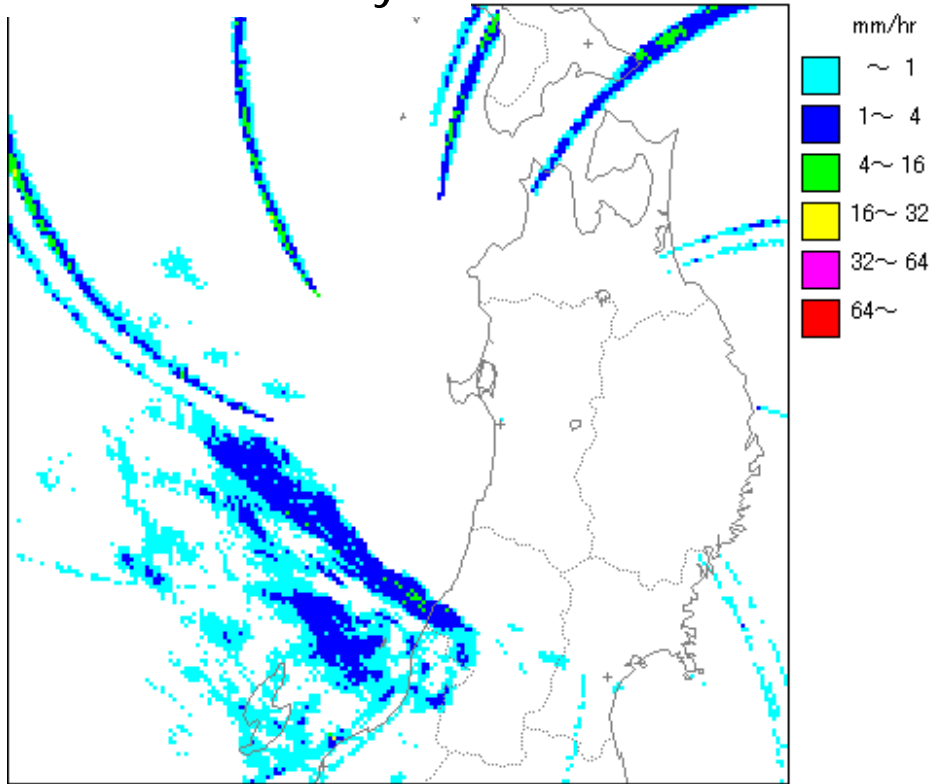
# Various Types of Electromagnetic Noises



- The sun generates noise
- The interference comes from artefactual electromagnetic sources.

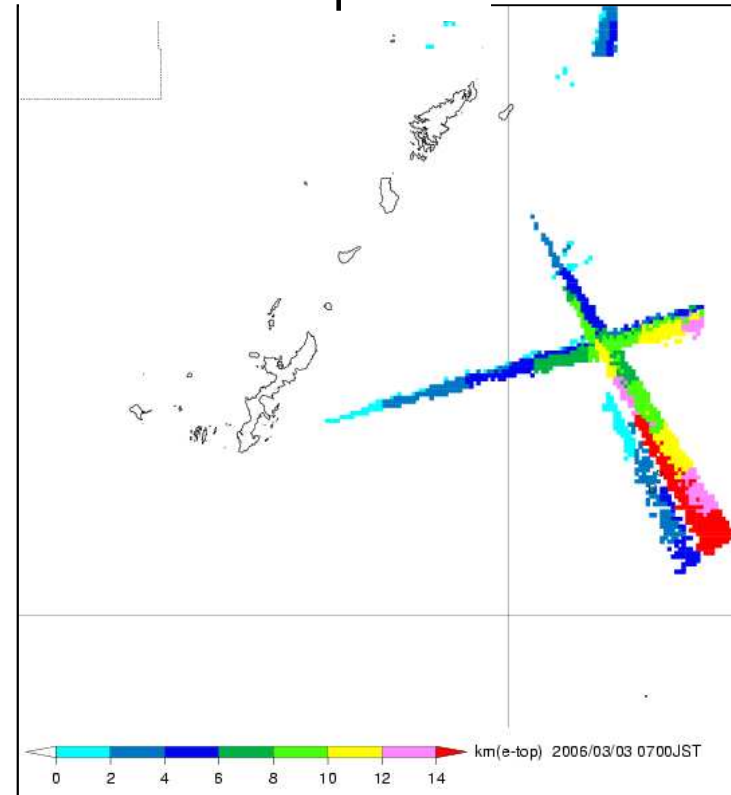
# Examples of interference

Echo Intensity



Interference from another radar

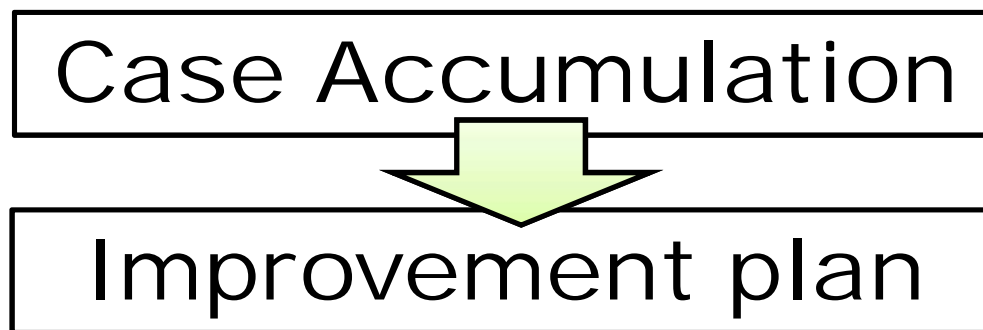
Echo Top



Interference from moving body

# Importance of Case Accumulation

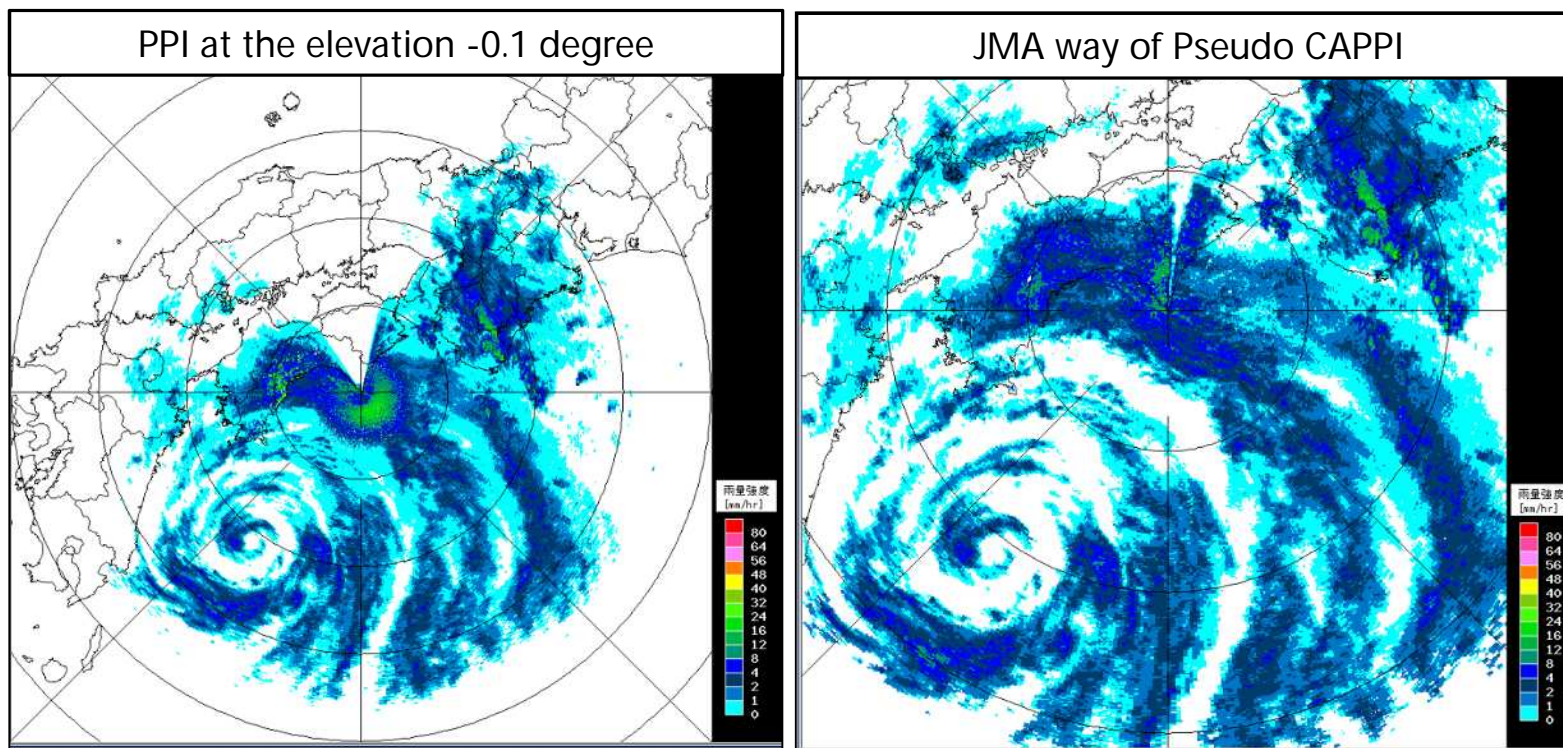
- It is important to accumulate cases of anomalous echo.
- It will be very useful for QC.
- The materials should include Meteorological information such as
  - *Weather charts*
  - *Various observations (AWS, sonde, satellite, radar...)*



# Hands-on Training on Weather Radar QC

- Introduction of JMA Operational system
- **Quality control algorithms**
  - Characteristics of non-precipitation echo
  - **JMA methods of Pseudo CAPPI process**
  - Statistical approach for QC
- Hands on training
  - Adjustment of elevation angle composite table
  - Making PCAPPI and Statistical data
  - Verification of the results

# JMA way of Pseudo CAPPI

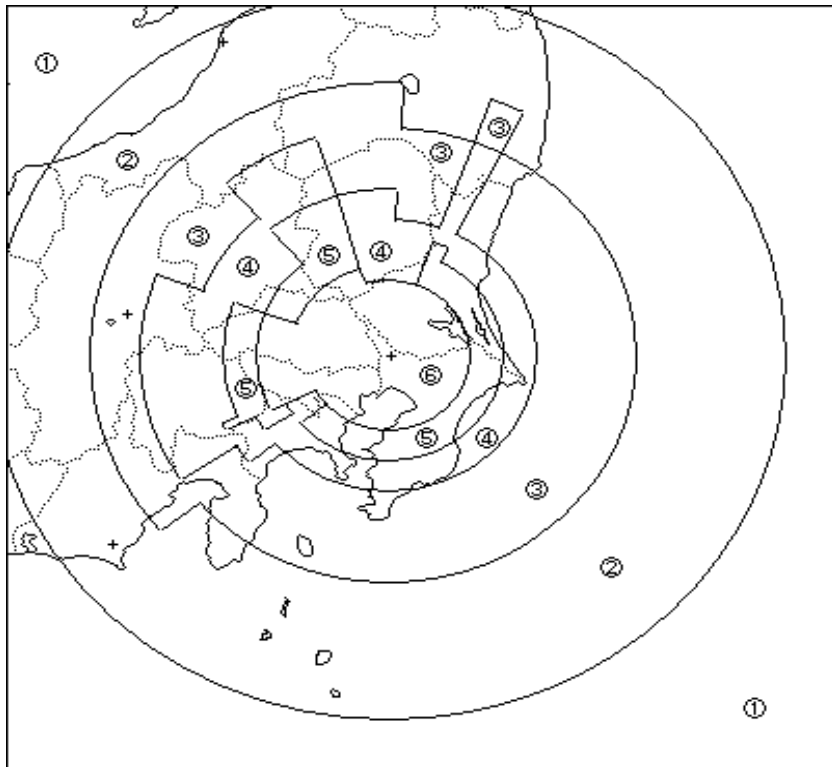


JMA methods of Pseudo CAPPI (PCAPPI); height is about 2 km by using several PPIs at low elevation angles.

This data can remove sea clutters and also ground clutters.

# Elevation angle composite table

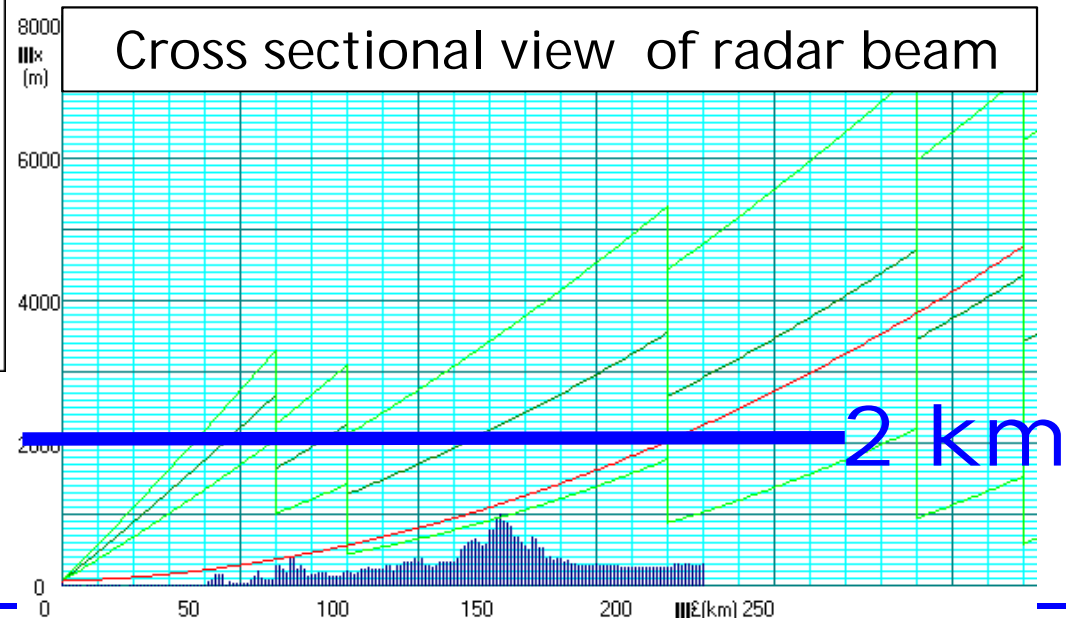
Elevation angle composite table is parameters for making Quality Controlled CAPPI data



- Selecting an optimal elevation angle located near 2 km altitude in each place
- Avoiding an effect of ground clutter

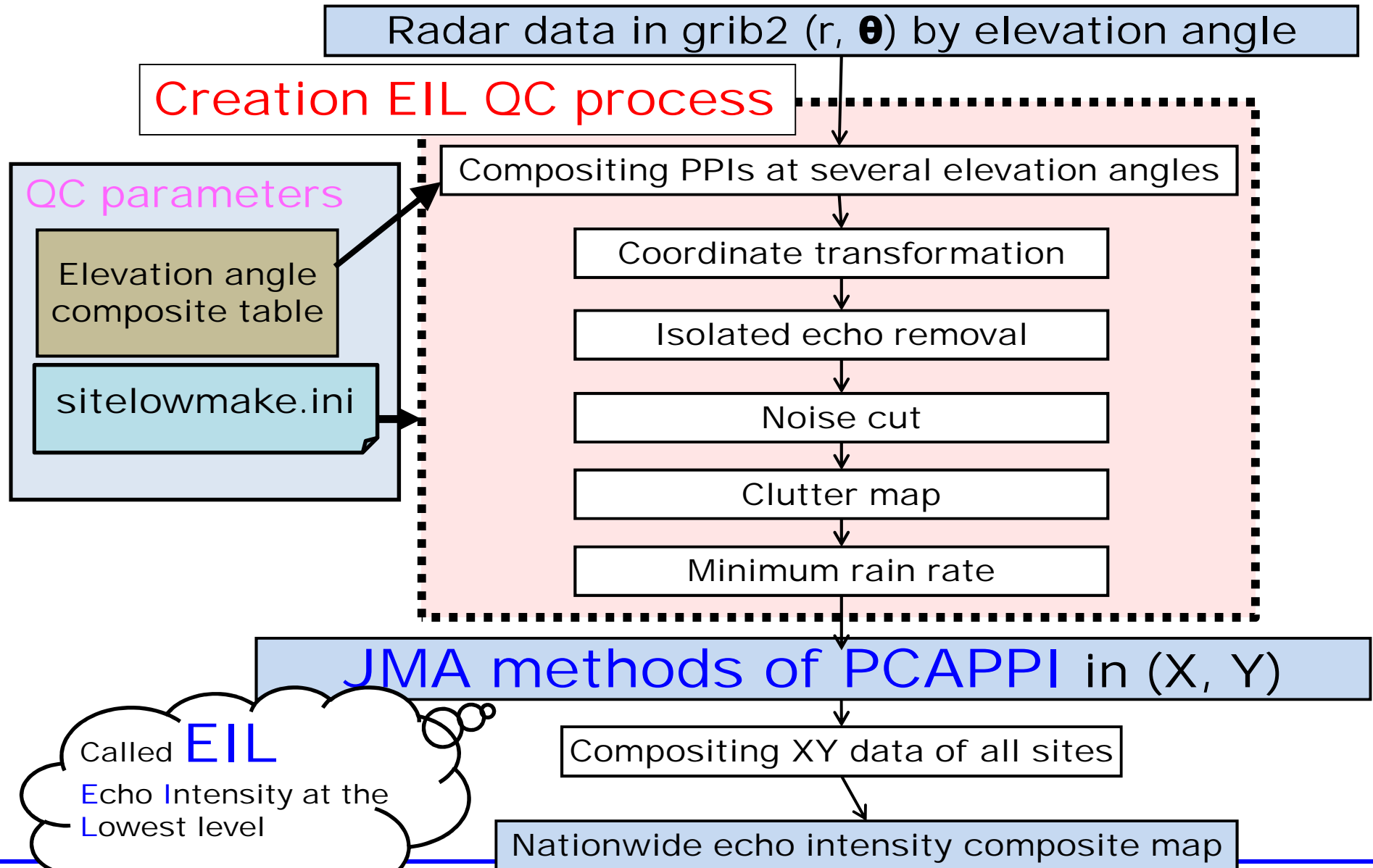
<Elevation>

- (1) 0.0deg (2) 0.3deg (3) 0.7deg  
(4) 1.1deg (5) 1.7deg (6) 2.5deg





# Data processing flow for PCAPPI



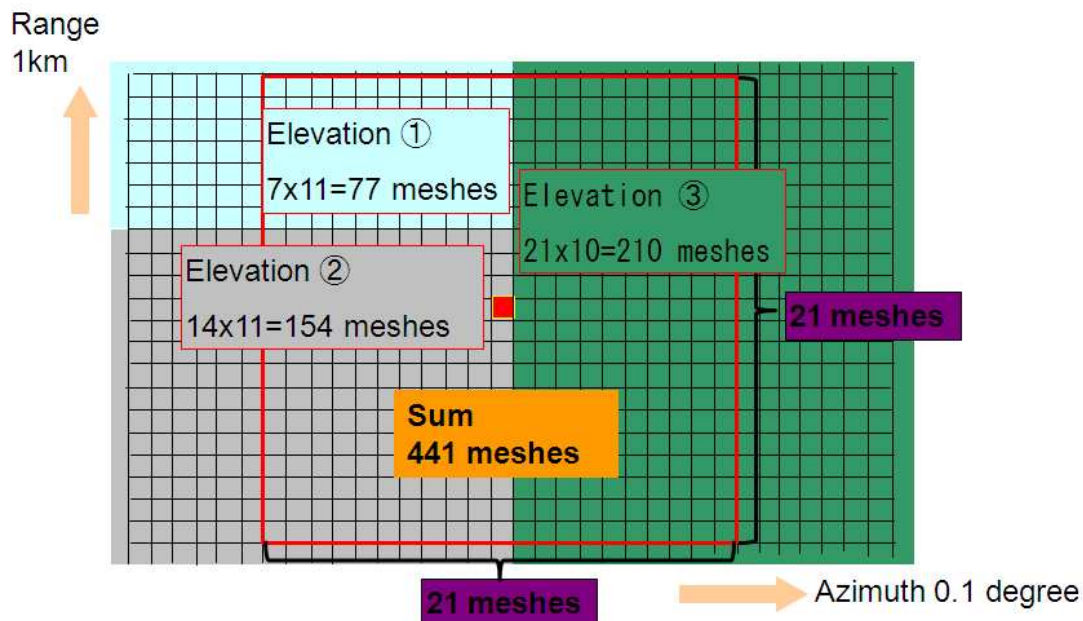
# Parameters Ex.)

```
[47695]
elangles=3.8,2,1.0,0.3,1.7,1.1,0.7,0.3,0.0,25.0,17.9,1
2.9,9.3,6.7,3.8,2.0,1.0,0.3,4.8,3.5,2.5,1.7,1.1,0.7,0.3,
0.0
use_angle_10a=0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0
,1,1,1,1,1,1
code=A5
ename=tokyo
offx=20
offy=20
n0=51.1
noise_cut=704
rain_cut=33
iso_window=5
iso_count=5
smooth_r=100
smooth_t=10
clut1_file=CLUT¥"aa¥"_00_1
clut1_type=3
clut1_wx=3
clut1_wy=3
clut1_count=0
clut2_file=
clut2_type=3
clut2_wx=0
clut2_wy=0
clut1_count=0
B=200
beta=1.6
```



sitelowmake.ini

# Smoothing around border of composite table



Smoothing around border of elevation angles to avoid discontinuity at connection in elevation angle composite process. The smoothing areas is 10km around border. We count the number of meshes every angle, and use them as weight for the averaging intensities. The left figure shows an example.

Elevation 1 is 77 meshes 30dBZ  
Elevation 2 is 154 meshes 50dBZ  
Elevation 3 is 210 meshes 35dBZ

$$\text{Smoothed intensity} = \frac{77 \cdot 10^{(30/10)} + 154 \cdot 10^{(50/10)} + 210 \cdot 10^{(35/10)}}{441} = 36601.08$$

$$\text{Logarithmic value, } 10 * \log 36601.08 = 45.63 \text{ ( dBZ )}$$

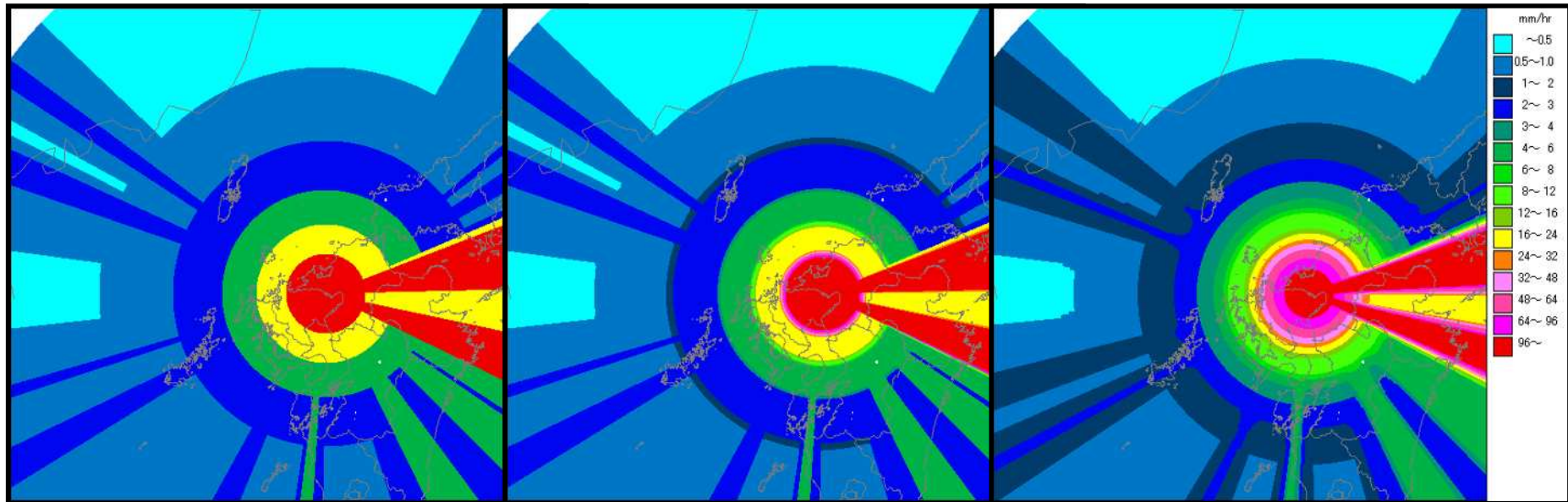
# Smoothing

## Test

Without smoothing

After smoothing: 1

After smoothing: 2



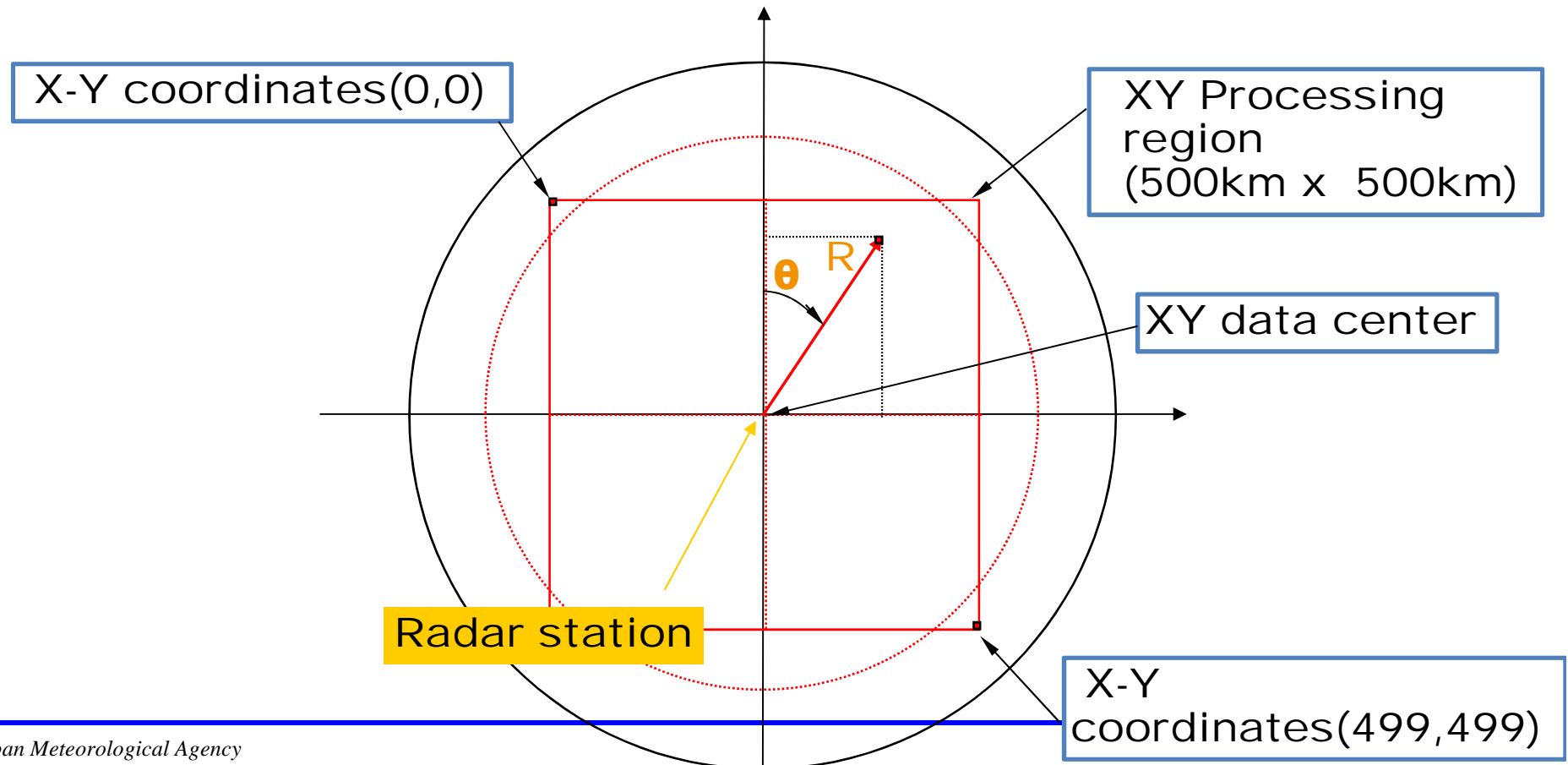
The weights are calculated  
: 10 km in range direction  
: 1 degree in azimuth direction

The weights are calculated  
: 100 km in range direction  
: 10 degree in azimuth direction

```
...  
smooth_r=100 : range for smoothing (km*10)  
smooth_t=10  : azimuth for smoothing (deg*10)  
...
```

# Transformation from Polar coordinates to X-Y coordinates

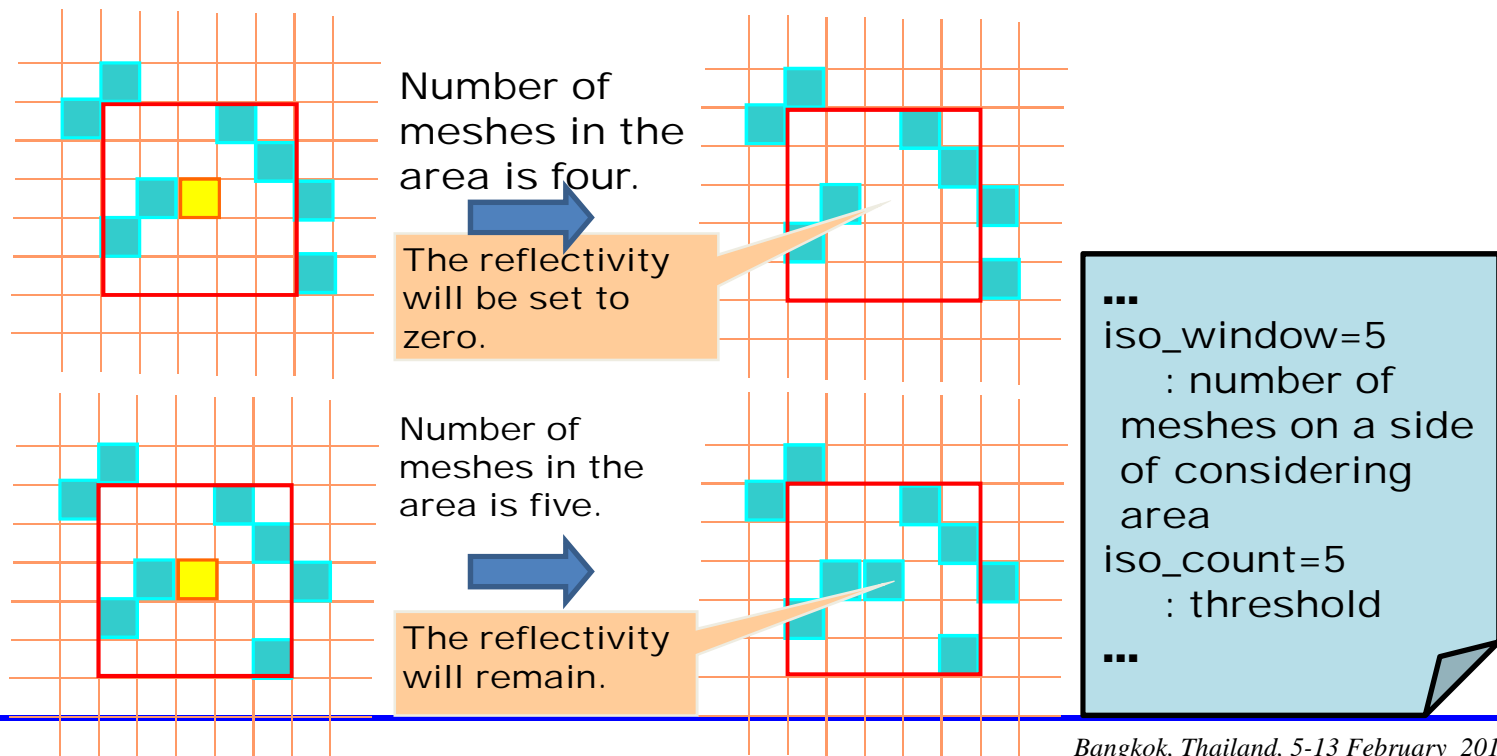
- ❑ Primary data (PPI in polar coordinate  $(R, \theta, \varphi)$ ) are transformed to X-Y coordinates  $(X, Y, \varphi)$  with a spatial resolution of 1km, and an area of 500km  $\times$  500km square X-Y coordinates.
- ❑ The nearest bin in polar coordinate is applied for each mesh in X-Y coordinate.
- ❑ This can reduce data size of huge primary data and make them be easier to use.



# Isolated echo removal

- Removing the isolated echoes caused by ground clutter, ships and aircraft.
  - In the  $5 \times 5$  meshes, the number of meshes of which intensity is larger than zero is counted except of the target center mesh.
  - If the number is below a threshold, the intensity of the mesh is set to zero. If not, it will remain.

Ex.)  
Threshold = 5



# Noise cut

- In this process, echo intensities below a threshold are set to zero, i.e, No Echo.
- This threshold depends on each radar.

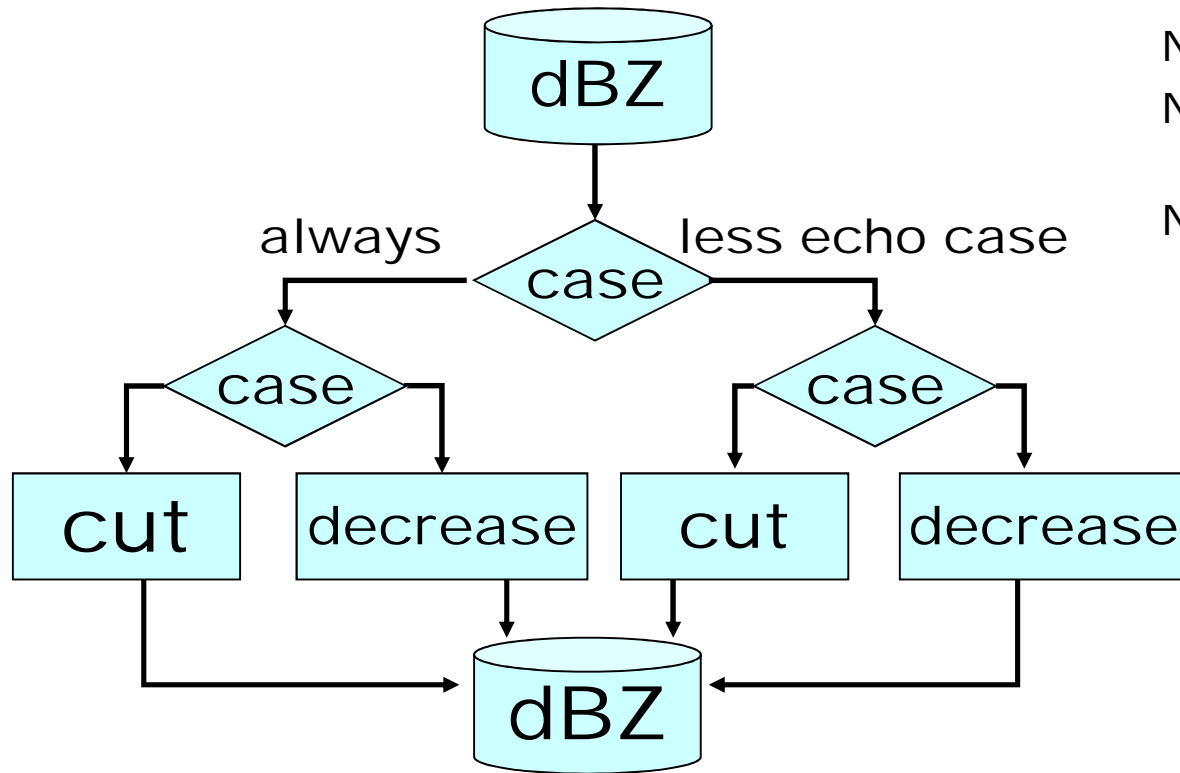
```
...  
noise_cut=704      :  
threshold (dBZ*100)
```

```
...
```

# Clutter map

Clutter map is used when process like MTI could not eliminated clutter. A clutter map has thresholds to delete echoes or values from the observed echo intensities.

$$N_r = N_s + 10 * \log( 1 - 10 ^ ( ( N_g - N_s ) / 10 ) )$$



$N_g$  : clutter map value(dBZ)

$N_s$  : reflectivity before subtraction(dBZ)

$N_r$  : reflectivity after subtraction(dBZ)

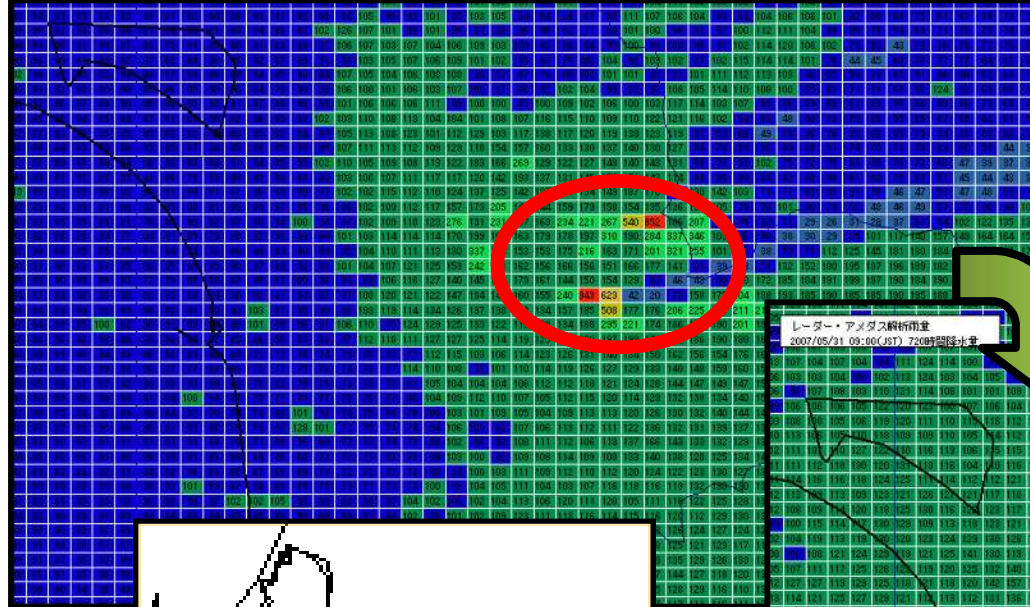
```

...
clut1_file=CLUT¥"aa¥"
_00_1
clut1_type=3
clut1_wx=3
clut1_wy=3
clut1_count=0
...
  
```

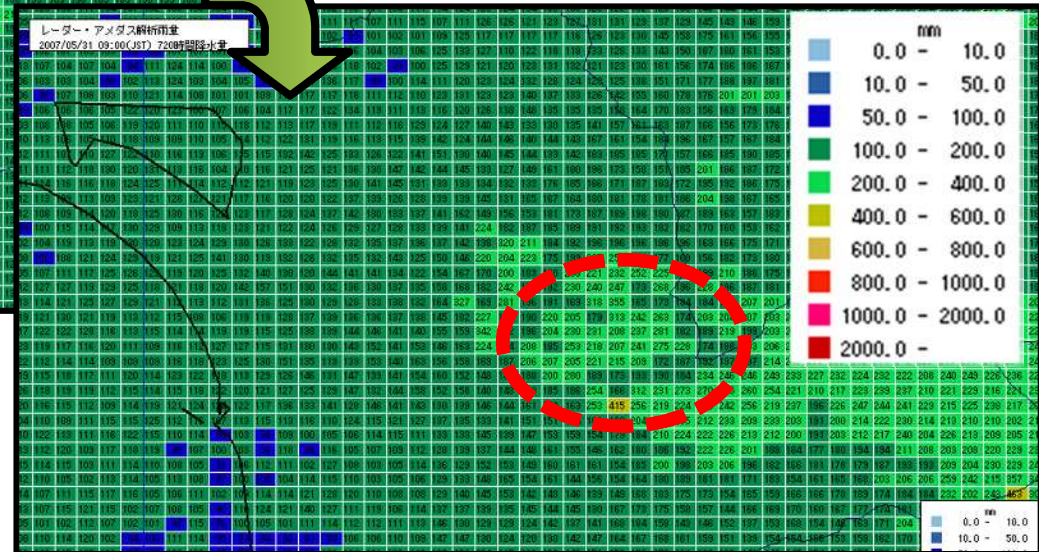
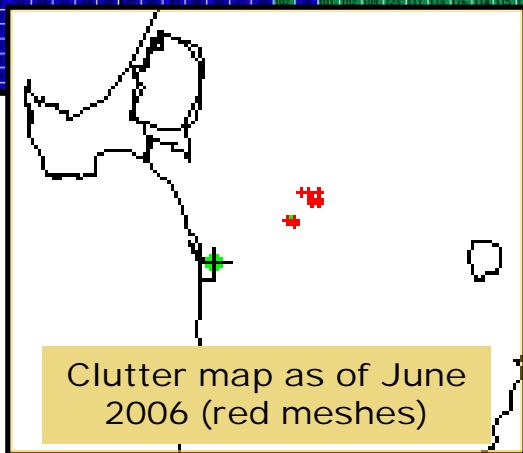


# Example of the impact of clutter map processing on QPE data

1-month accumulated QPE data for May 2006 (before applying clutter map)



We applied clutter map to meshes which shows extremely high value compared to the surrounding meshes decreased.



1-month accumulated QPE data for May 2007 (after applying clutter map)

# Minimum rain-rate

- Minimum rain-rate is a process for cutting low level value after clutter map process.
- If the Nr is below a minimum rain-rate, the Nr is set to zero (No Echo)

Nr : reflectivity after subtraction(dBZ)

```
...  
rain_cut=33      : threshold  
(mm/h*100)  
...
```

# Features of each algorithm

Algorithm	Type	Advantage	Disadvantage
Elevation angle composite table	Selected angle Area:(r,theta)	Sea clutter Ground clutter	
Noise cut Minimum rain-rate	Low level cut Area : all	Low level noise	Low level echo
Clutter map	Level cut(set) Area : mesh	Ground clutter (enable to remove by MTI)	Remove precipitation echo (Labor for setting)

# Summary of EIL process

- EIL process contains many quality control methods.
- In order to create Cartesian data with good quality (less clutter and less noise), we need to set various parameters adequately.
- Removing non-precipitation echo has a possibility also removing precipitation echo.

# Hands-on Training on Weather Radar QC

- Introduction of JMA Operational system
- **Quality control algorithms**
  - Characteristics of non-precipitation echo
  - JMA methods of Pseudo CAPPI process
  - **Statistical approach for QC**
- Hands on training
  - Adjustment of elevation angle composite table
  - Making PCAPPI and Statistical data
  - Verification of the results

# Statistical approach for QC

Statistical method is effective way to understand the quality of radar data.

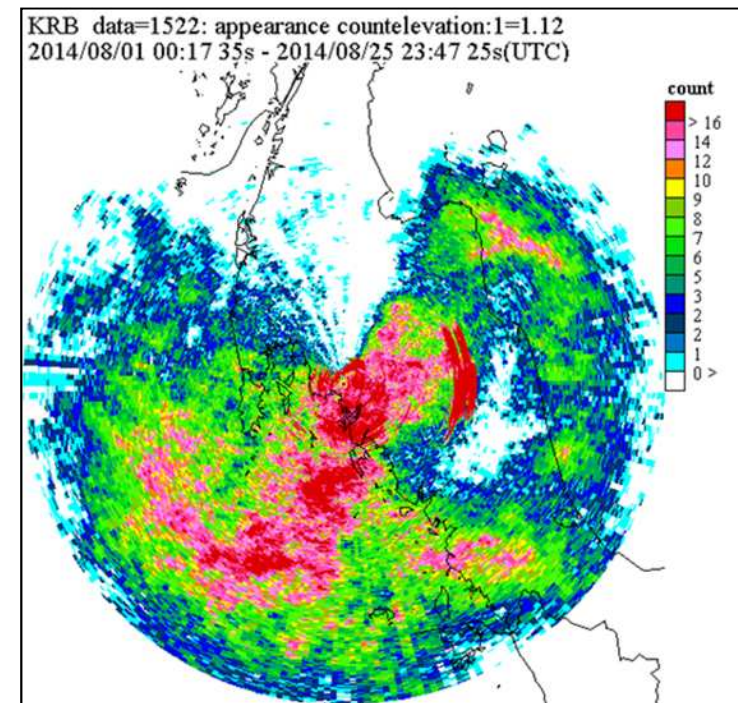
JMA uses the statistics for quality control.

- Appearance count
- Summation

Make every sites, angles and lowest.(monthly)

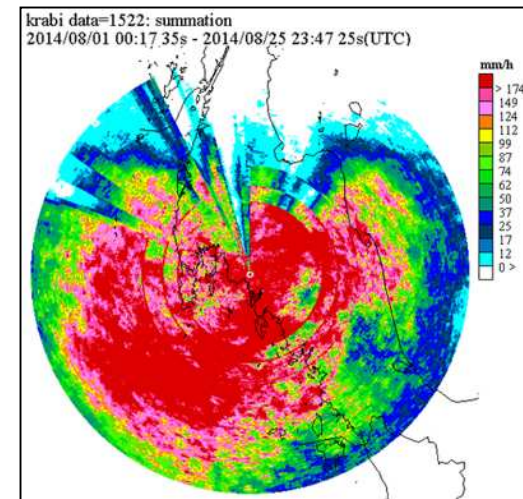
# Appearance Count

- Count over 1mm/h precipitation intensity calculated from dBZ, B, and beta.
- The appearance clarifies : continuous weak echoes



# Summation

- Sum up precipitation from radar data.
- “Appearance count” can’t detect clutter or high intensity echo, but summation can detect these things.
- That would be clear using summation data.
- The summation of precipitation from clutter affects QPE.





# Target

- Every elevation's observation

To understand the characteristics of observation at each elevation.

- EIL (Echo Intensity at the Lowest Level)

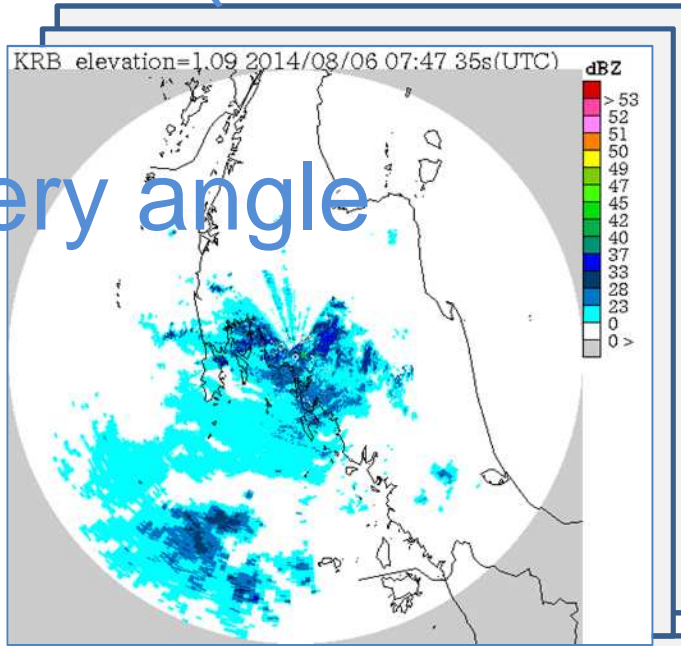
To understand the characteristics of products.

- Shadowed area
- Observable area
- Low quality area

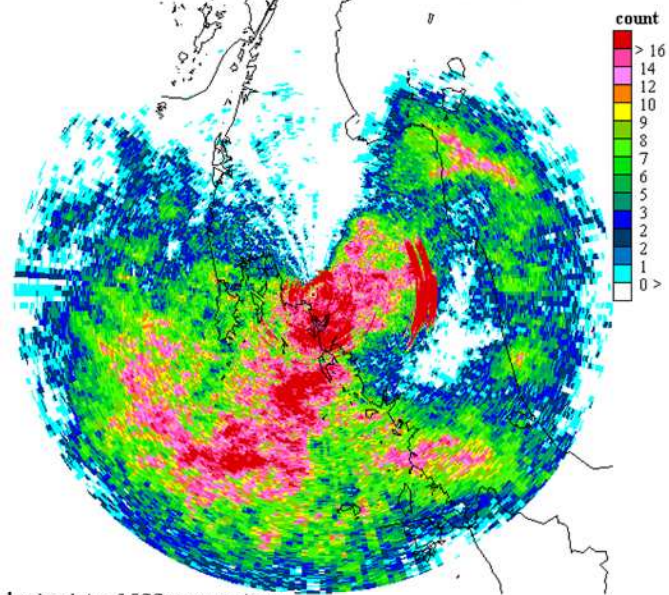
# Each Data(observation time)

# Statistical Data

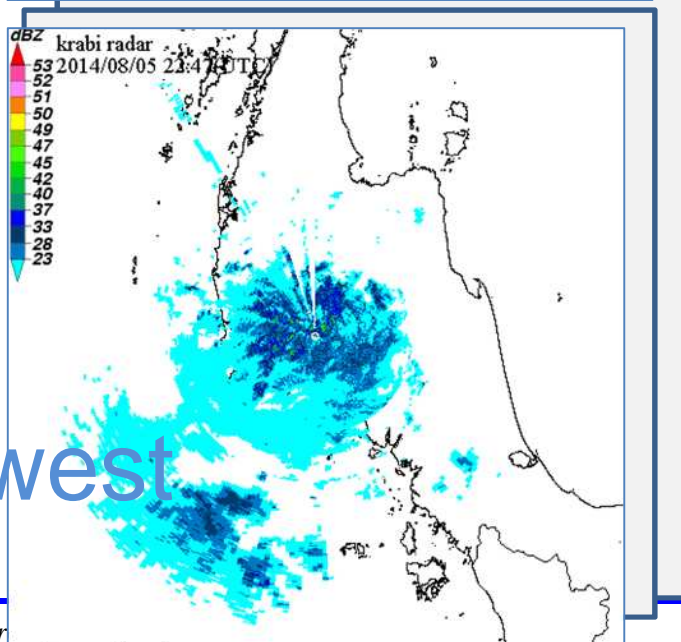
Every angle



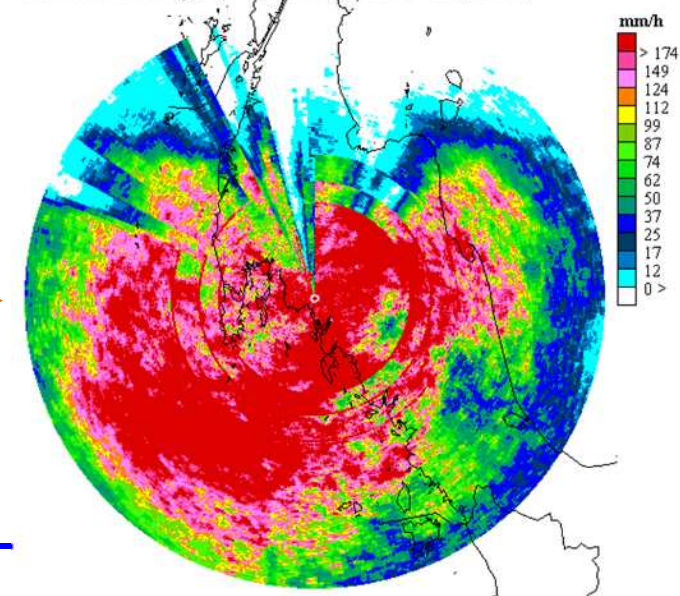
KRB data=1522: appearance countelevation:1=1.12  
2014/08/01 00:17 35s - 2014/08/25 23:47 25s(UTC)



Lowest



krabi data=1522: summation  
2014/08/01 00:17 35s - 2014/08/25 23:47 25s(UTC)



# In Statistical program

- Use average instead of Summation
  - Equivalent ( with using data count)

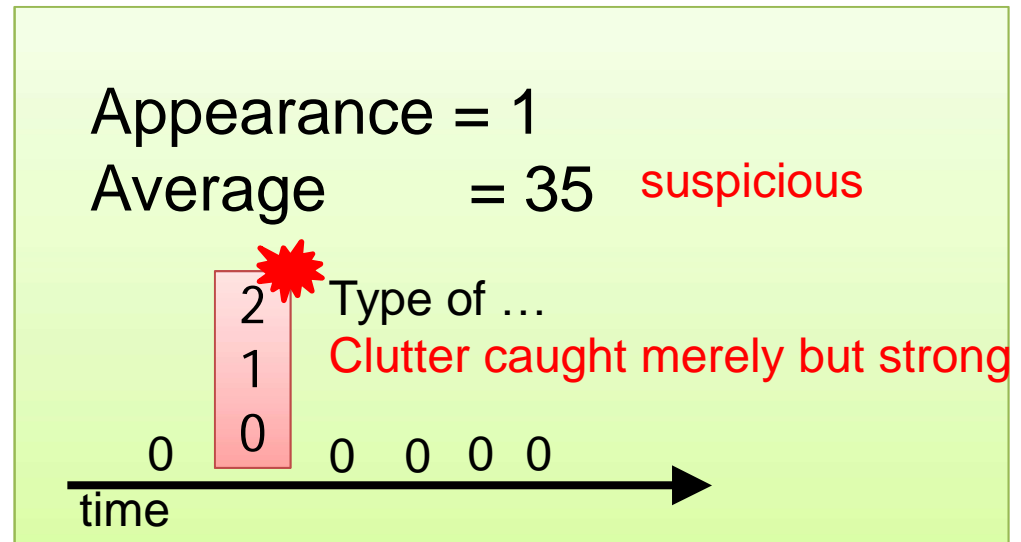


# How to detect clutter

Various type of clutter exists but ...

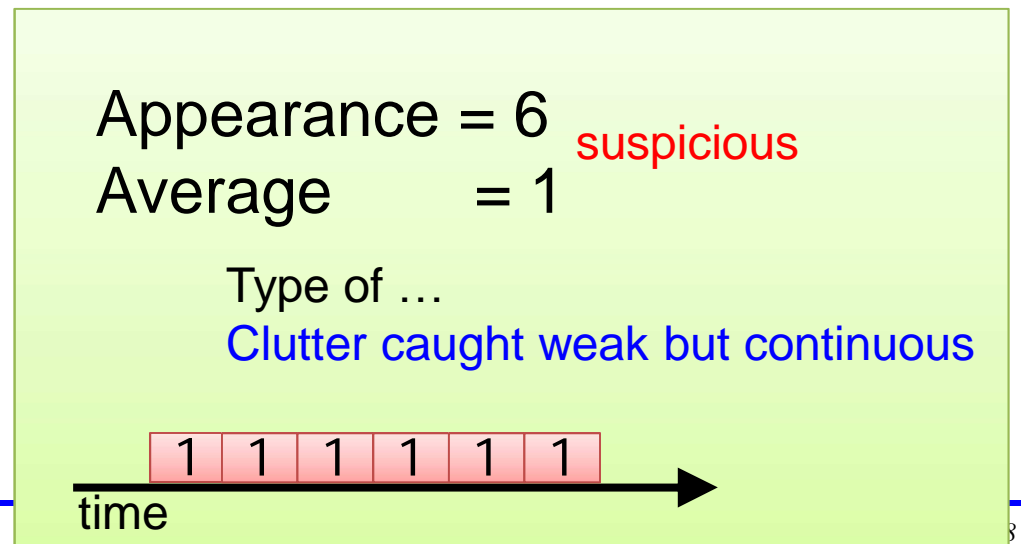
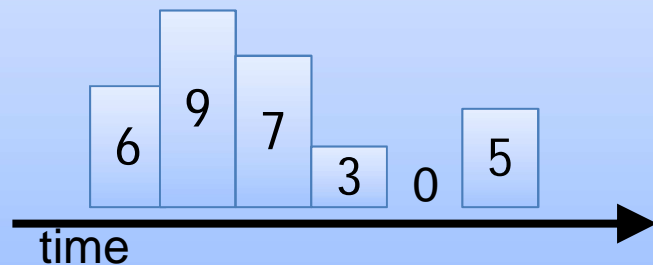
- Advantages

- Average
  - Merely but strong
- Appearance
  - Weak but continuous



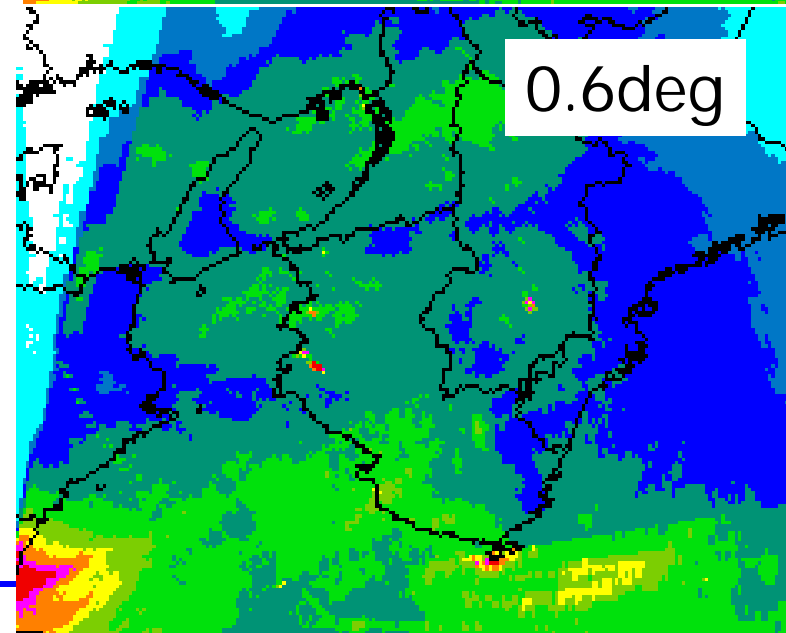
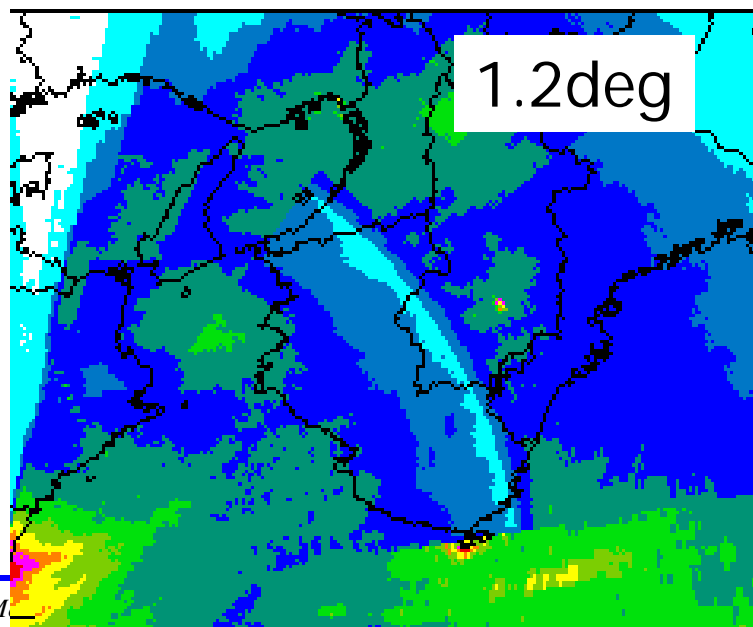
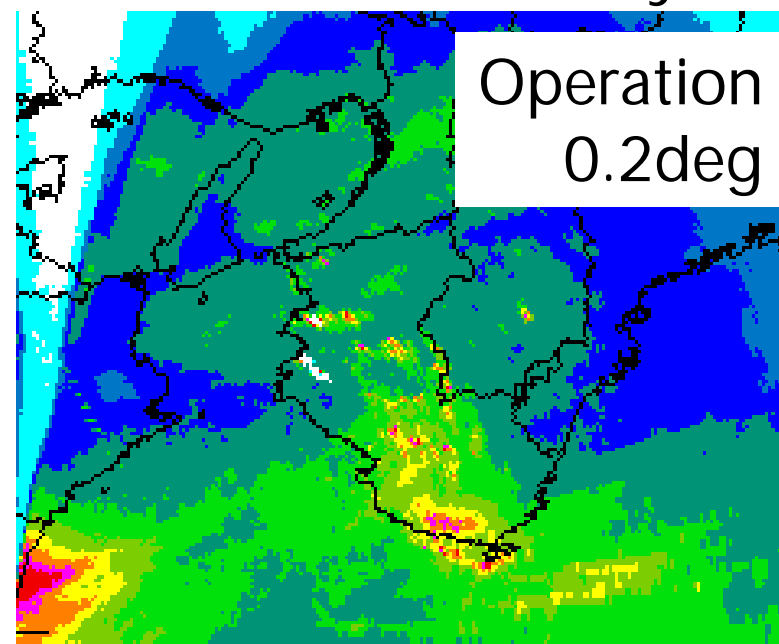
Precipitation case is not so suspicious

Appearance = 6  
Average = 5



## Summation Test of MUROTOMISAKI Radar May. 2014

- 0.2 deg is operation.  
(observational product)
- 0.6 deg test decrease the clutter.
- 1.2 deg test also decrease the clutter ,but decrease real precipitation echo.



# Summary of Quality control

- Anomalous echo is too intense echoes compared with the actual precipitation area. Such as,
  - Ground clutter
  - Sea clutter
  - Anomalous propagation ... etc.
- Complete elimination is impossible by automatic processing
- System operators must check such echoes
- Case accumulation contributes to QC

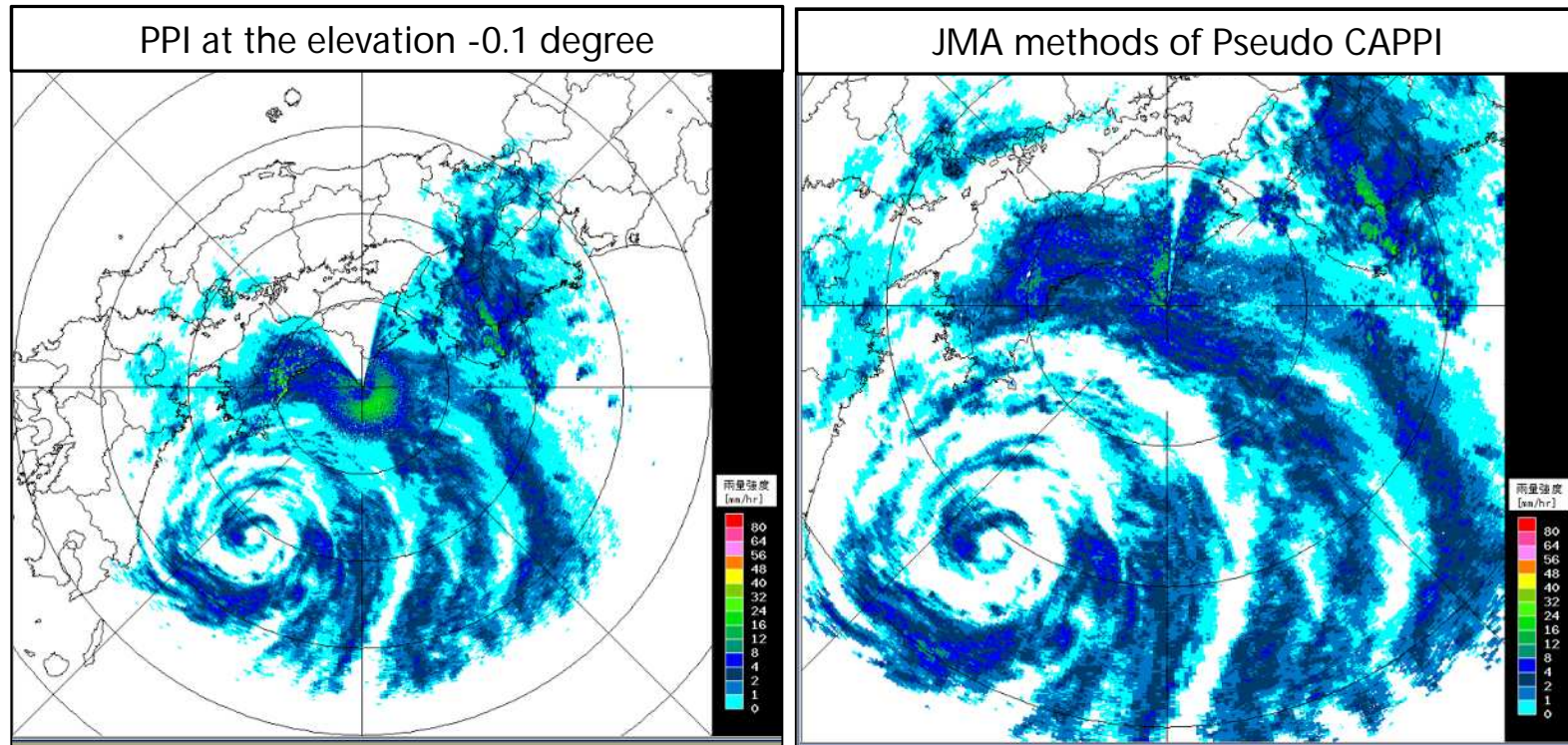
Thank you for your attention !!



# Hands-on Training on Weather Radar QC

- Introduction of JMA Operational system
- Quality control algorithm
  - Characteristics of non-precipitation echo
  - JMA methods of Pseudo CAPPI process
  - Statistical approach for QC
- **Hands on training**
  - Adjustment of elevation angle composite table
  - Making PCAPPI and Statistical data
  - Verification of the results

# JMA methods of Pseudo CAPPI



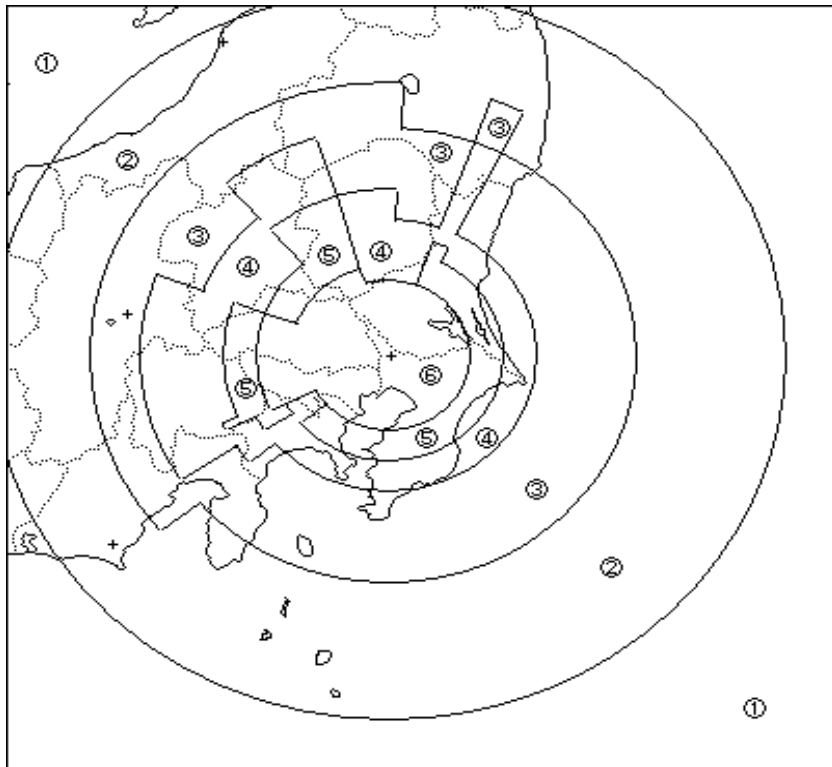
JMA methods of Pseudo CAPPI (PCAPPI); height is about 2 km by using several PPIs at low elevation angles.

This data can remove sea clutters and also ground clutters.



# Elevation angle composite table

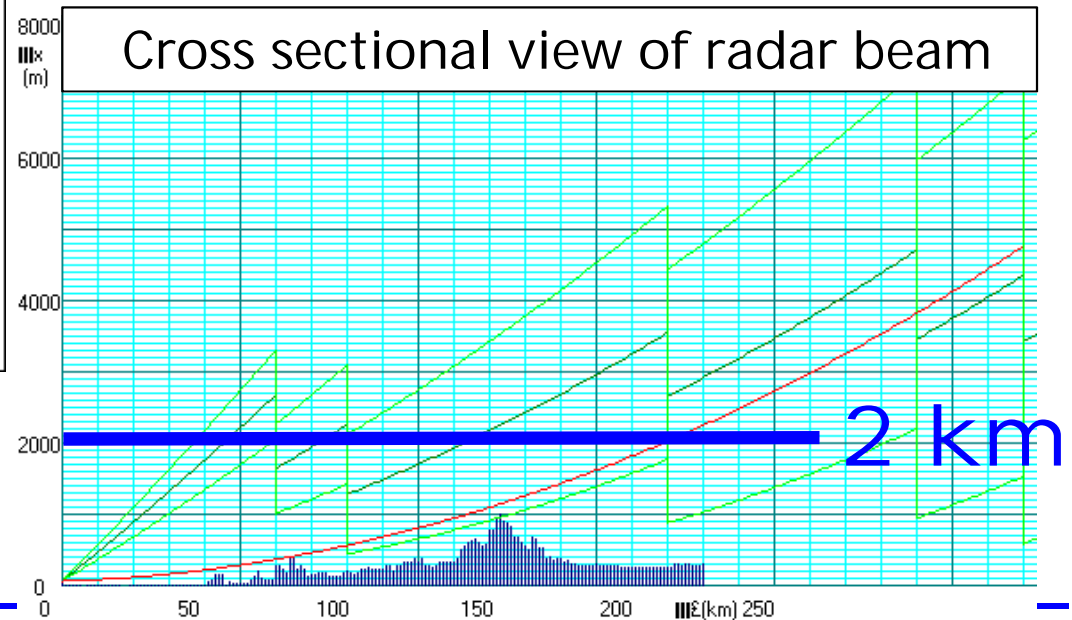
Elevation angle composite table is parameters for making Quality Controlled CAPPI data



- Selecting an optimal elevation angle located near 2 km altitude in each place
- Reducing effect of ground clutter

<Elevation>

- (1) 0.0deg (2) 0.3deg (3) 0.7deg  
(4) 1.1deg (5) 1.7deg (6) 2.5deg



# Targets of Hands-on training

- To experience benefits of JMA's Pseudo CAPPI process
  - By adjusting elevation angle composite table
- To realize importance of statistical data
  - By verifying statistical data

This practice will give answers to questions below;

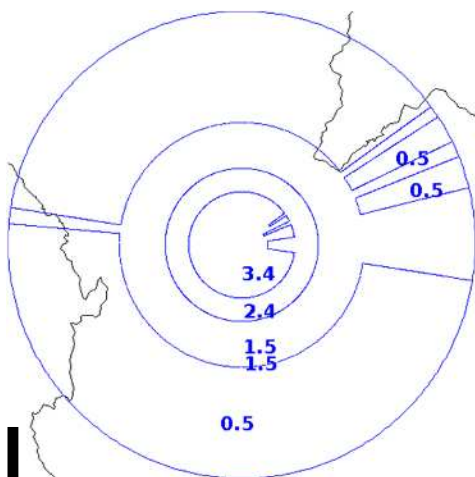
- How PCAPPI process can improve data quality?
- How we find out a better way of QC with statistical data?

Technical cooperation with TMD (Tokyo, Nov 2014)

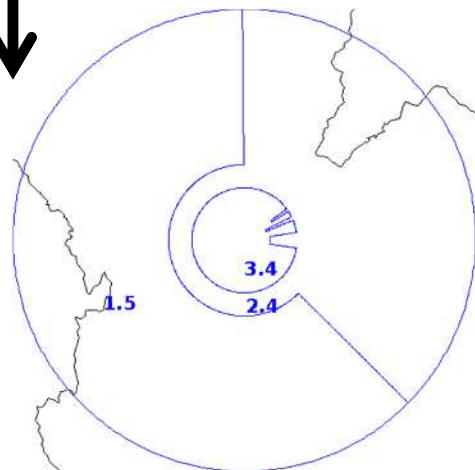
# Adjustment of Composite Tables

(2014 Aug, Phisanulok radar site)

Composite table



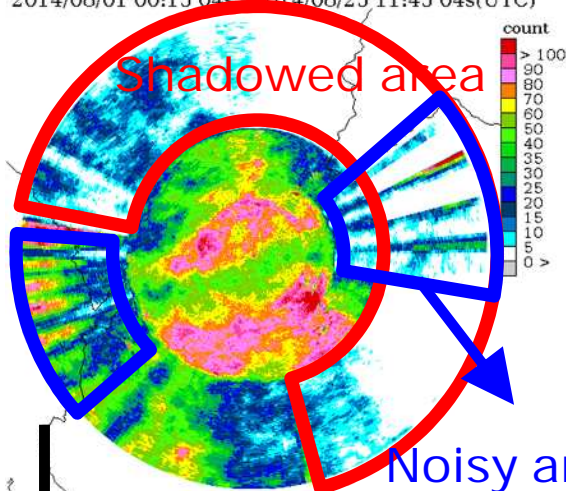
Adjusting Composite table



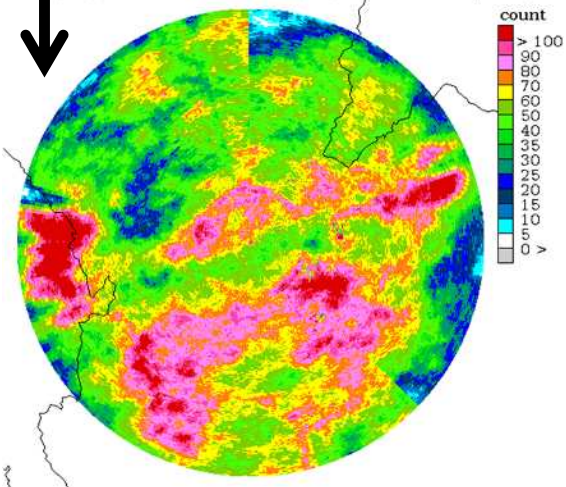
Statistical PCAPPI data

Appearance Count

phisanolok data=1429: appearance count  
2014/08/01 00:15 04s - 2014/08/25 11:45 04s(UTC)

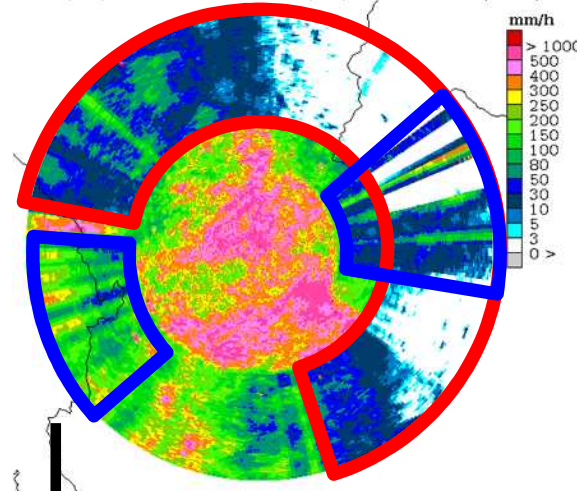


phisanolok data=1429: appearance count  
2014/08/01 00:15 04s - 2014/08/25 11:45 04s(UTC)

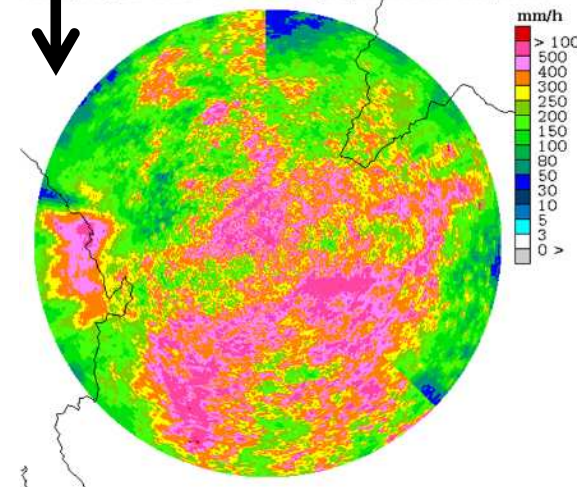


Summarized data

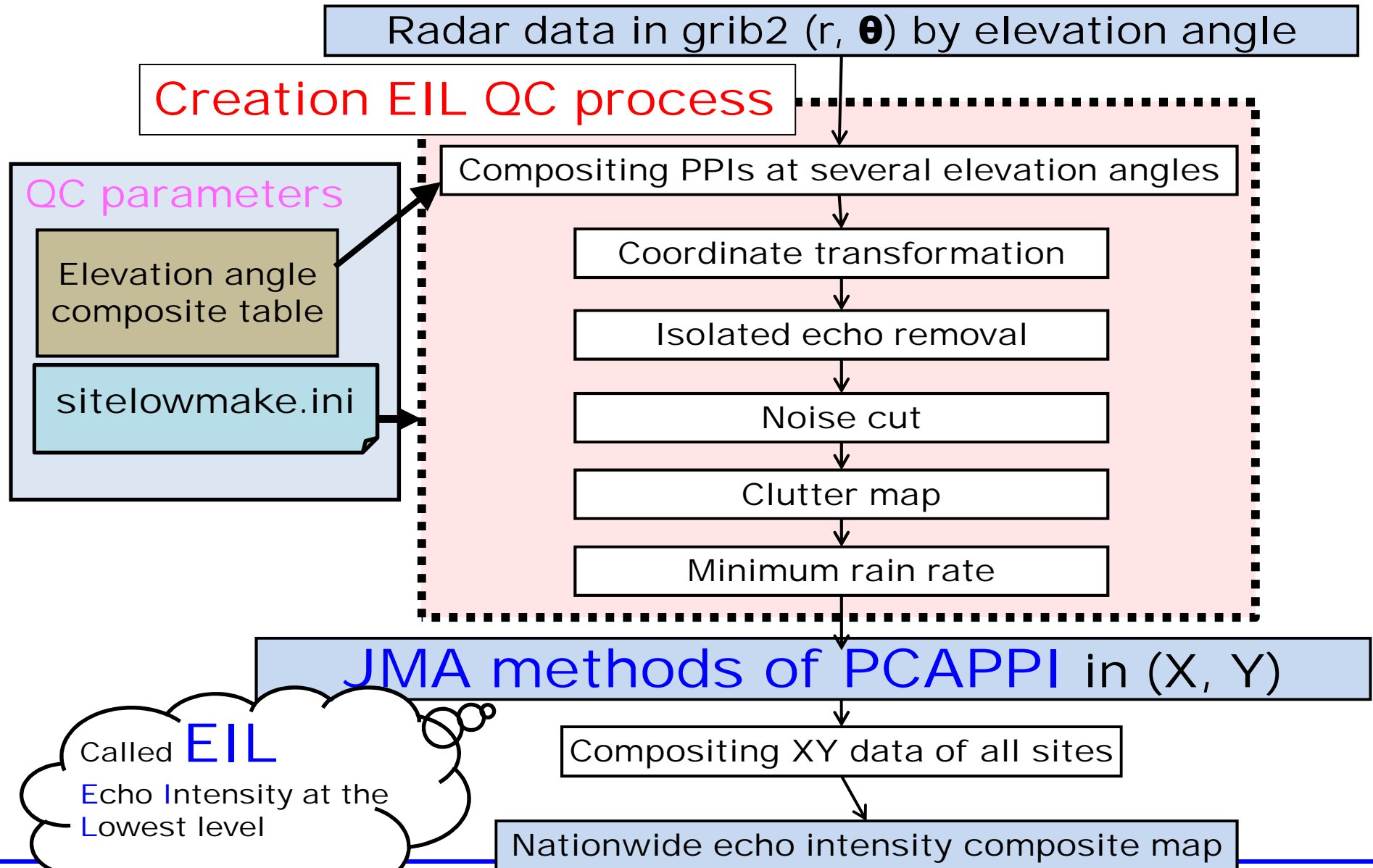
phisanolok data=1429: summation  
2014/08/01 00:15 04s - 2014/08/25 11:45 04s(UTC)



phisanolok data=1429: summation  
2014/08/01 00:15 04s - 2014/08/25 11:45 04s(UTC)




# Data processing flow for PCAPPI




# “radar-library.jar”

- Executable binary
- Written in java and Compressed in “jar” (Java ARchive)
- Contains decoding, encoding, data processing, coordinate transforming, and data viewing programs.
- Runnable in command for every purpose
- We use windows batch files today for simplicity.

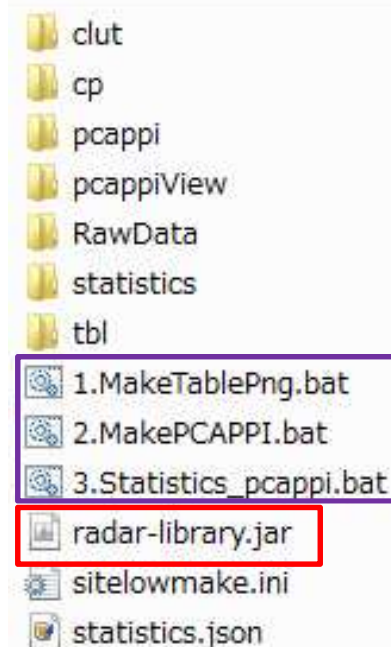
- More information about this program is in...

 \_references

 How to use Practice Programs.pptx



radar-library.jar



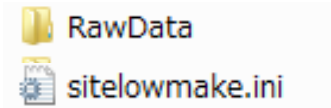
# Radar data and parameter file



- Butterworth site RAW data (IRIS format)
- Data period : 1 day (17 Dec, 2014)
- Elevation angles for PPI : 0.0, 0.7, 1.5, 2.5

```
[Butterworth]
elangles=0.0,0.7,1.5,2.5
use_angle=1,1,1,1
code=BW
ename=Butterworth
offx=0
offy=0
n0=54.3
noise_cut=6
rain_cut=3
iso_window=5
iso_count=5
smooth_r=41
smooth_t=3
...
```

sitelowmake.ini



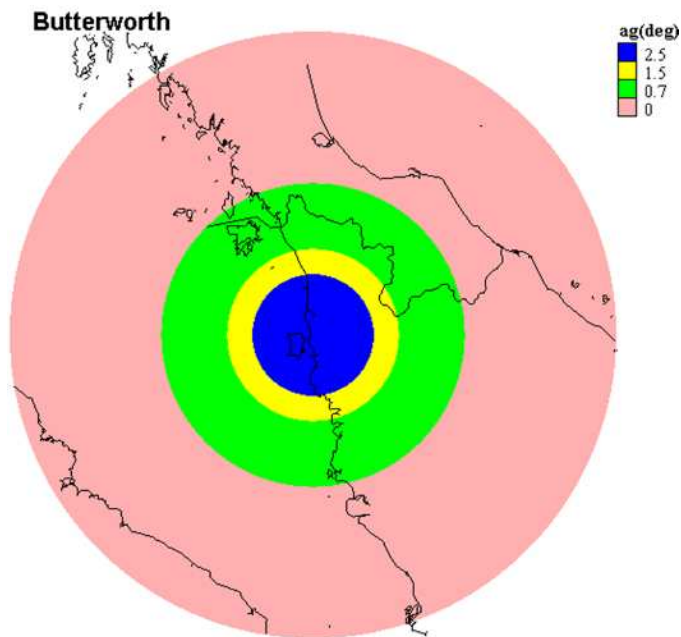
# Composite table(CSV file)

- Composite table shows angles used in each area.

agButterworth.csv(simple CAPPI)

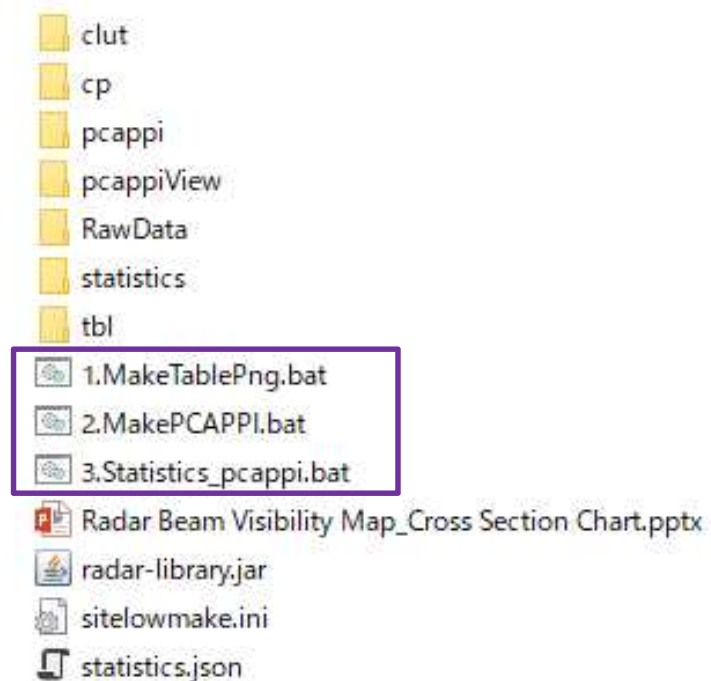
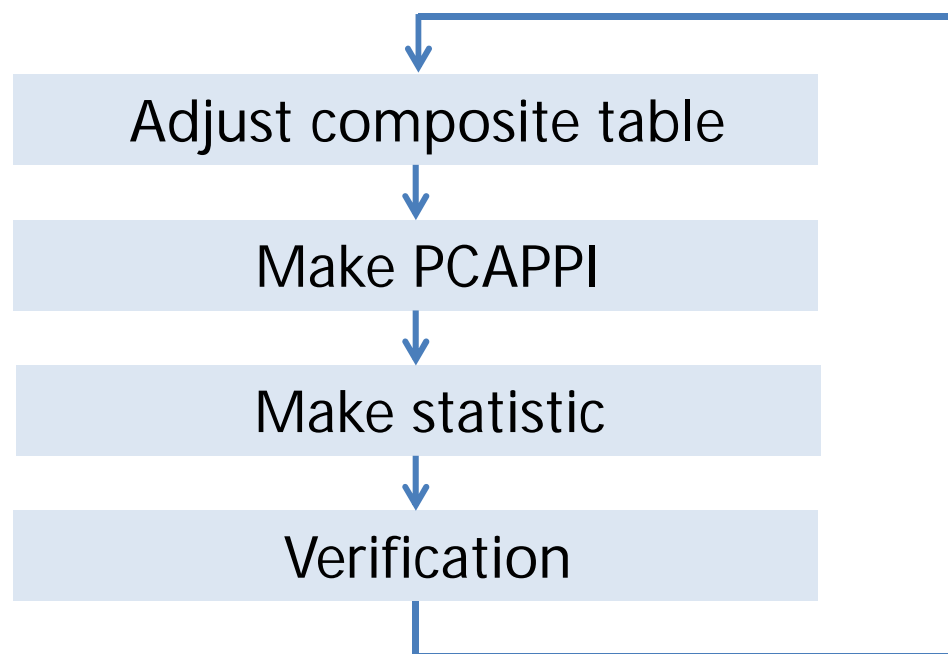
360, 0, 2.5, 60, 1.5, 85, 0.7, 150, 0, 300

Azimuth(deg), Distance(km), Angle (deg)



- simple CSV(Comma-Separated Values)
- this file means...
  - for 0-360 azimuth (for all around),
  - use 2.5 angle PPI data for 0-60 km,
  - use 1.5 angle PPI data for 60-85 km,
  - use 0.7 angle PPI data for 85-150km,
  - use 0.0 angle PPI data for 150-300km

# Preparation: Operation check



- At first, We do operation check of these batch files.
- Please call JMA staff if you're in trouble.



# 1. MakeTablepng.bat

```
java -cp radar-library.jar PCAPPITableToPNG ./tbl/agButterworth.csv
```

MakeTablepng.bat

classname

tbl

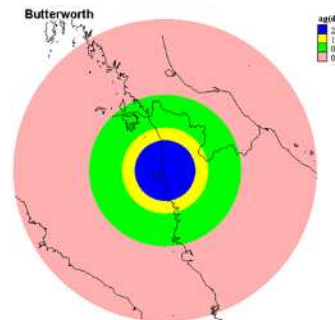
agButterworth.csv

agButterworth.csv.png

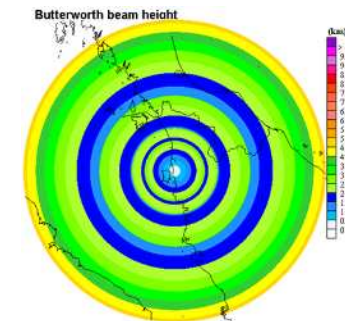
agButterworth.csvBH.png

agButterworth.csv

PCAPPITableToPNG

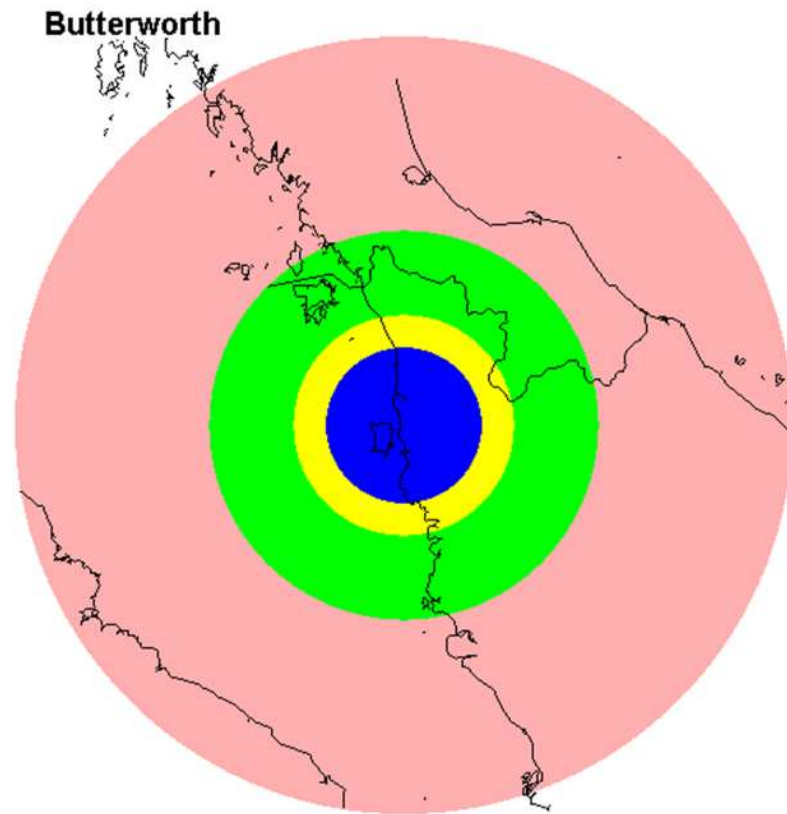


agButterworth.csv.png

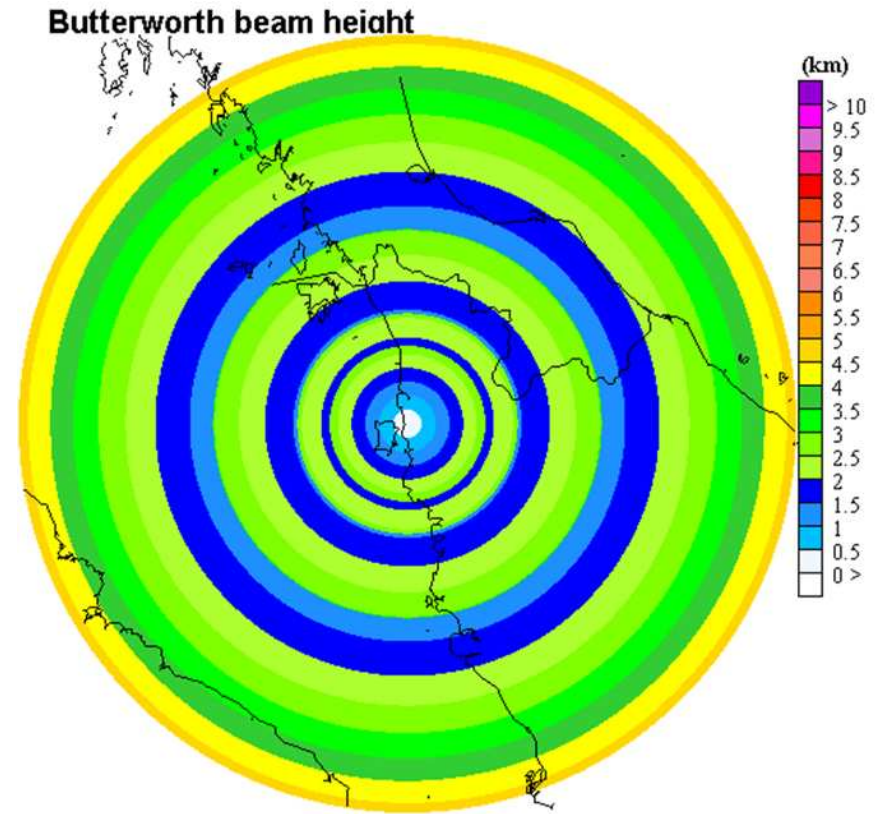


agButterworth.csvBH.png

# Composite table: Simple CAPPI(2km)



Angle

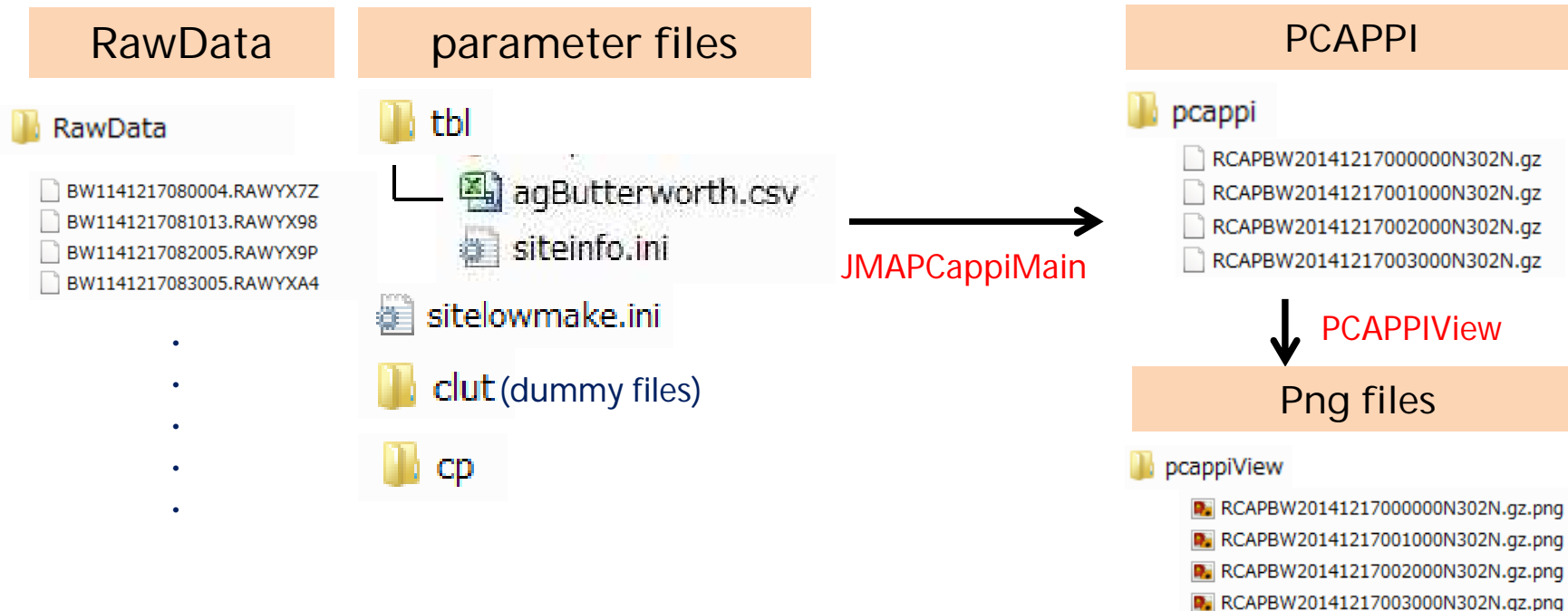


Beam Height

# 2. MakePCAPPI.bat

```
for %%i in (./RawData/BW*) do (  
  java -cp radar-library.jar JMAPCappiMain -envfile=./sitelowmake.ini -tblDir=./tbl  
  -destDir=./pcappi/. -clutDir=./clut ./RawData/%%i -gz  
)  
for %%i in (./pcappi/*) do (  
  java -cp radar-library.jar PCAPPIView ./pcappi/%%i -dest=./pcappiView/  
  -colorPallet=./cp/dbz_color.txt  
)
```










MakePCAPPI.bat



# PCAPPI data

 pcappi

Filename

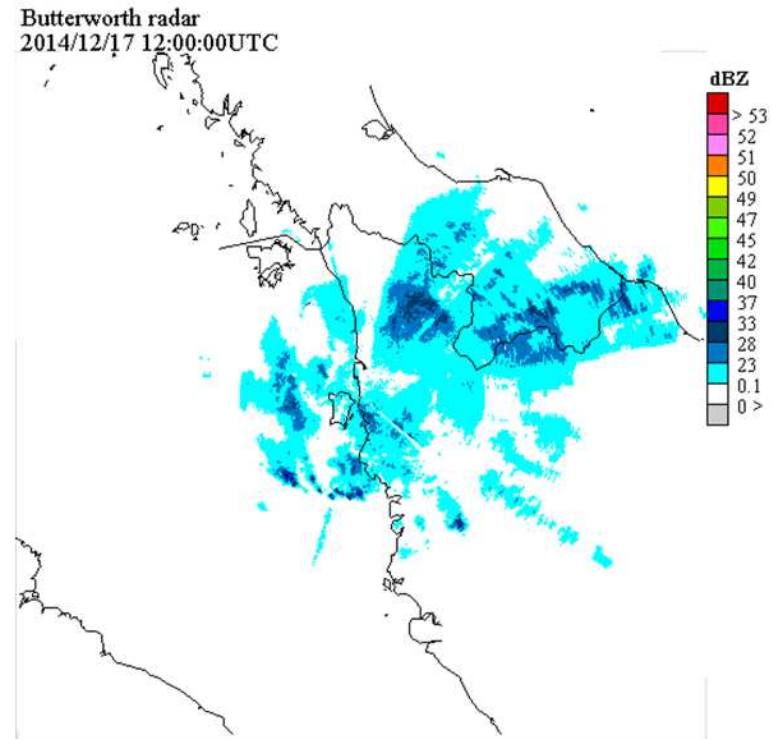
-  RCAPBW20141217000000N302N.gz
-  RCAPBW20141217001000N302N.gz
-  RCAPBW20141217002000N302N.gz
-  RCAPBW20141217003000N302N.gz
-  RCAPBW20141217004000N302N.gz
-  RCAPBW20141217005000N302N.gz
-  RCAPBW20141217010000N302N.gz
-  RCAPBW20141217011000N302N.gz
-  RCAPBW20141217012000N302N.gz

- Details of the format is in ...

 \_references

 JMAPCAPPIFormat.pptx

 pcappiView



# 3.Statistics\_pcappi.bat

```
java -cp radar-library.jar StatisticsMain -ini=statistics.json -name=pcappi -start=201412170000  
-end=201412180000  
java -cp radar-library.jar StatisticsView ./statistics/pcappi
```

Statistics\_pcappi.bat

## PCAPPI

pcappi

- RCAPBW20141217000000N302N.gz
- RCAPBW20141217001000N302N.gz
- RCAPBW20141217002000N302N.gz
- RCAPBW20141217003000N302N.gz

StatisticsMain

## Statistics(csv)

statistics

- Butterworth\_pcappi\_201412170000\_201412172350\_Butterworth\_APPEARANCE.csv
- Butterworth\_pcappi\_201412170000\_201412172350\_Butterworth\_APPEARANCE\_header.csv
- Butterworth\_pcappi\_201412170000\_201412172350\_Butterworth\_AVERAGE.csv
- Butterworth\_pcappi\_201412170000\_201412172350\_Butterworth\_AVERAGE\_header.csv

StatisticsView

## parameter file

statistics.json

```
"filename": "./pcappi/RCAP.*'yyyyMMddHHmmss'N302N.gz",  
"sek": "10",  
"calculation": "DBZtoRAIN",  
"outdir": "./statistics/pcappi/"}"
```

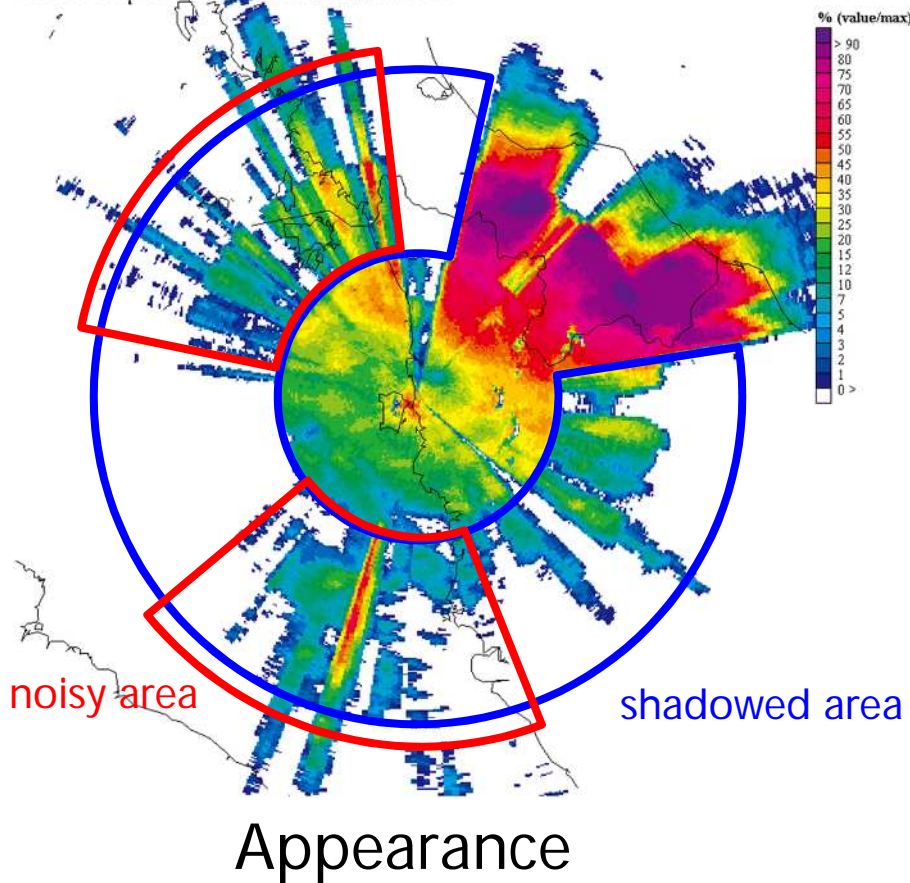
## Png files

statistics

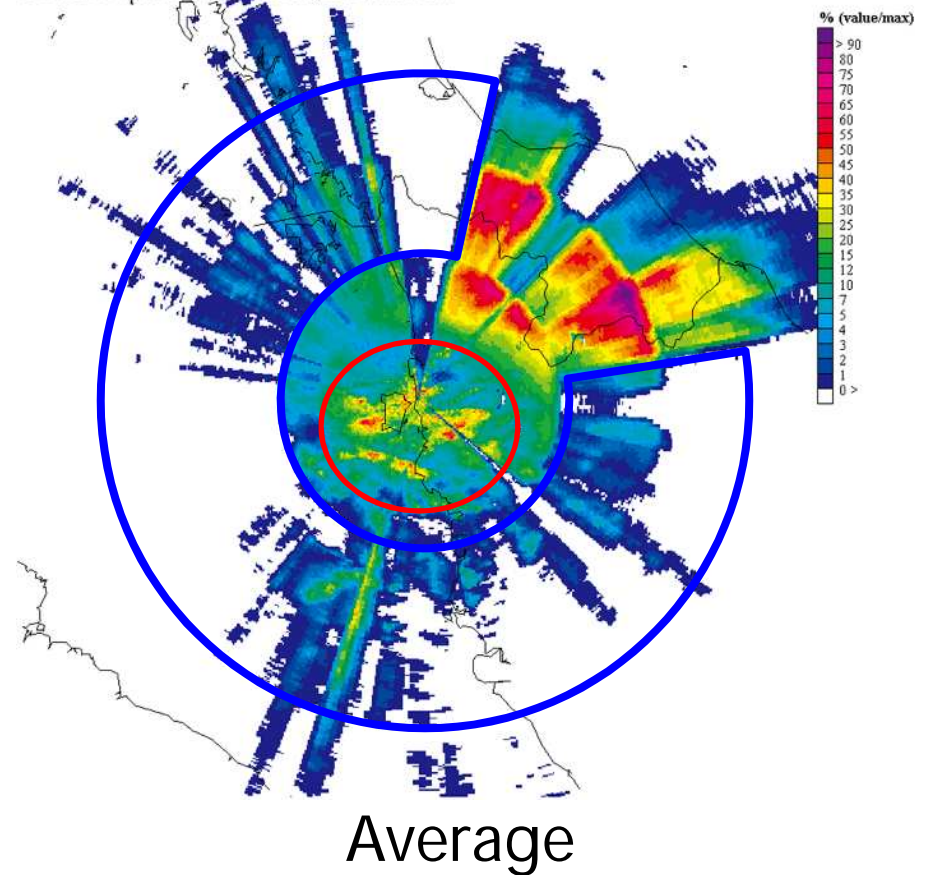
- Butterworth\_pcappi\_201412170000\_201412172350\_Butterworth\_APPEARANCE\_header.png
- Butterworth\_pcappi\_201412170000\_201412172350\_Butterworth\_AVERAGE\_header.png

# Statistics: Simple CAPPI(2km)

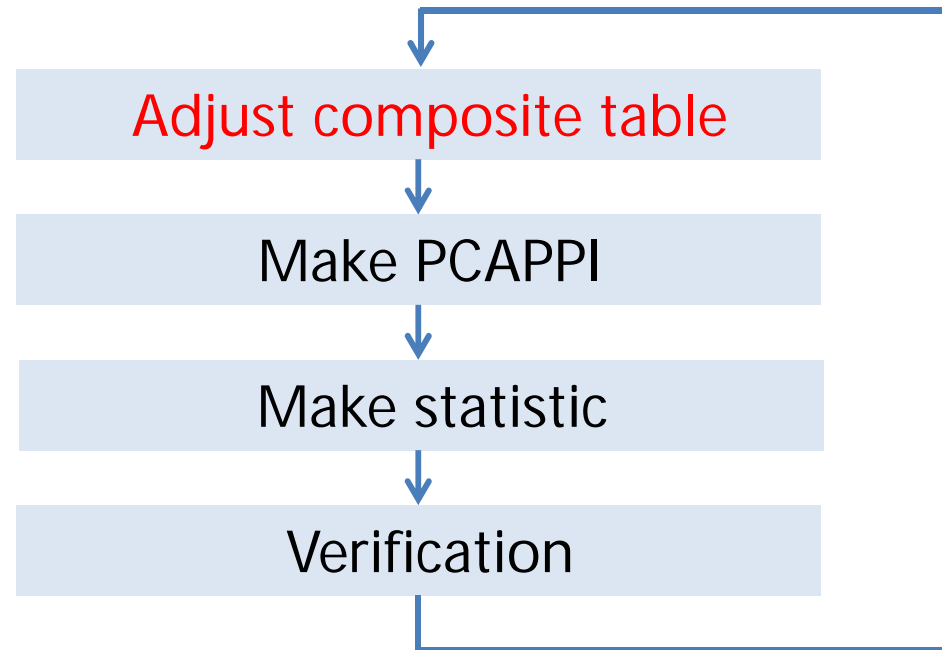
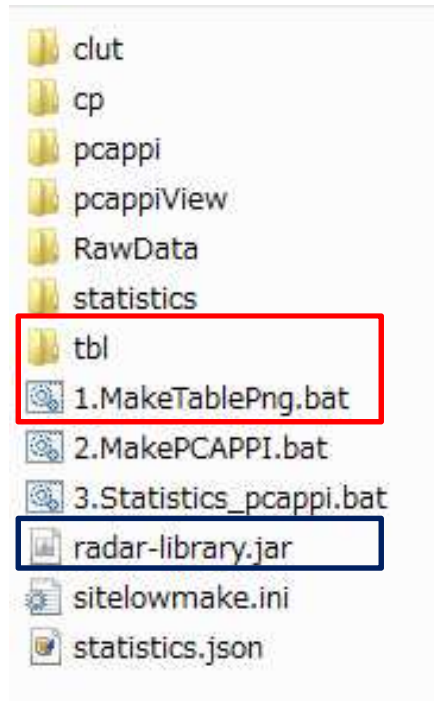
pcappi Butterworth APPEARANCE scale 100 =139.0  
2014/12/17 00:00-2014/12/17 23:50(UTC) data : 144



pcappi Butterworth AVERAGE scale 100 =1.1348299  
2014/12/17 00:00-2014/12/17 23:50(UTC) data : 144



# Flow of the practice



- Let`s adjust composite table to avoid obstacle.
- Radar Beam Visibility map and Cross Section Chart are useful.

# Radar Beam Visibility Map and Cross Section Chart

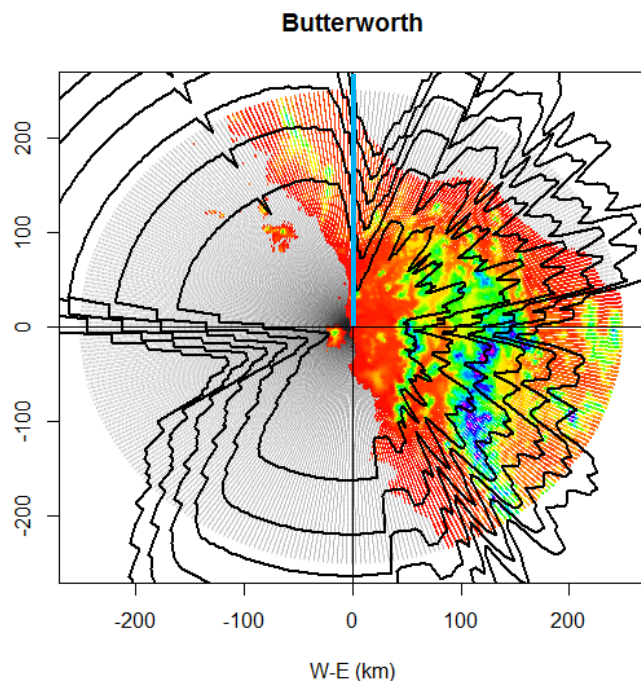
- In this case (azimuth = 0.0 deg, 0.0deg means due north), we should not use 0.0 degree angle data because the beam is blocked.

## Map

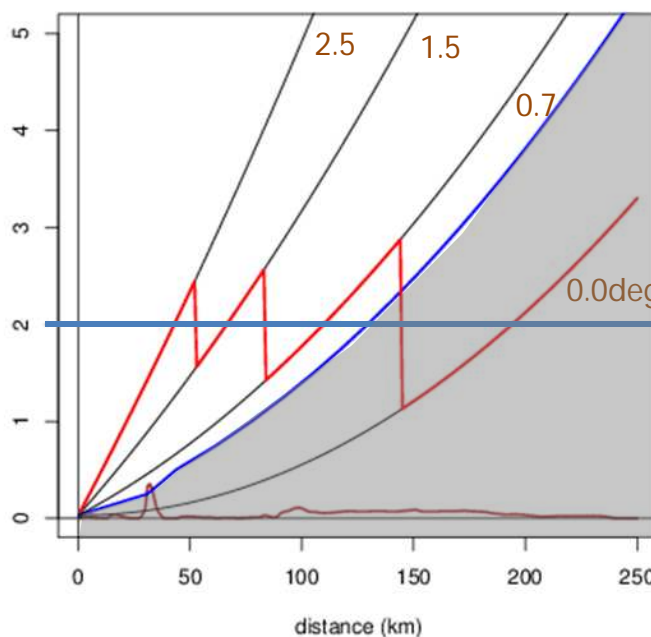
**Color:**  
altitude  
warm is low  
cold is high

**Gray:**  
sea

**Black:**  
ranges of radar beam visibility at heights of 1 km, 2km ... from inside



Butterworth, azimuth = 0.0 (deg)



## Cross section

**Black:**  
radar beams for each elevation angles

**Red:**  
beams for cappi(2km), land surface ignored

**Blue:**  
limitation of radar beam visibility

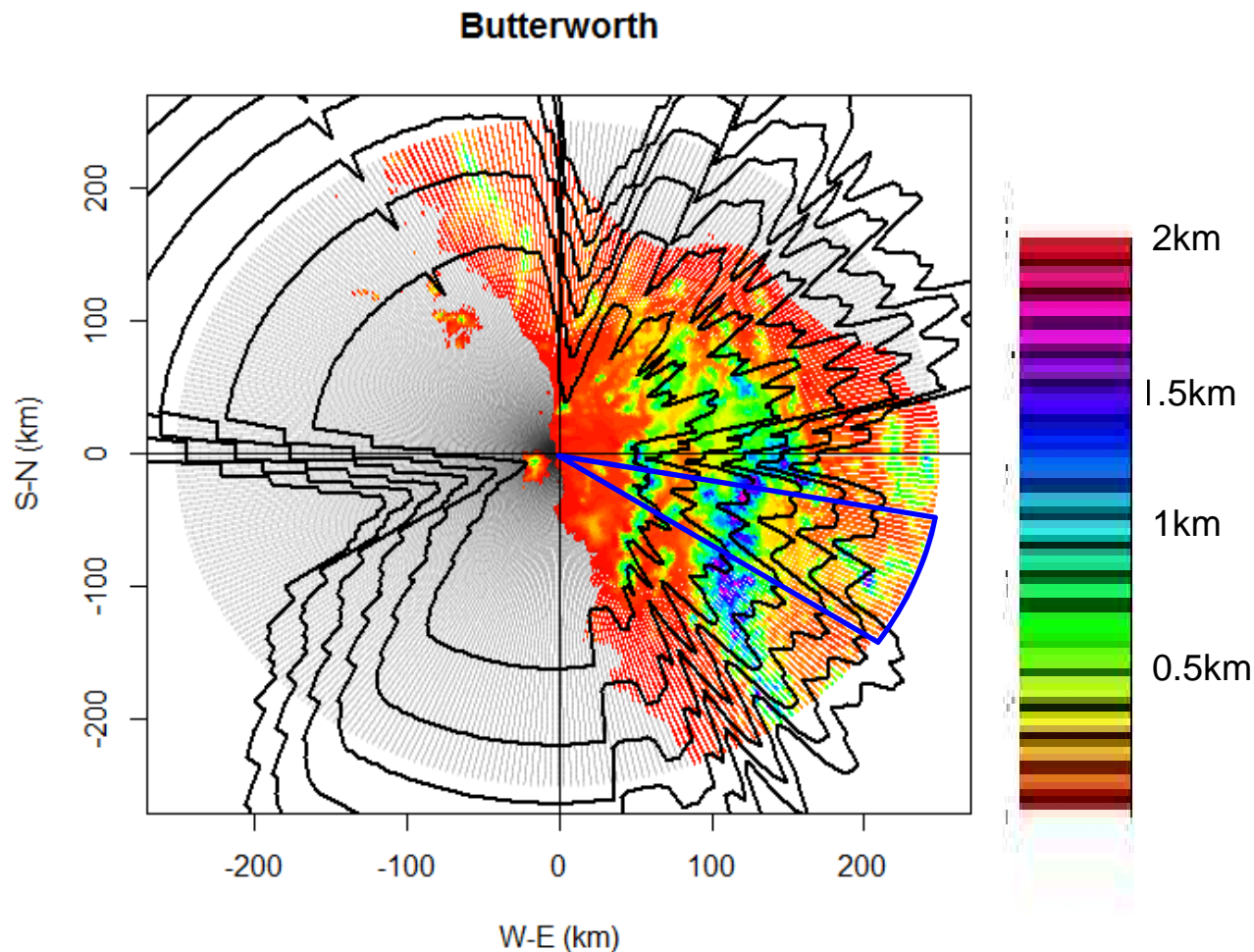
**Brown:**  
land surface



# How to avoid obstacles

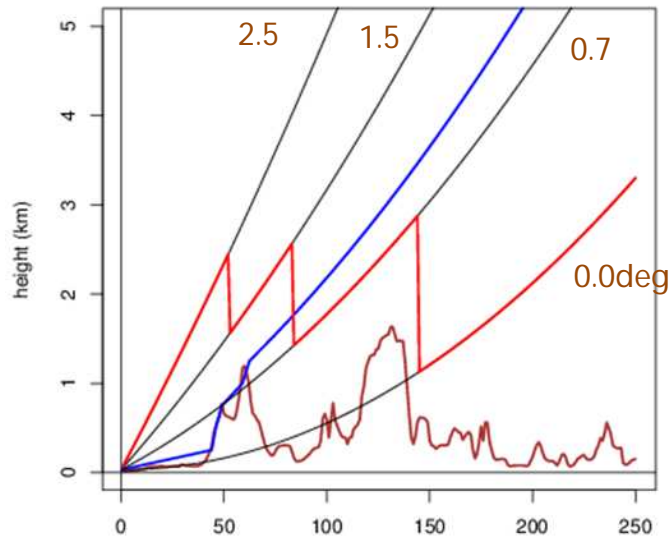
- Check the beam blockage with cross section chart
  - Beams below the limitation line(**blue line**) are blocked by land surface.
  - We **should not use** the angle which beam is blocked.
- Edit composite table (agButterworth.csv)
  - Adopt the **higher** angle instead of the angle which beam is blocked.
- Edited composite table will give us more better PCAPPI data.
- Let's try with me.

# Check the beam blockage

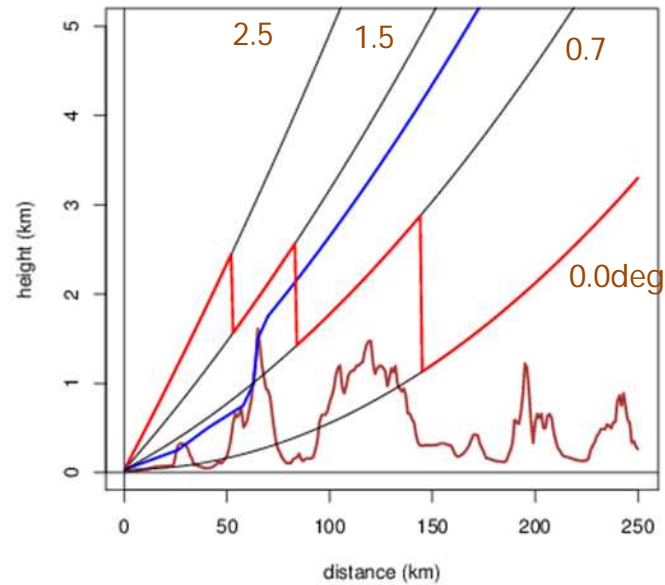


- We focus on south eastern part.

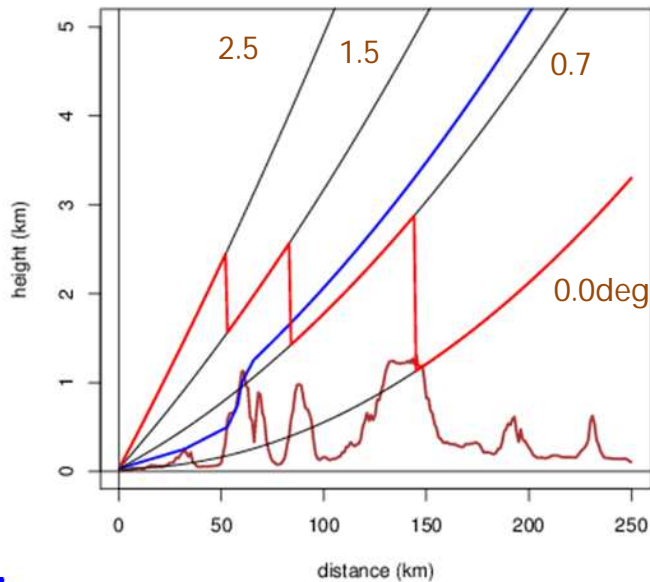
azimuth = 100 deg



azimuth = 110 deg



azimuth = 120 deg



- In 100 – 120 degree azimuth, We **should not** use ? angle PPI data.

# Exercise 1



100	0	2.5	60	1.5	85	0.7	150	0	300
120									
360	0	2.5	60	1.5	85	0.7	150	0	300

Azimuth(deg), Distance(km), Angle (deg)

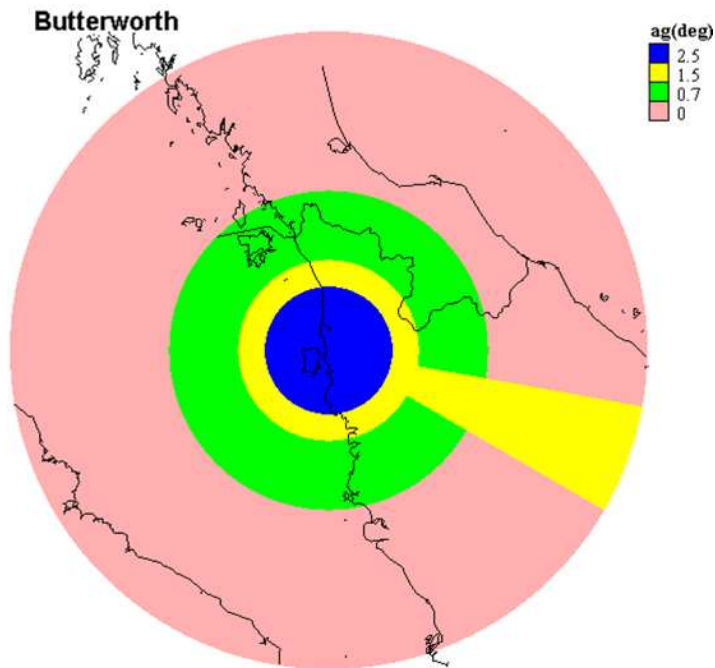
- Fill in the blanks and complete composite table.
- If you finished, then copy this file to upper folder, and overwrite the old table.

# Edited composite table

agButterworth.csv(modified)

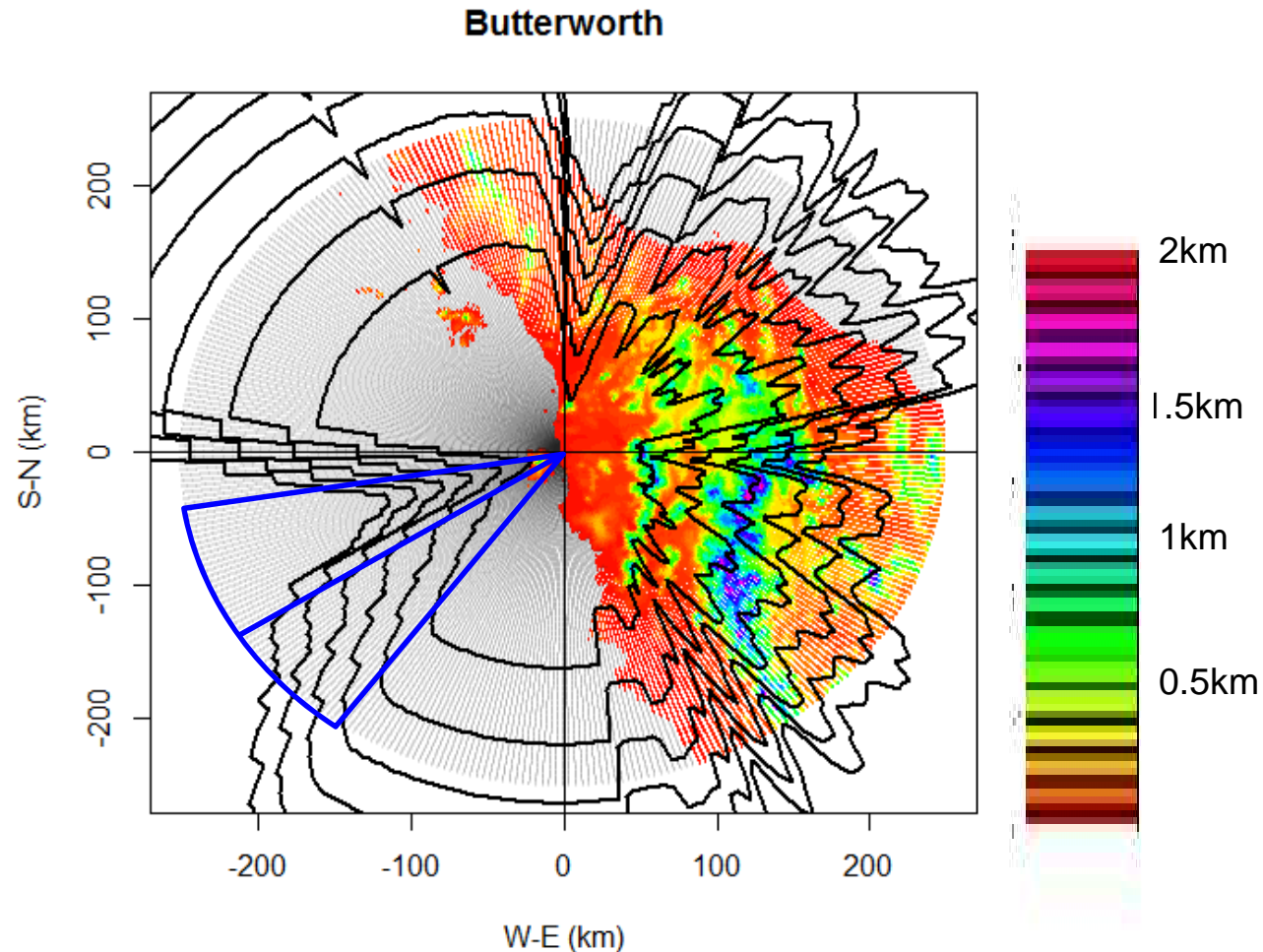
```
100, 0, 2.5, 60, 1.5, 85, 0.7, 150, 0, 300  
120, 0, 2.5, 60, 1.5, 300  
360, 0, 2.5, 60, 1.5, 85, 0.7, 150, 0, 300
```

Azimuth(deg), Distance(km), Angle (deg)



- Edit agButterworth.csv and execute [MakeTablepng.bat](#), then you can check your table by png file .
- In this case, I added lines to stop using 0.7 and 0.0 angle data for 100-120 azimuth.

# Check the beam blockage



- Next, We focus on south western part.

# Exercise 2

tbl

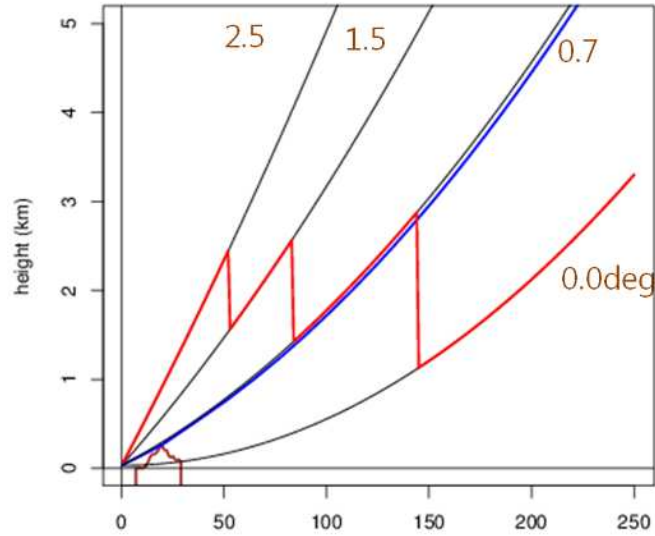
Exercise\_2

agButterworth.csv

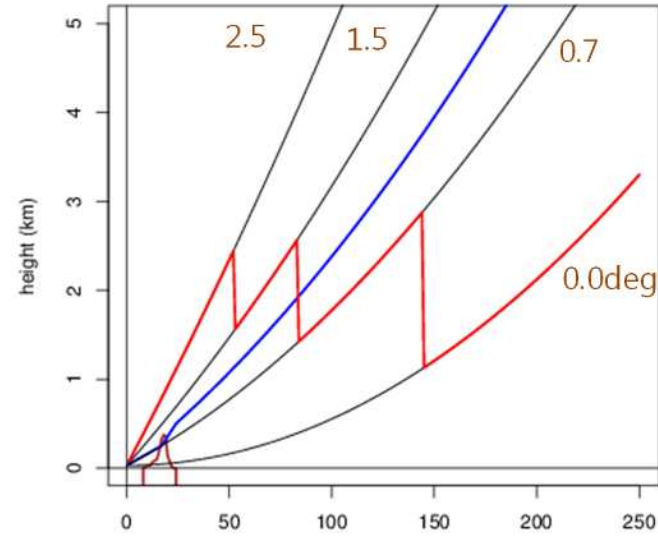
20	0	2.5	60	1.5	300					
80	0	2.5	60	1.5	85	0.7	300			
100	0	2.5	300							
120	0	2.5	60	1.5	300					
170	0	2.5	60	1.5	85	0.7	300			
210	0	2.5	60	1.5	85	0.7	150	0	300	
220	0	2.5	60	1.5	85	0.7	300			
240										
260										
270	0	2.5	60	1.5	85	0.7	300			
350	0	2.5	60	1.5	85	0.7	150	0	300	
360	0	2.5	60	1.5	85	0.7	300			



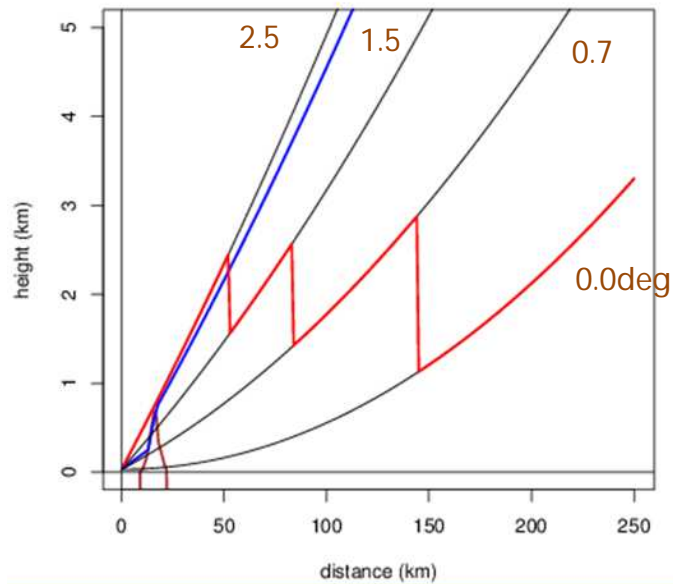
azimuth = 230 deg



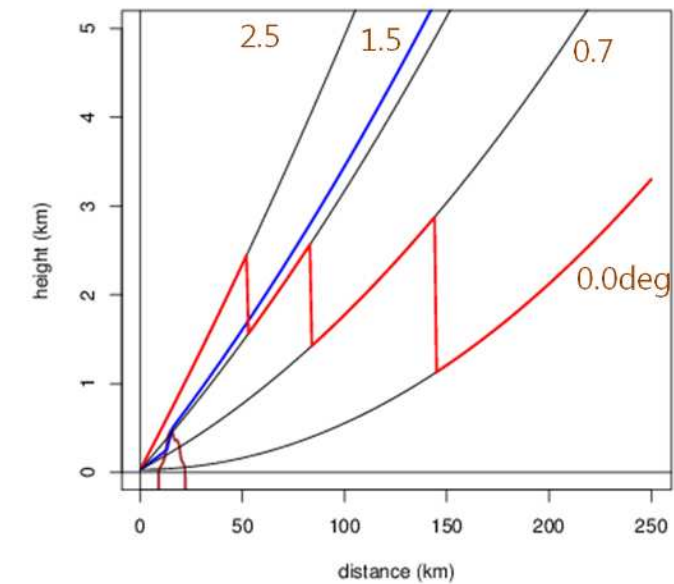
azimuth = 240 deg



azimuth = 250 deg

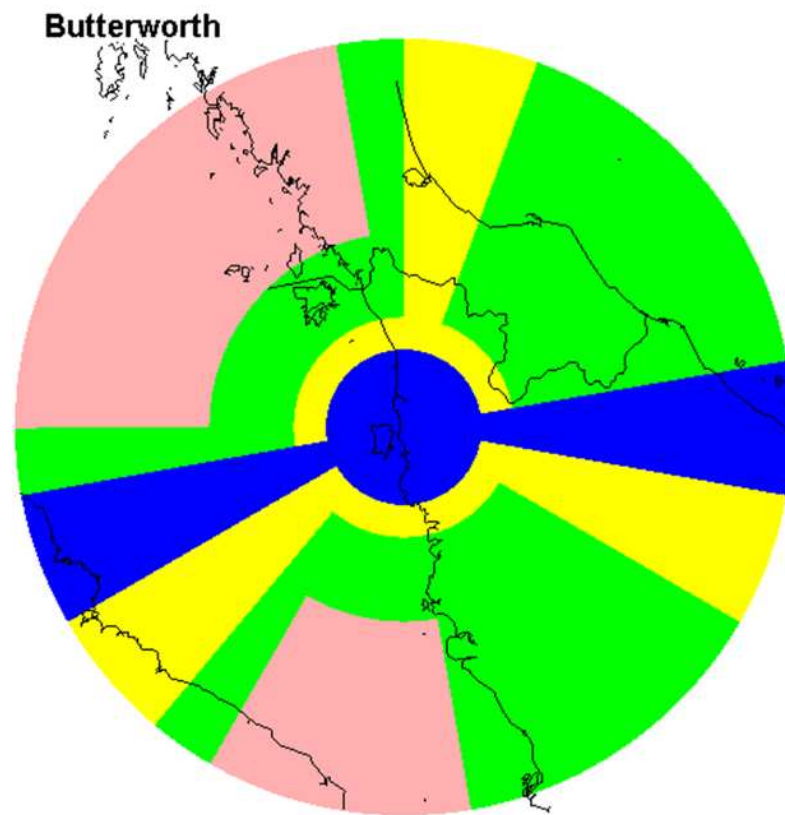


azimuth = 260 deg

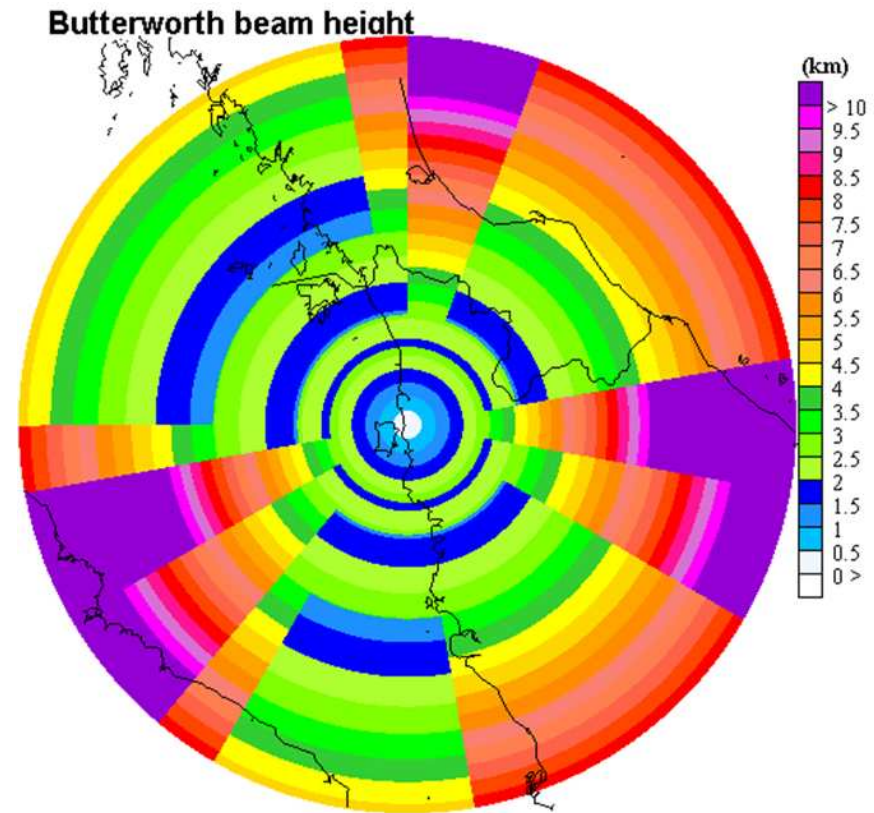
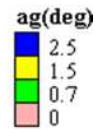




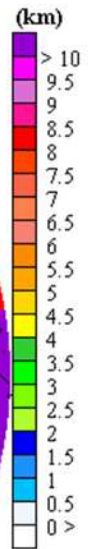
# Composite table(considered obstacle)



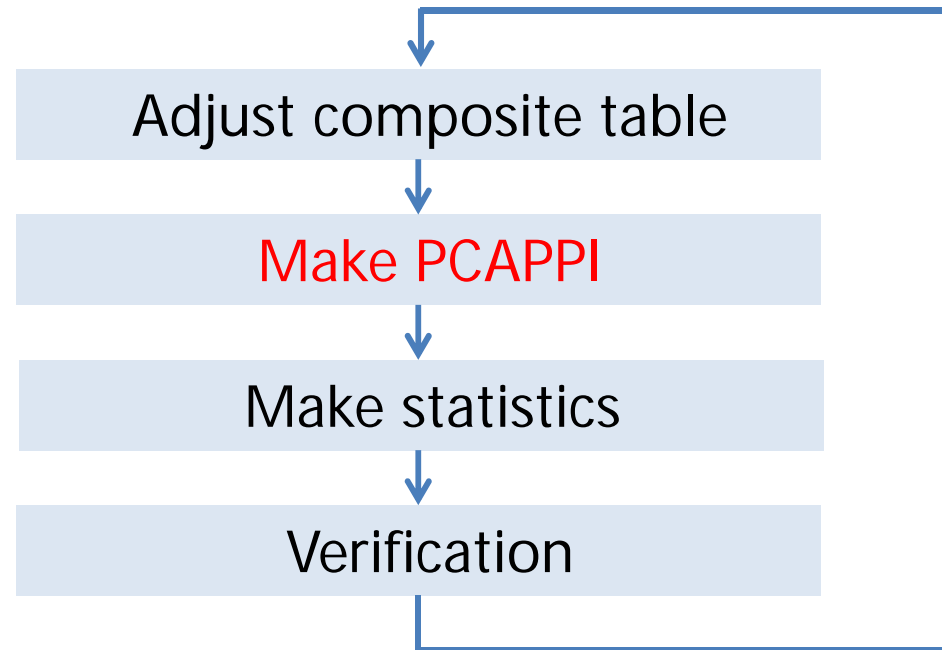
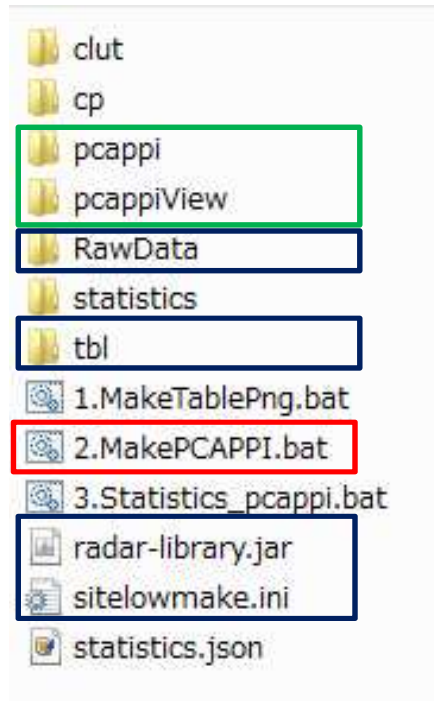
Angle



Beam Height

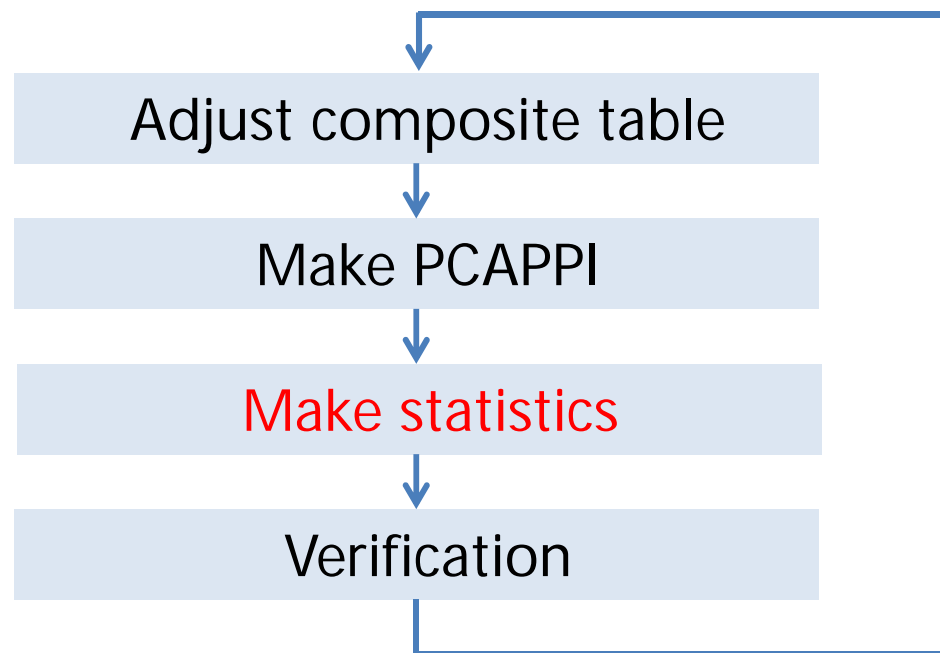
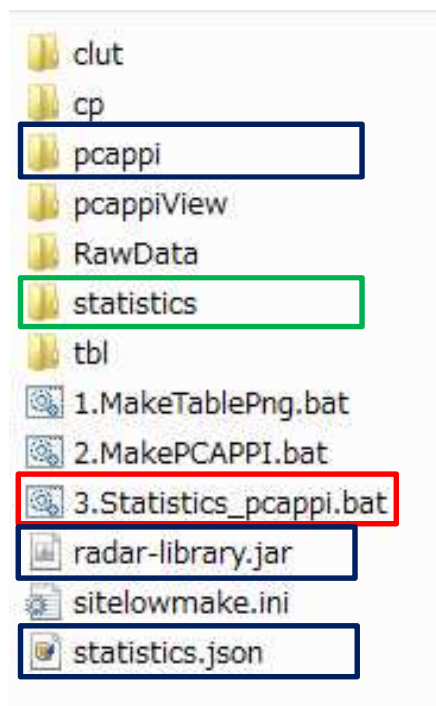


# Flow of the practice



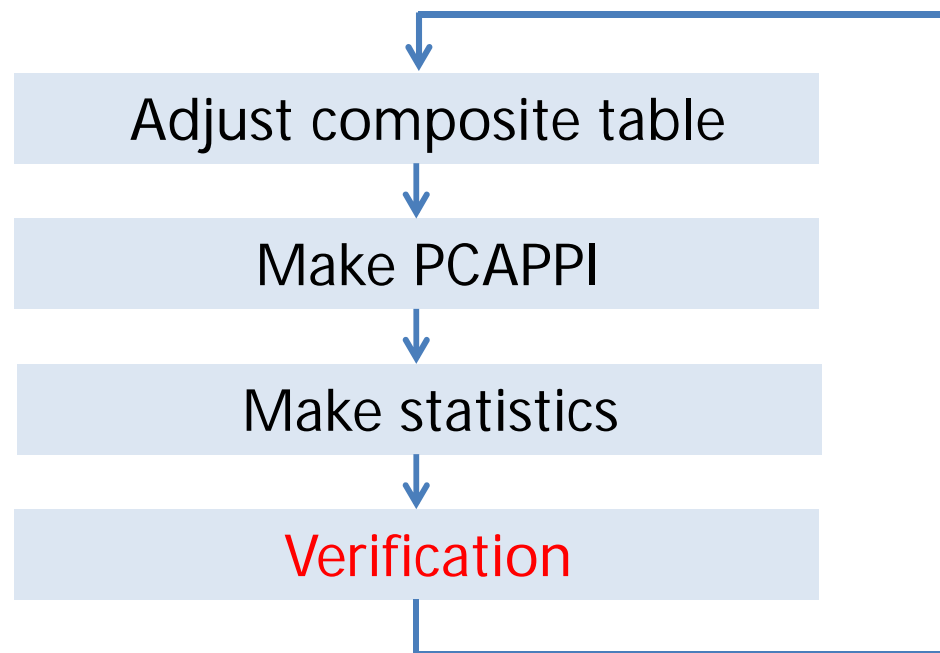
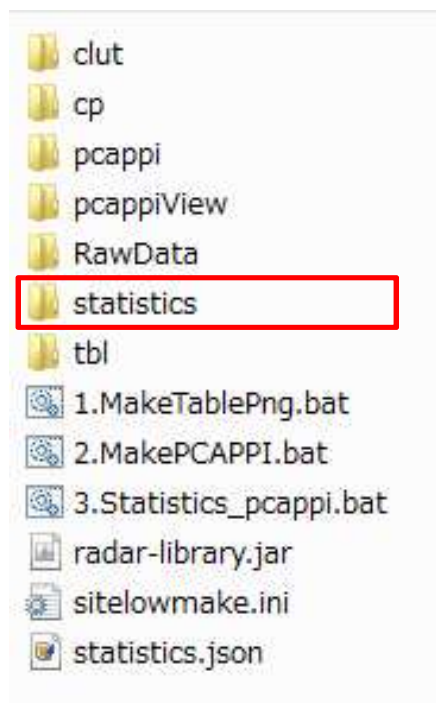
- Let's make PCAPPI by new composite table.

# Flow of the practice



- Next, To make statistical data, Execute Statistics\_pcappi again.

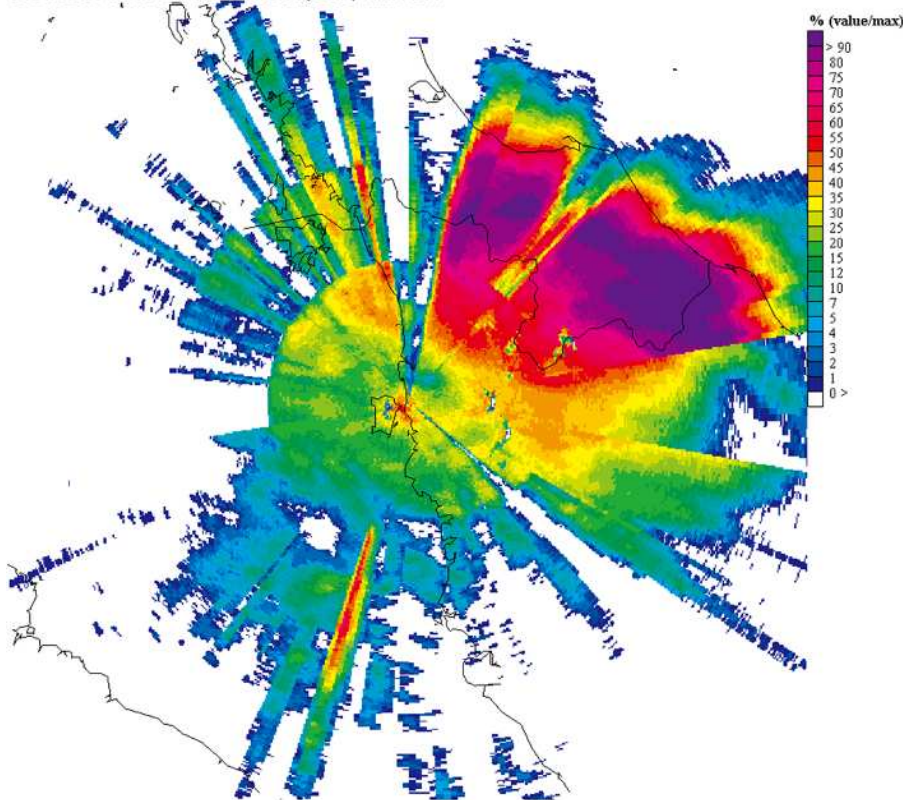
# Flow of the practice



- Verify the result of statistics from remade PCAPPI.
- It is important to verify the adjusted data.
- Because , there might be a case in which the adjusted affect might have low quality data.

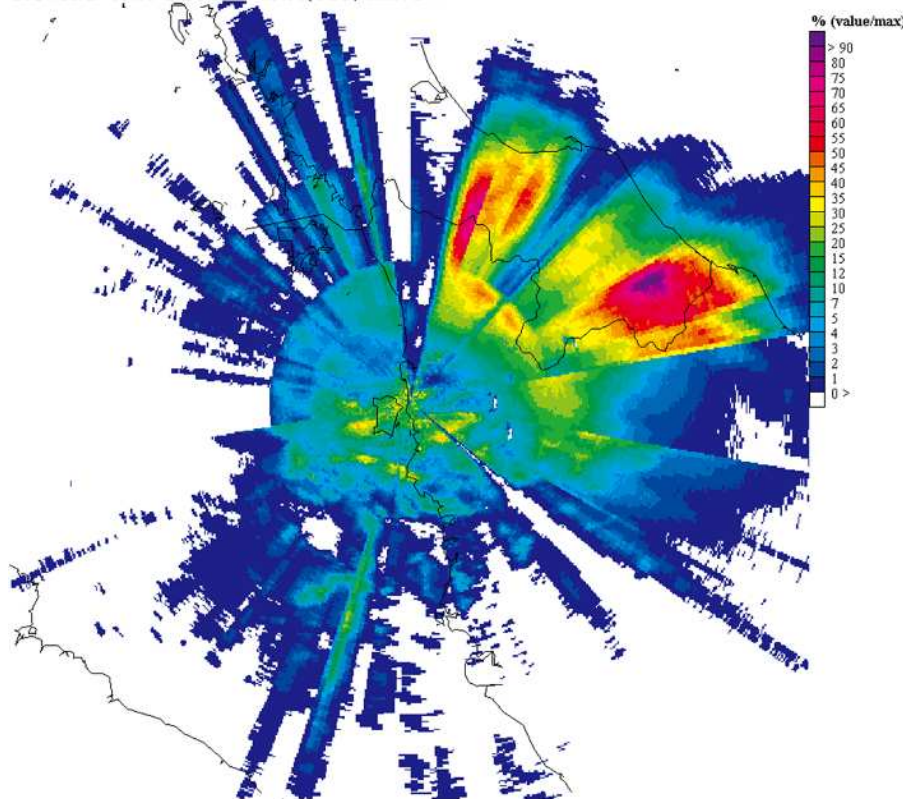
# Statistics: PCAPPI (considered obstacle)

pcappi Butterworth APPEARANCE scale 100 =140.0  
2014/12/17 00:00-2014/12/17 23:50(UTC) data : 144



Appearance

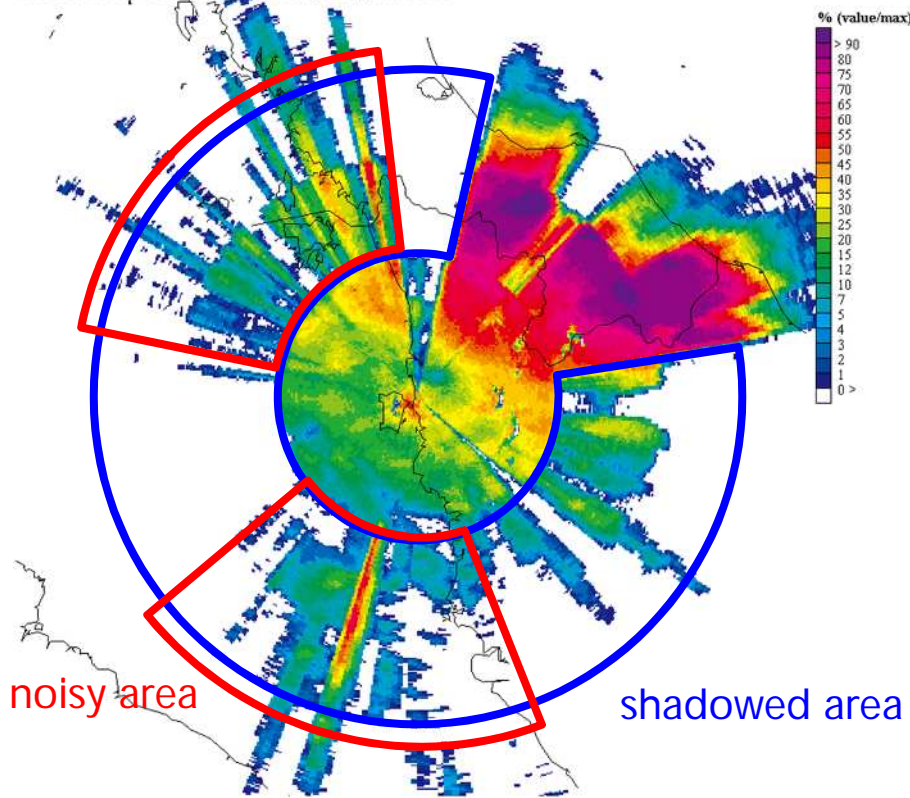
pcappi Butterworth AVERAGE scale 100 =1.7425351  
2014/12/17 00:00-2014/12/17 23:50(UTC) data : 144



Average

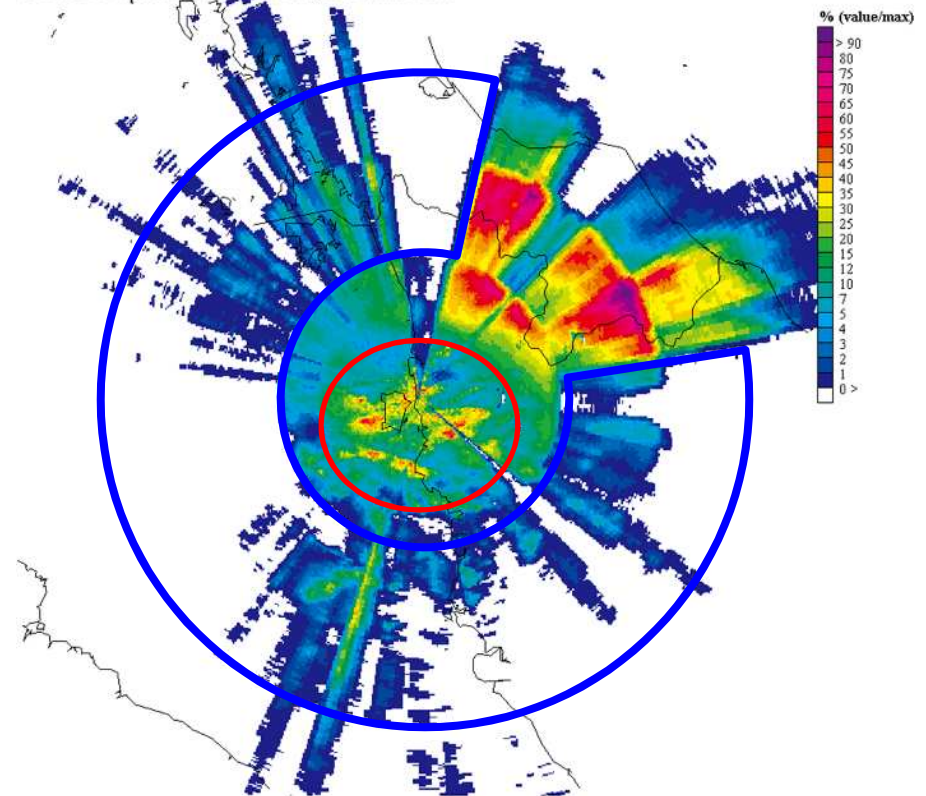
# Statistics: Simple CAPPI (2km)

pcappi Butterworth APPEARANCE scale 100 =139.0  
2014/12/17 00:00-2014/12/17 23:50(UTC) data : 144



Appearance

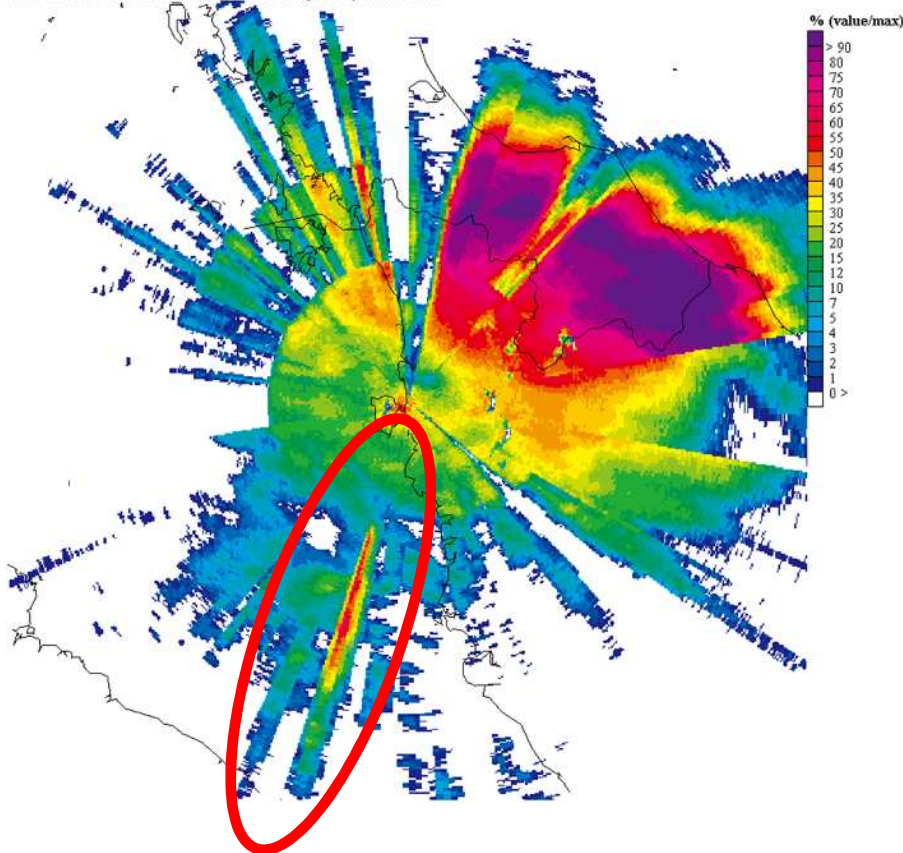
pcappi Butterworth AVERAGE scale 100 =1.1348299  
2014/12/17 00:00-2014/12/17 23:50(UTC) data : 144



Average

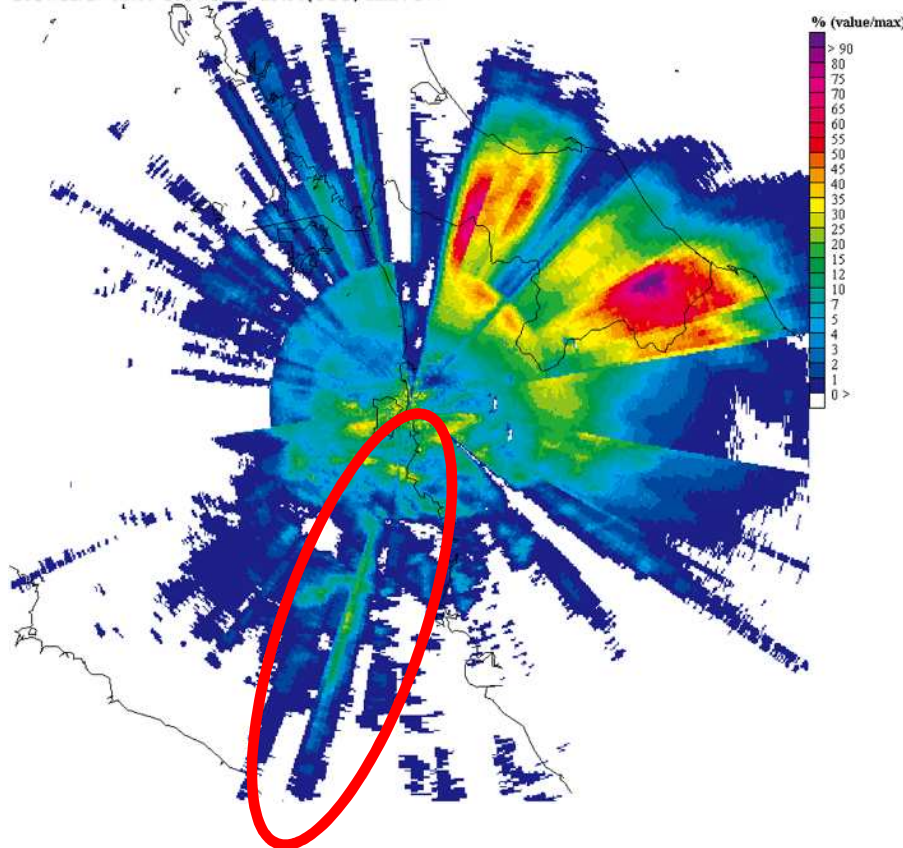
# Statistics: PCAPPI (considered obstacle)

pcappi Butterworth APPEARANCE scale 100 =140.0  
2014/12/17 00:00-2014/12/17 23:50(UTC) data : 144



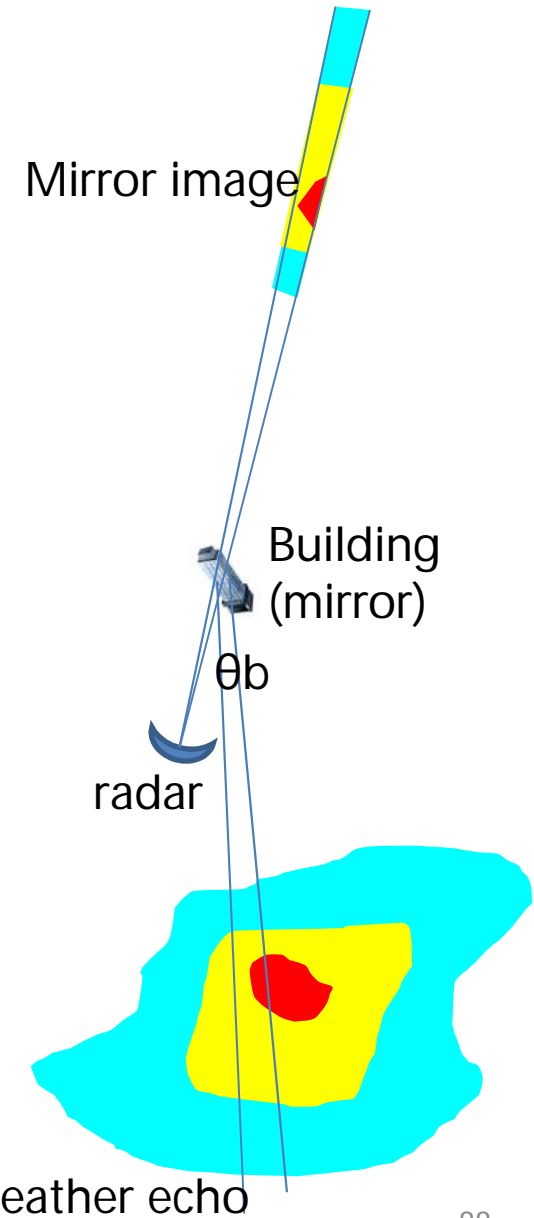
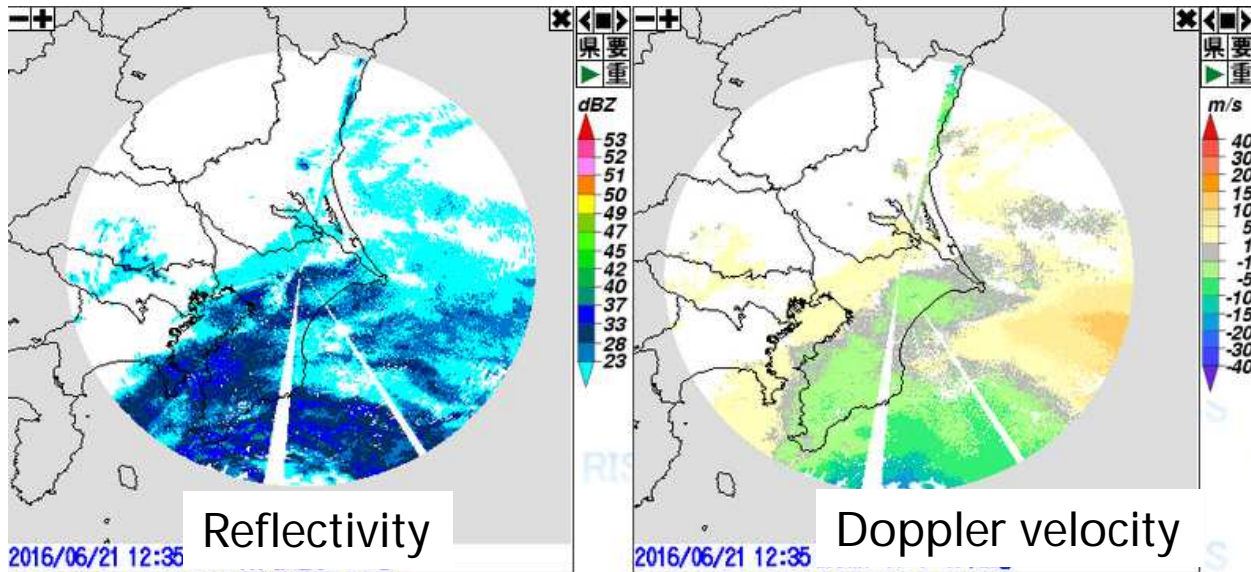
Appearance

pcappi Butterworth AVERAGE scale 100 =1.7425351  
2014/12/17 00:00-2014/12/17 23:50(UTC) data : 144



Average

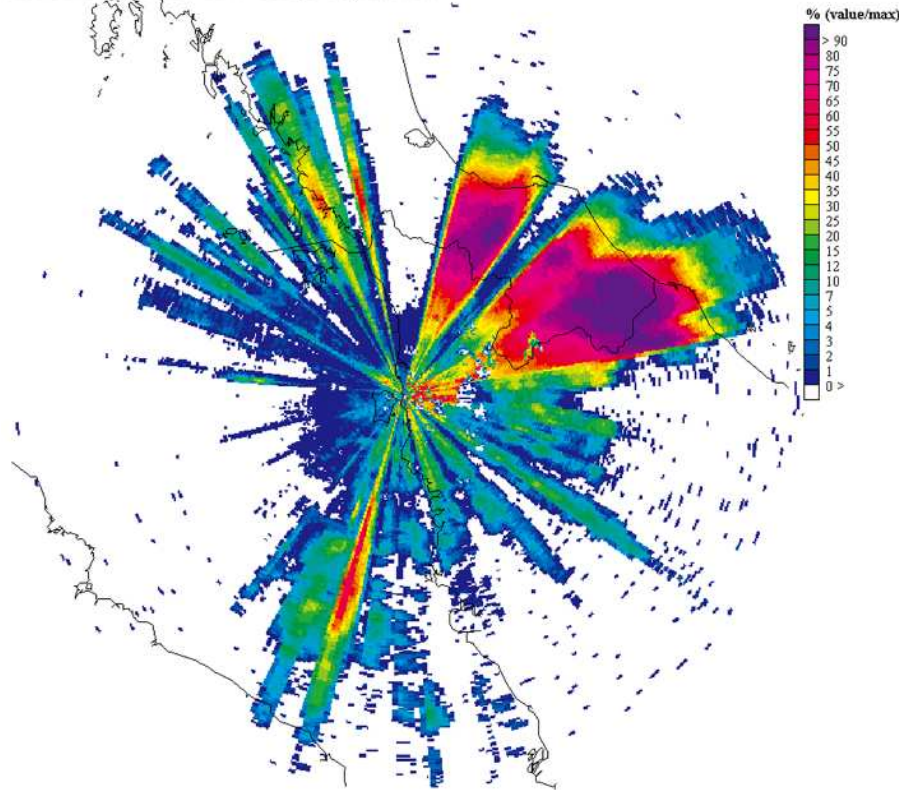
# Mirror image





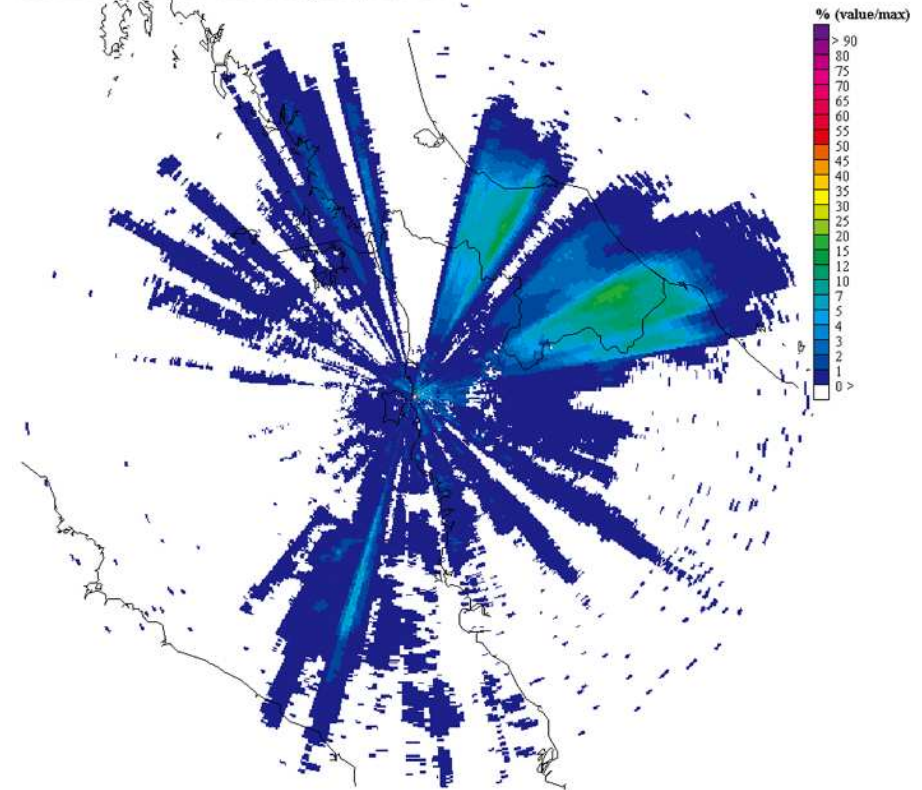
# Raw Data Statistics(0.0deg)

Butterworth\_0\_300.0BW\_iris APPEARANCE scale 100 =140.0  
2014/12/17 00:00-2014/12/17 23:50(UTC) data : 144



Appearance

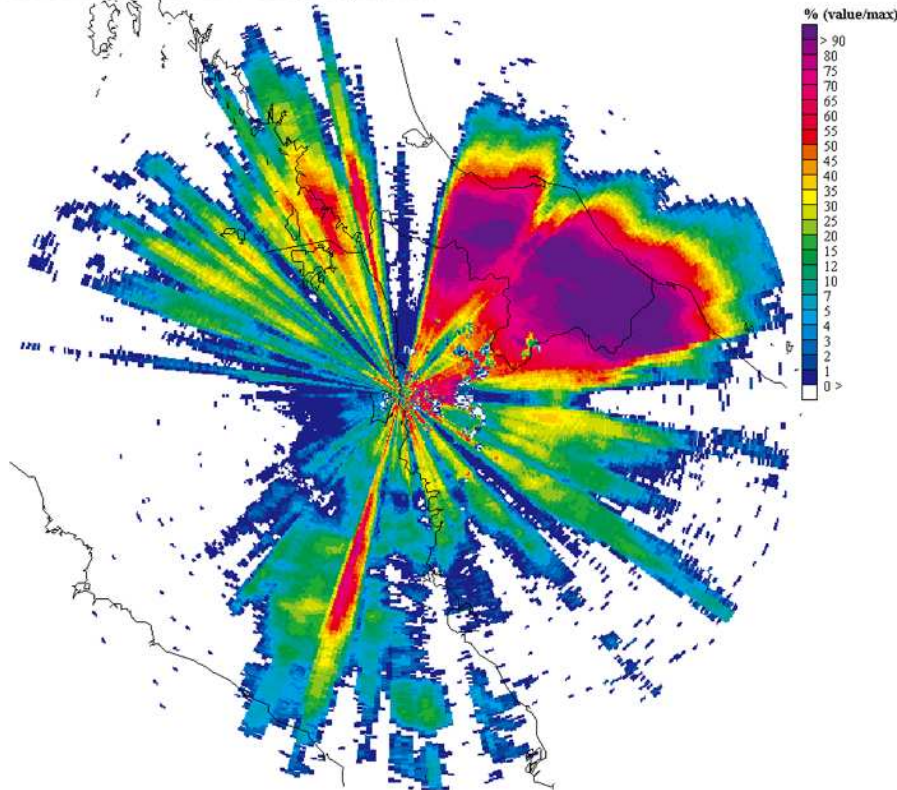
Butterworth\_0\_300.0BW\_iris AVERAGE scale 100 =3.5597873  
2014/12/17 00:00-2014/12/17 23:50(UTC) data : 144



Average

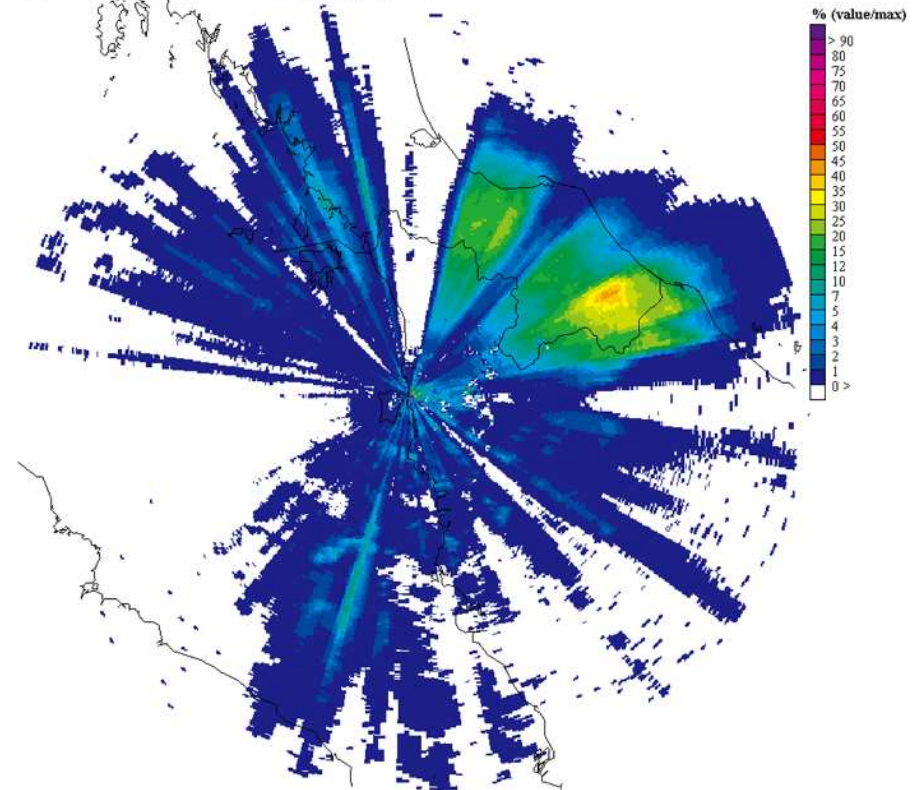
# Raw Data Statistics(0.7deg)

Butterworth\_0.7\_300.0BW\_iris APPEARANCE scale 100 =144.0  
2014/12/17 00:00-2014/12/17 23:50(UTC) data : 144



Appearance

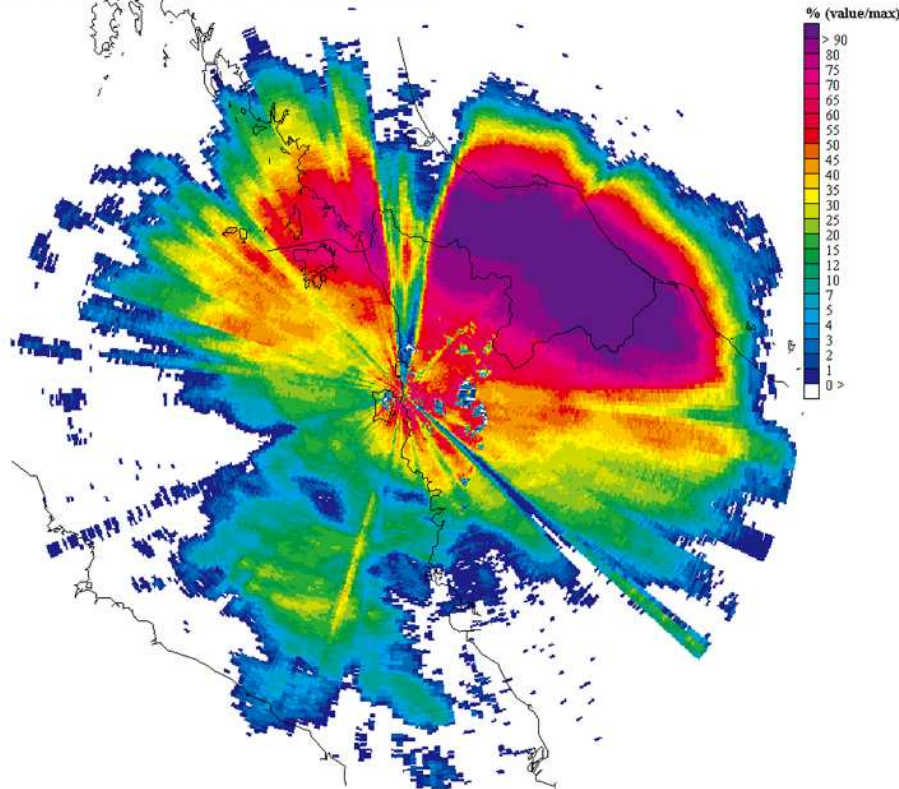
Butterworth\_0.7\_300.0BW\_iris AVERAGE scale 100 =3.808475  
2014/12/17 00:00-2014/12/17 23:50(UTC) data : 144



Average

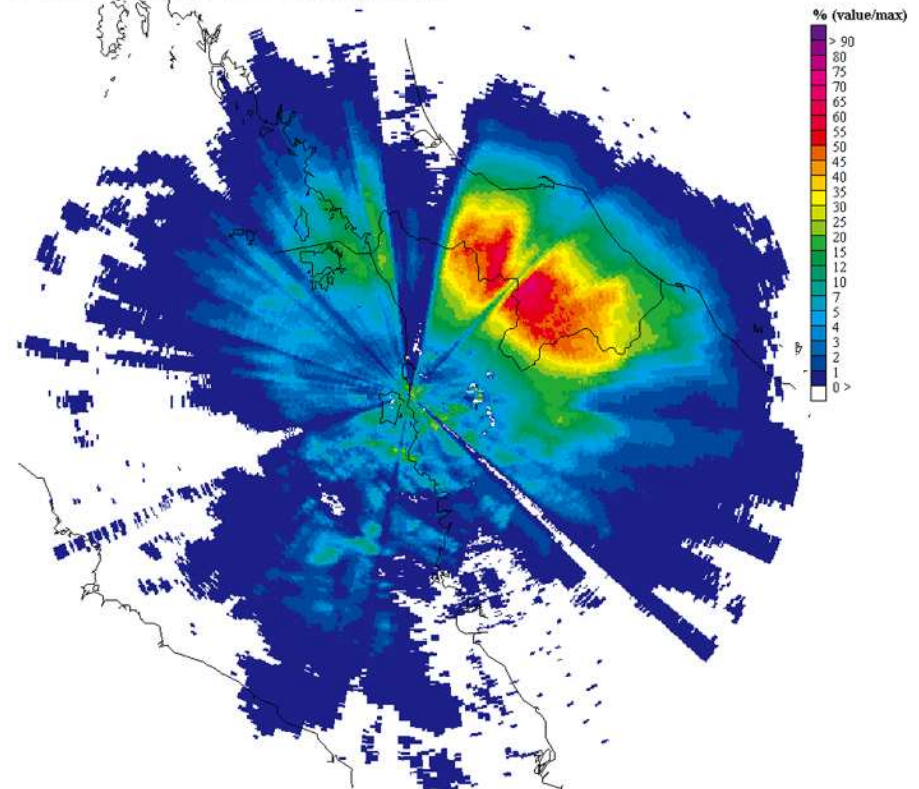
# Raw Data Statistics(1.5deg)

Butterworth\_1.5\_300.0BW\_iris APPEARANCE scale 100 =144.0  
2014/12/17 00:00-2014/12/17 23:50(UTC) data : 144



Appearance

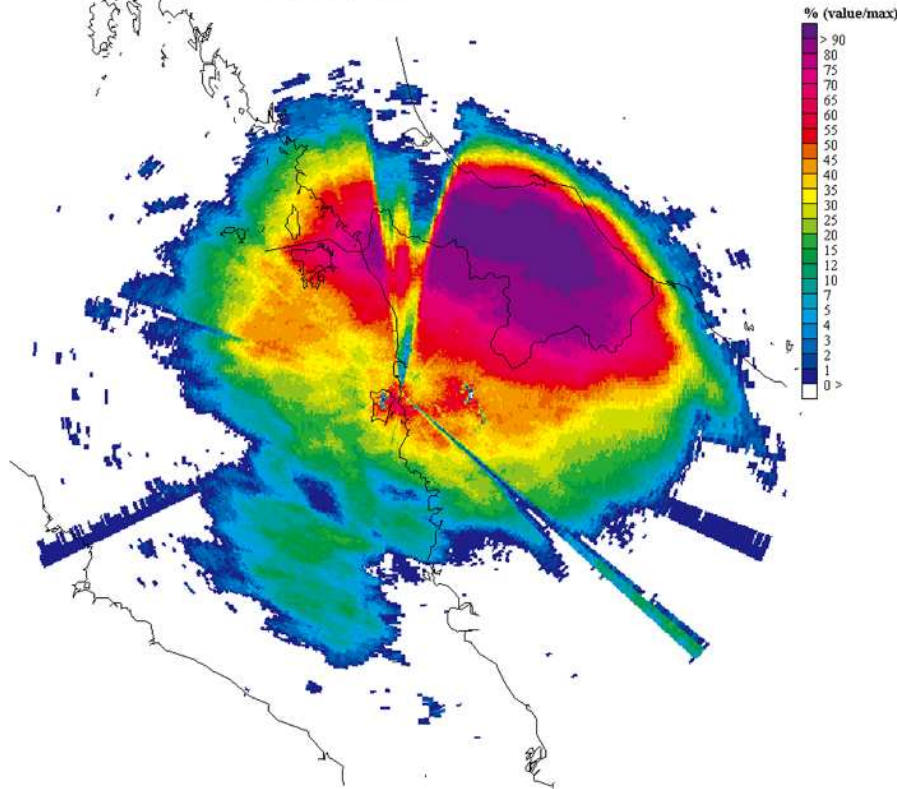
Butterworth\_1.5\_300.0BW\_iris AVERAGE scale 100 =2.6529007  
2014/12/17 00:00-2014/12/17 23:50(UTC) data : 144



Average

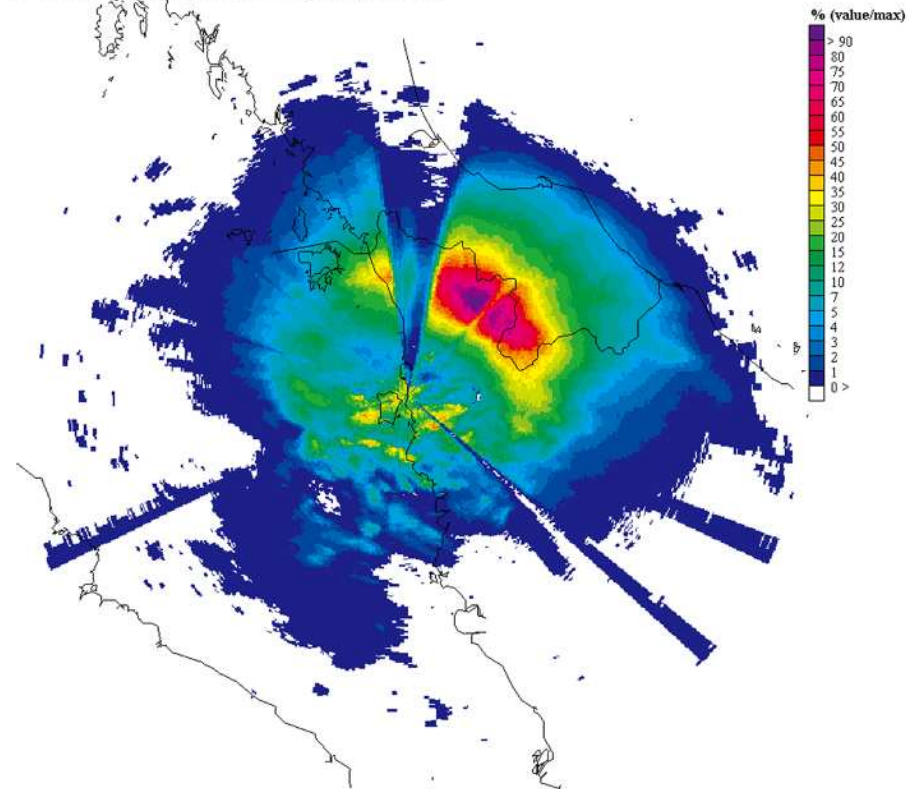
# Raw Data Statistics(2.5deg)

Butterworth\_2.5\_300.0BW\_iris APPEARANCE scale 100 =144.0  
2014/12/17 00:00-2014/12/17 23:50(UTC) data : 144



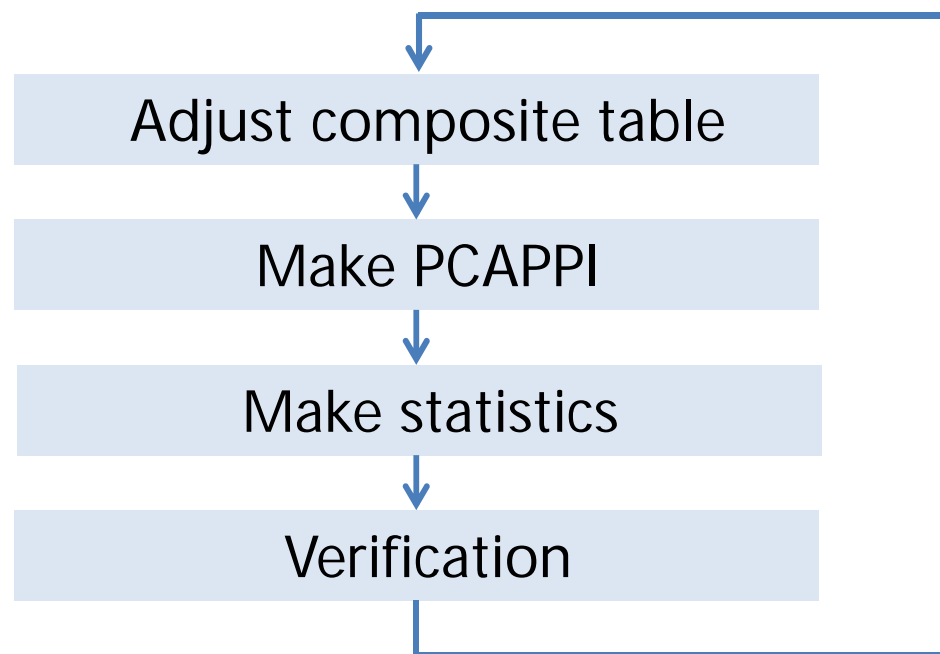
Appearance

Butterworth\_2.5\_300.0BW\_iris AVERAGE scale 100 =1.460051  
2014/12/17 00:00-2014/12/17 23:50(UTC) data : 144



Average

# Next Challenge: Avoid mirror-image



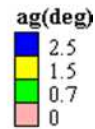
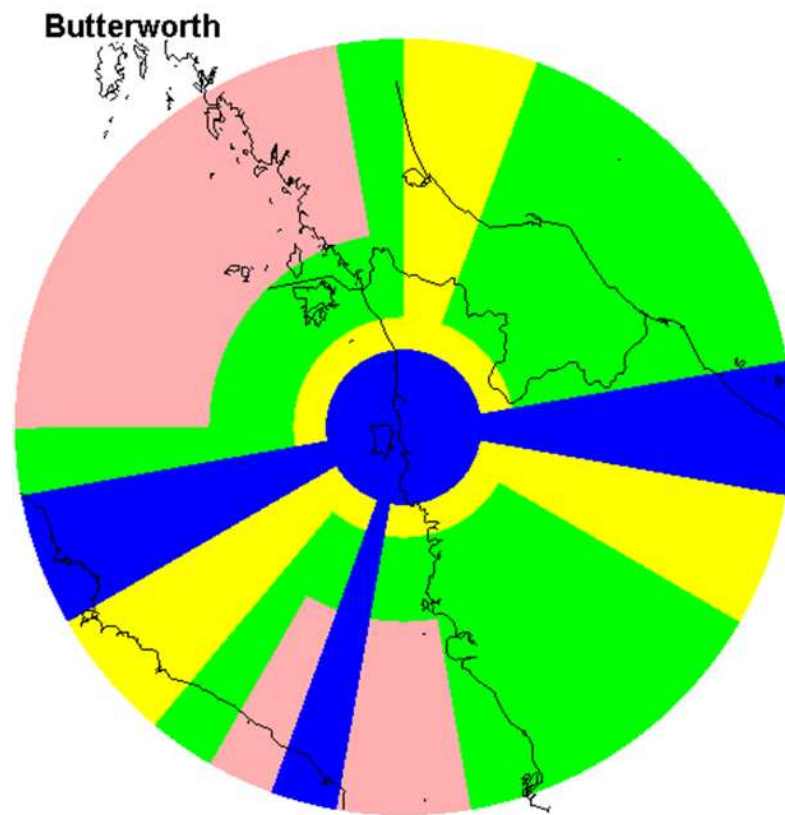
- Statistical data revealed that PCAPPI is partly contaminated by mirror-image.
- To remove mirror-image, let's adjust composite table again.



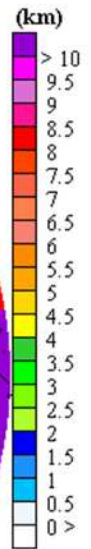
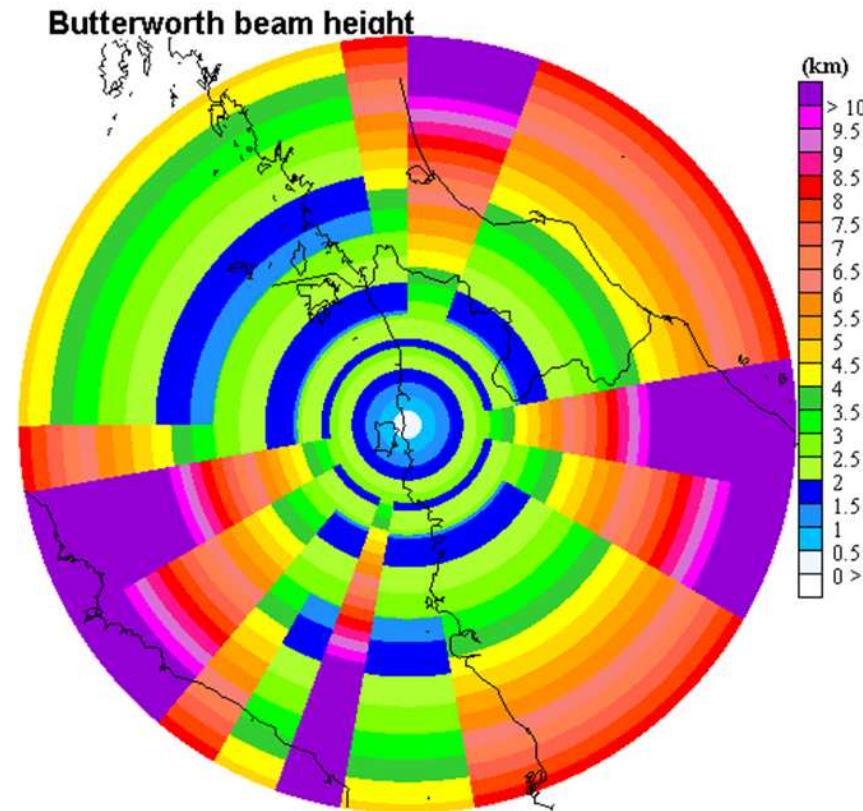
# Exercise 3

20	0	2.5	60	1.5	300					
80	0	2.5	60	1.5	85	0.7	300			
100	0	2.5	300							
120	0	2.5	60	1.5	300					
170	0	2.5	60	1.5	85	0.7	300			
190	0	2.5	60	1.5	85	0.7	150	0	300	
200										
210	0	2.5	60	1.5	85	0.7	150	0	300	
220	0	2.5	60	1.5	85	0.7	300			
240	0	2.5	60	1.5	300					
260	0	2.5	300							
270	0	2.5	60	1.5	85	0.7	300			
350	0	2.5	60	1.5	85	0.7	150	0	300	
360	0	2.5	60	1.5	85	0.7	300			

# Composite table: PCAPPI (avoid mirror-image)



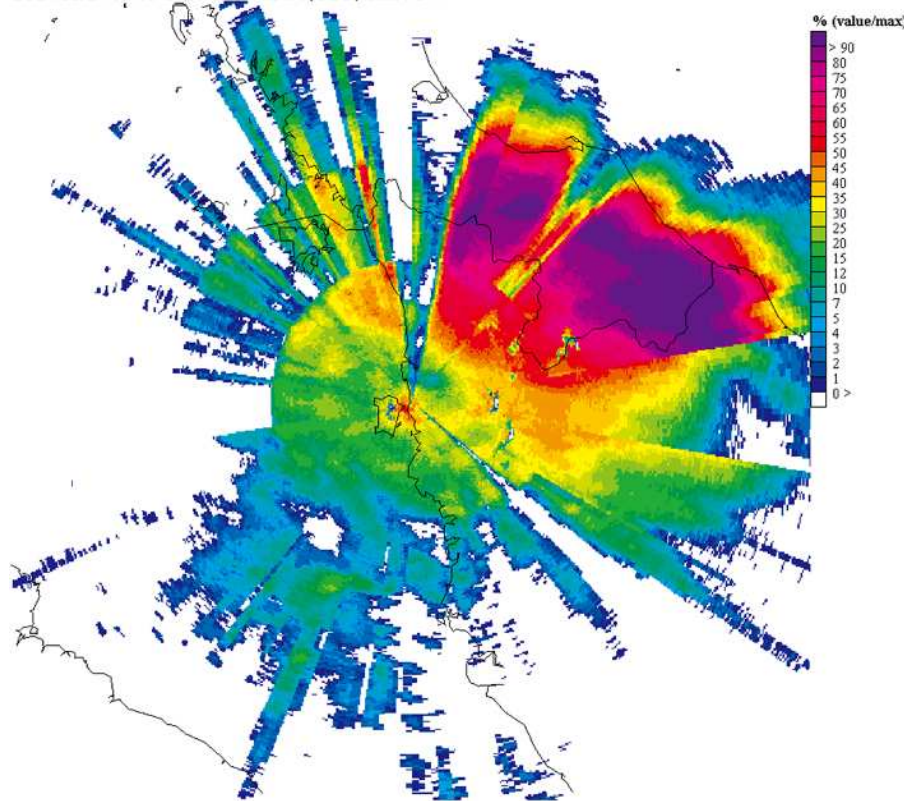
Angle



Beam Height

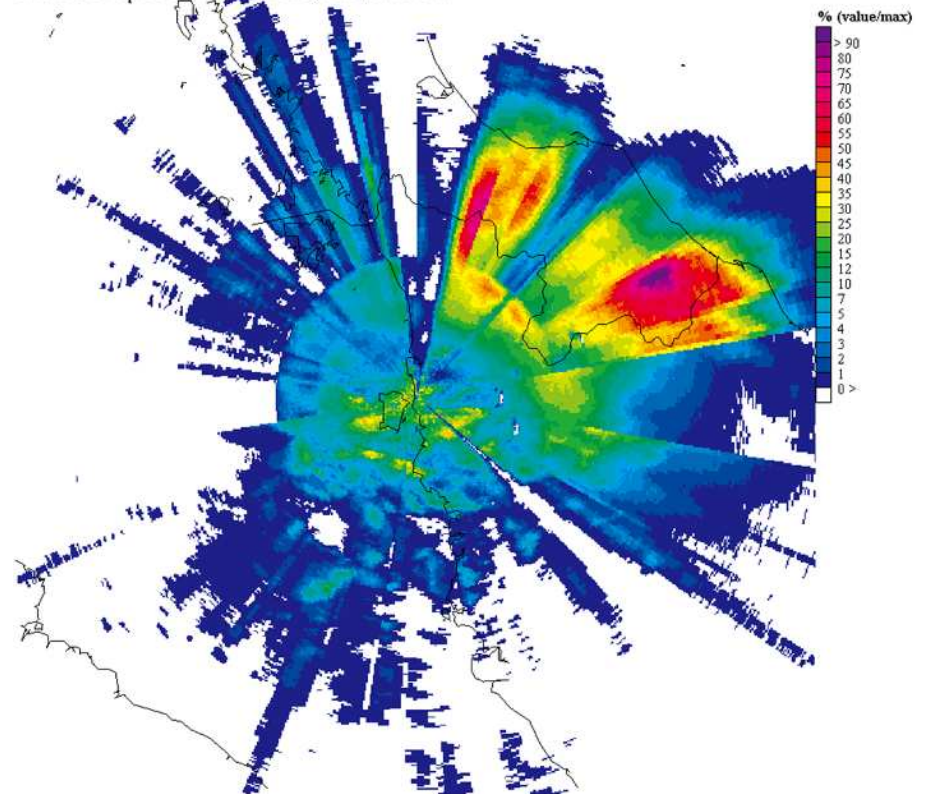
# Statistics: PCAPPI (avoid mirror-image)

pcappi Butterworth APPEARANCE scale 100 =140.0  
2014/12/17 00:00-2014/12/17 23:50(UTC) data : 144



Appearance

pcappi Butterworth AVERAGE scale 100 =1.7425351  
2014/12/17 00:00-2014/12/17 23:50(UTC) data : 144



Average



# Result

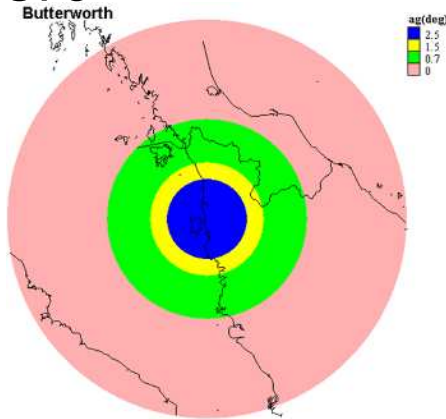
Composite table

Statistical PCAPPI data

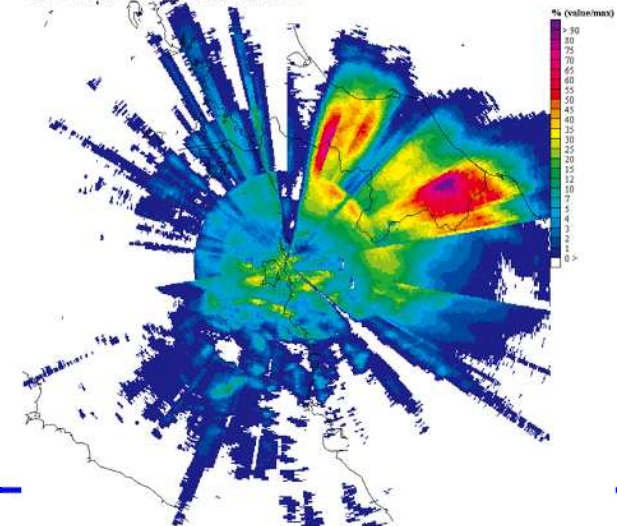
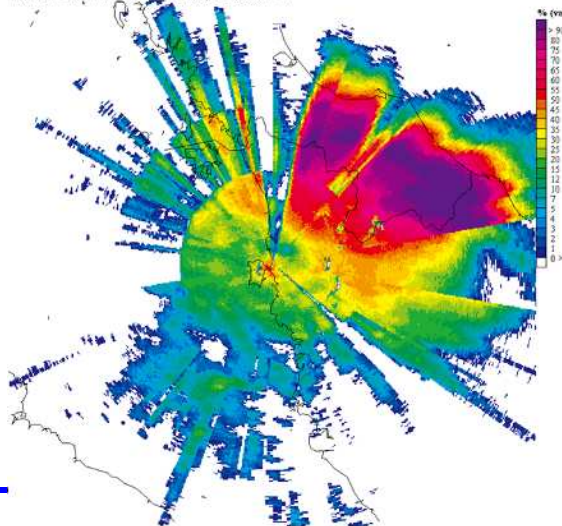
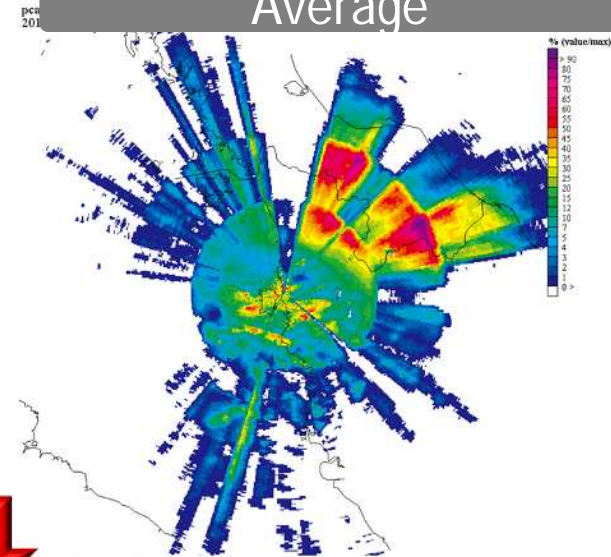
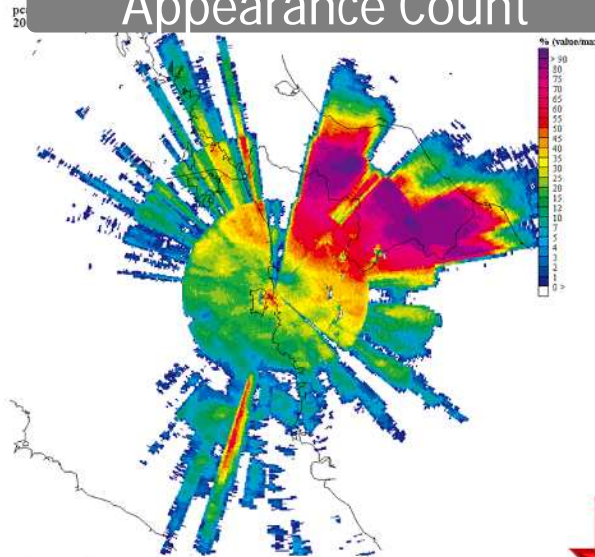
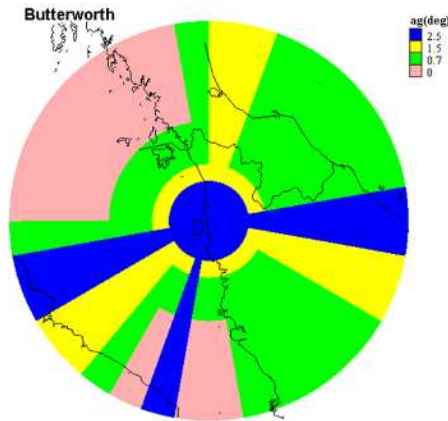
Appearance Count

Average

Before

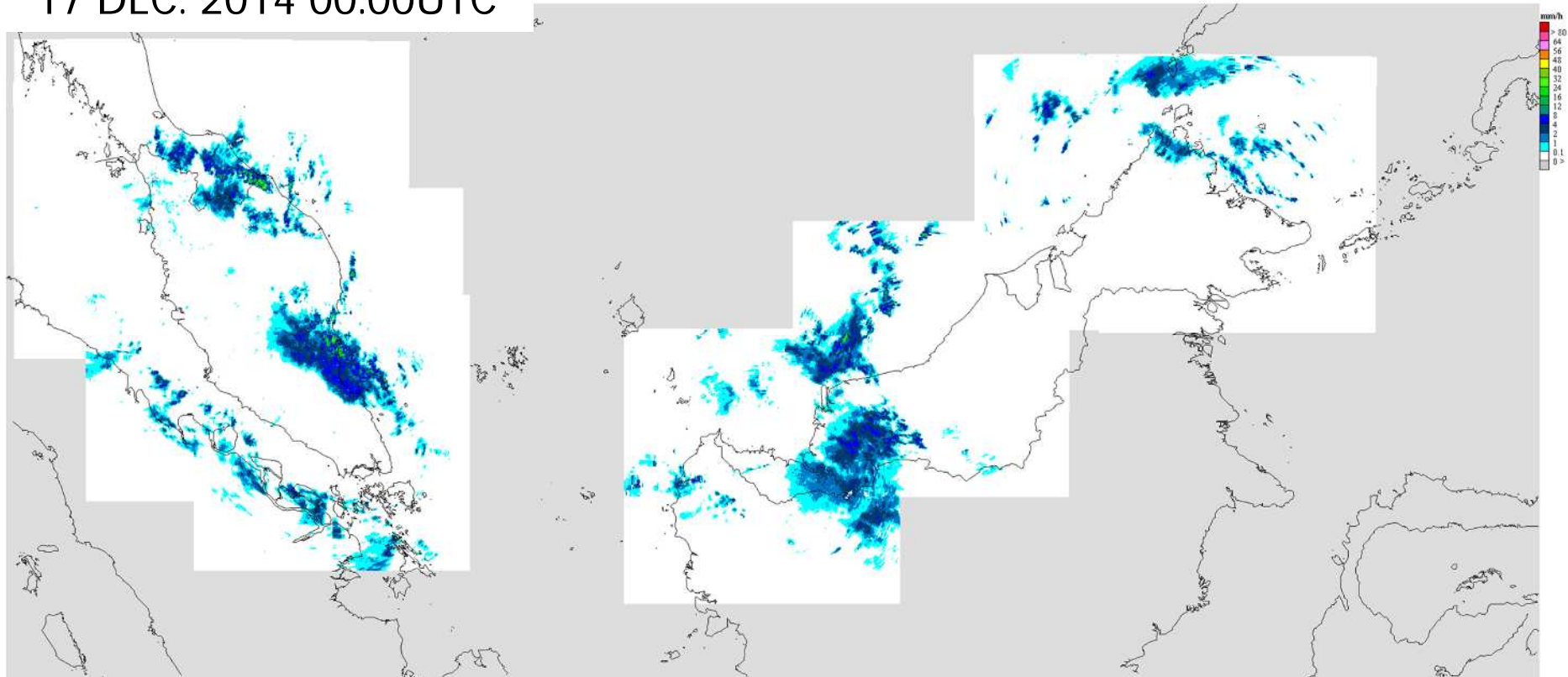


After



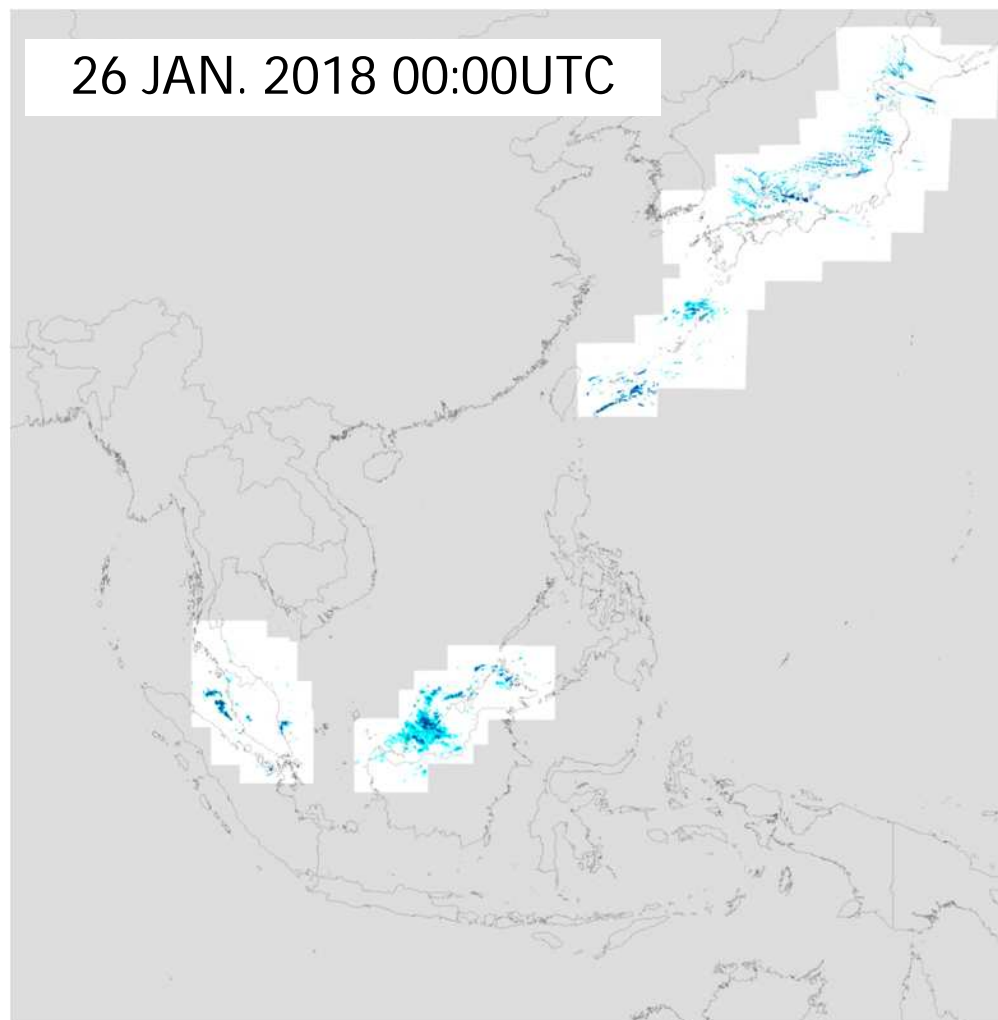
# National composite map

17 DEC. 2014 00:00UTC

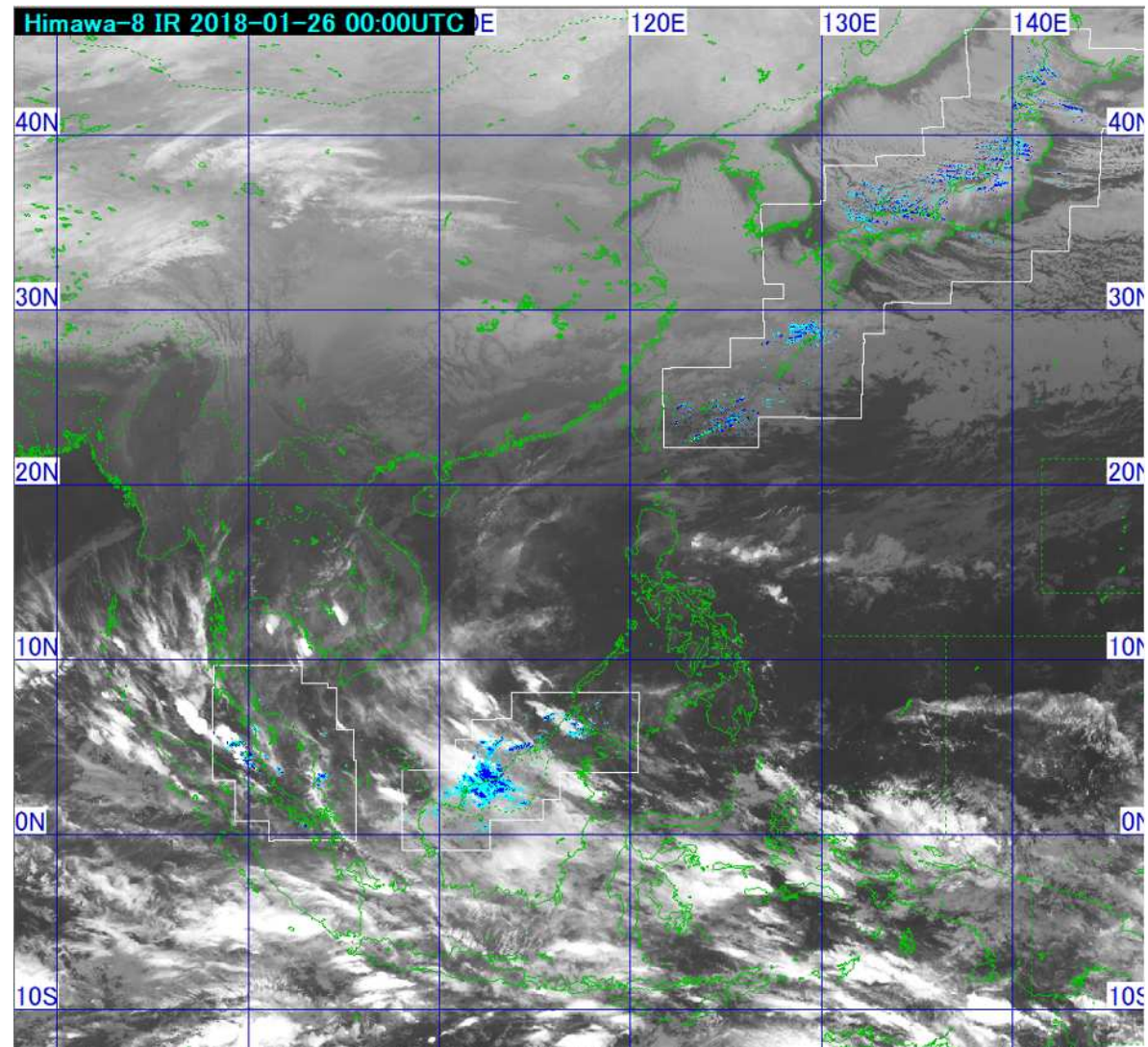


- Quality of composite map depends on quality of each radar's EIL.

# International Radar Composite Imagery



# With Satellite Image



# Summary

- In order to create Cartesian data with good quality (less clutter and less noise), we need various processes.
- However, it is impossible to completely eliminate anomalous echoes by automatic processing.
- Radar data quality control should be done through whole radar systems.
- Accumulation and careful investigation of radar data will improve QC results.

Thank you for your attention !!